

A Versatile Methodology for Assessing the Electricity Consumption and Environmental Footprint of Machine Learning Training: from Supercomputers to Edge Devices

PhD Defense of Mathilde JAY

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 Unité de recherche : Laboratoire d'Informatique de Grenoble

Une méthodologie polyvalente pour évaluer la consommation électrique et l'empreinte environnementale de l'entraînement à l'apprentissage machine : des supercalculateurs aux équipements embarqués

A Versatile Methodology for Assessing the Electricity Consumption and Environmental Footprint of Machine Learning Training: from Supercomputers to Edge Devices

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Invités :

| | |
|--|--|
| BRUNO MONNET INGENIEUR, Hewlett Packard Enterprise | |
|--|--|



Power measurement

A Versatile Methodology for assessing
the Electricity Consumption and
Environmental Footprint of
Machine Learning Training:
from Supercomputers to Edge
Devices

Estimation from
environmental
databases

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Limits of the approach & how to overcome them

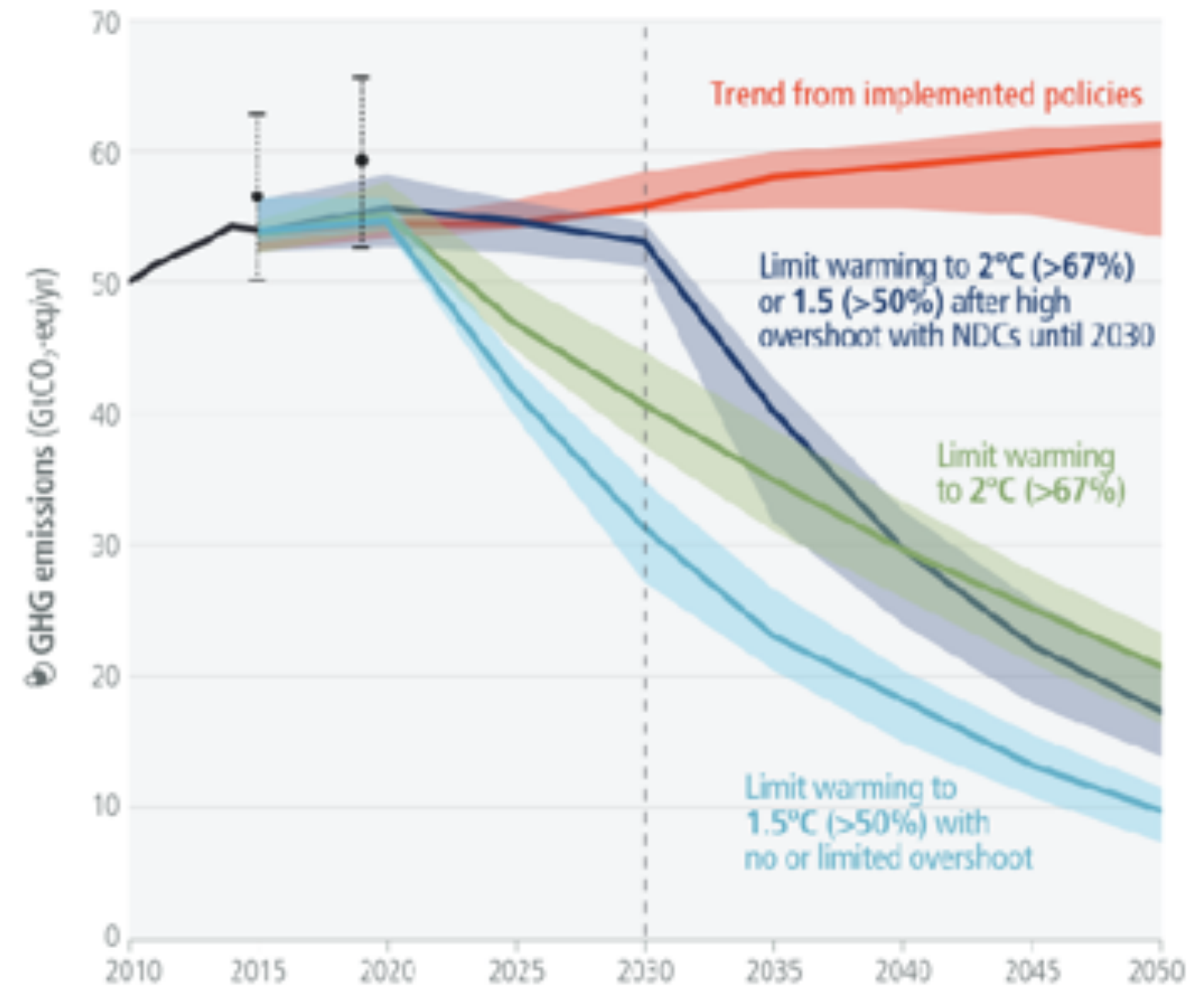
06.

Conclusion & perspectives

The impacts of Information and Communication Technologies

- Between **2.1% and 3.9%** of worldwide greenhouse gas emissions in 2020 [Freitag2021]
- Emissions increased by $\sim 5.5\%$ every year (2015 to 2019) [ShiftProject2021]
- More than climate change, ICTs can contribute to
 - Freshwater change
 - Rare metal depletion
 - Primary energy consumption

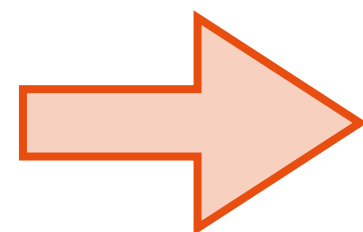
[Benqassem2021]



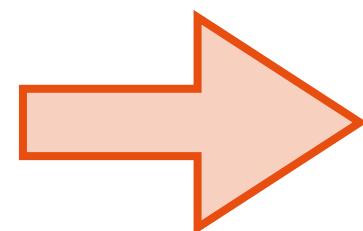
Global GHG emissions of modeled pathways from IPCC 2023 Sixth Assessment Report.

Treaties and regulations to reduce emissions

- Paris Agreement (2015)
- European Green Deal
 - Corporate Sustainability Reporting Directive (January 2023)
 - Energy Efficiency Directives



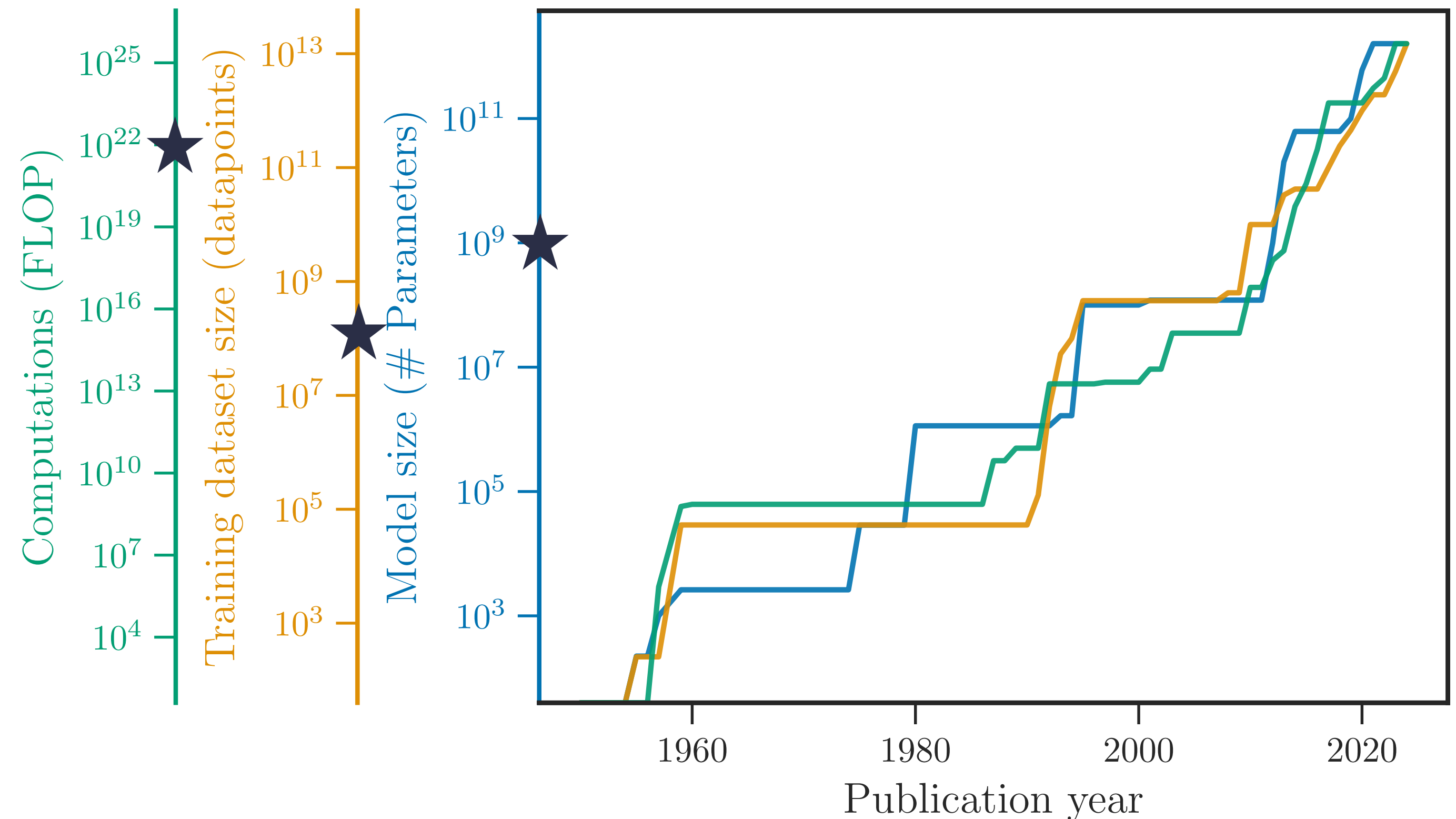
Need for the **companies** to assess the footprint of their digital services



Need for **policy makers** of assessment standards

Computational cost of Machine Learning

- Artificial Intelligence (AI)
 - Tasks that typically require human intelligence
- Machine Learning (ML)
 - AI that automatically learns from a set of data
- Deep Learning (DL)
 - ML that relies on deep neural network models



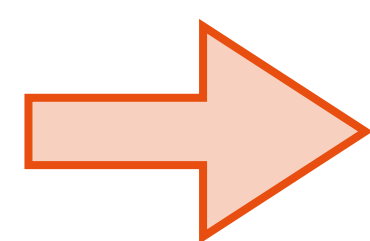
Evolutions in Machine Learning Model and their training, as the maximum value up to the given year. [EpochAI2024]

Stable Diffusion (2022): 256 A100 GPUs for 25 days

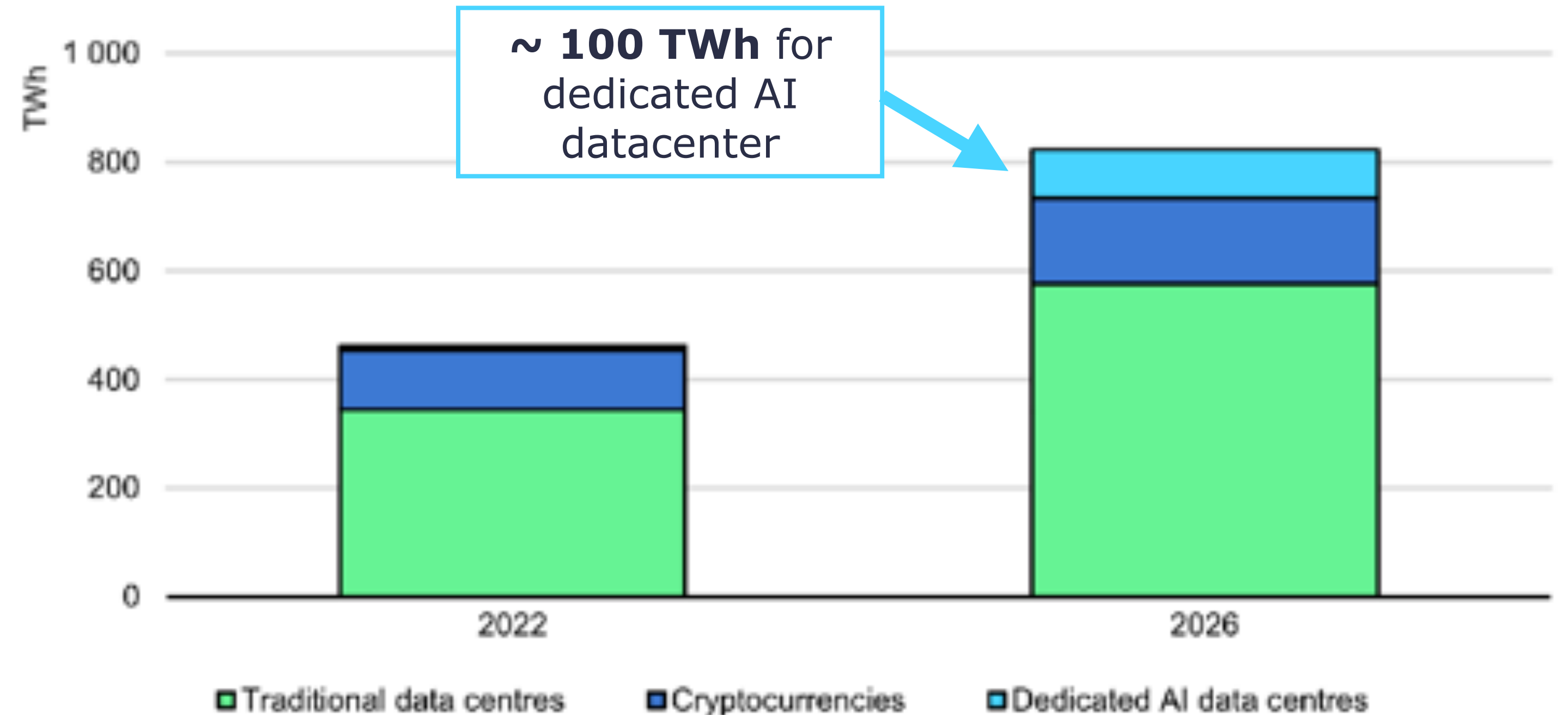
The growing impact of Machine Learning

Machine Learning is one of main drivers of increase of **electricity demand** in the European Union between 2023 and 2026

[IEA2024]

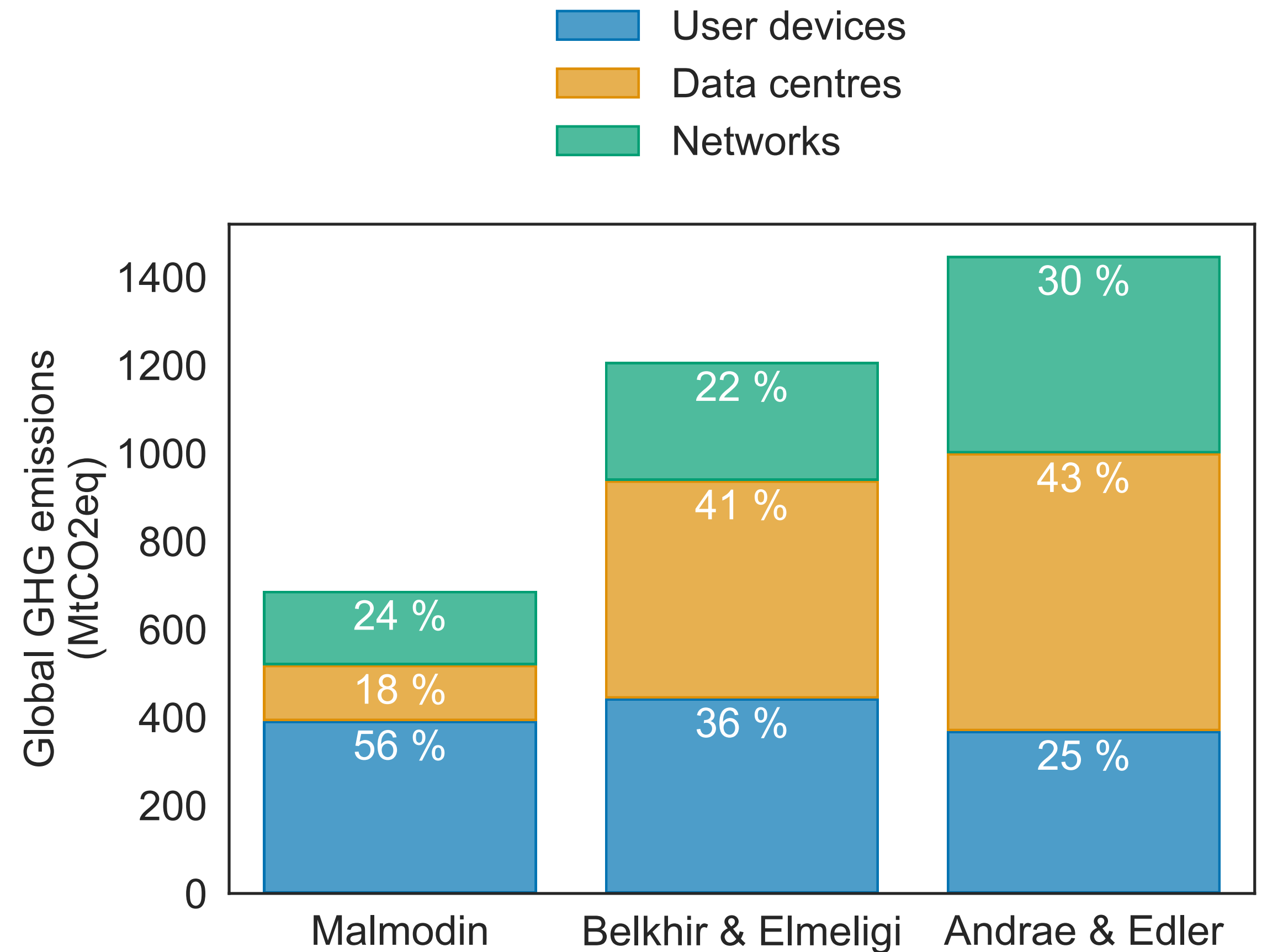
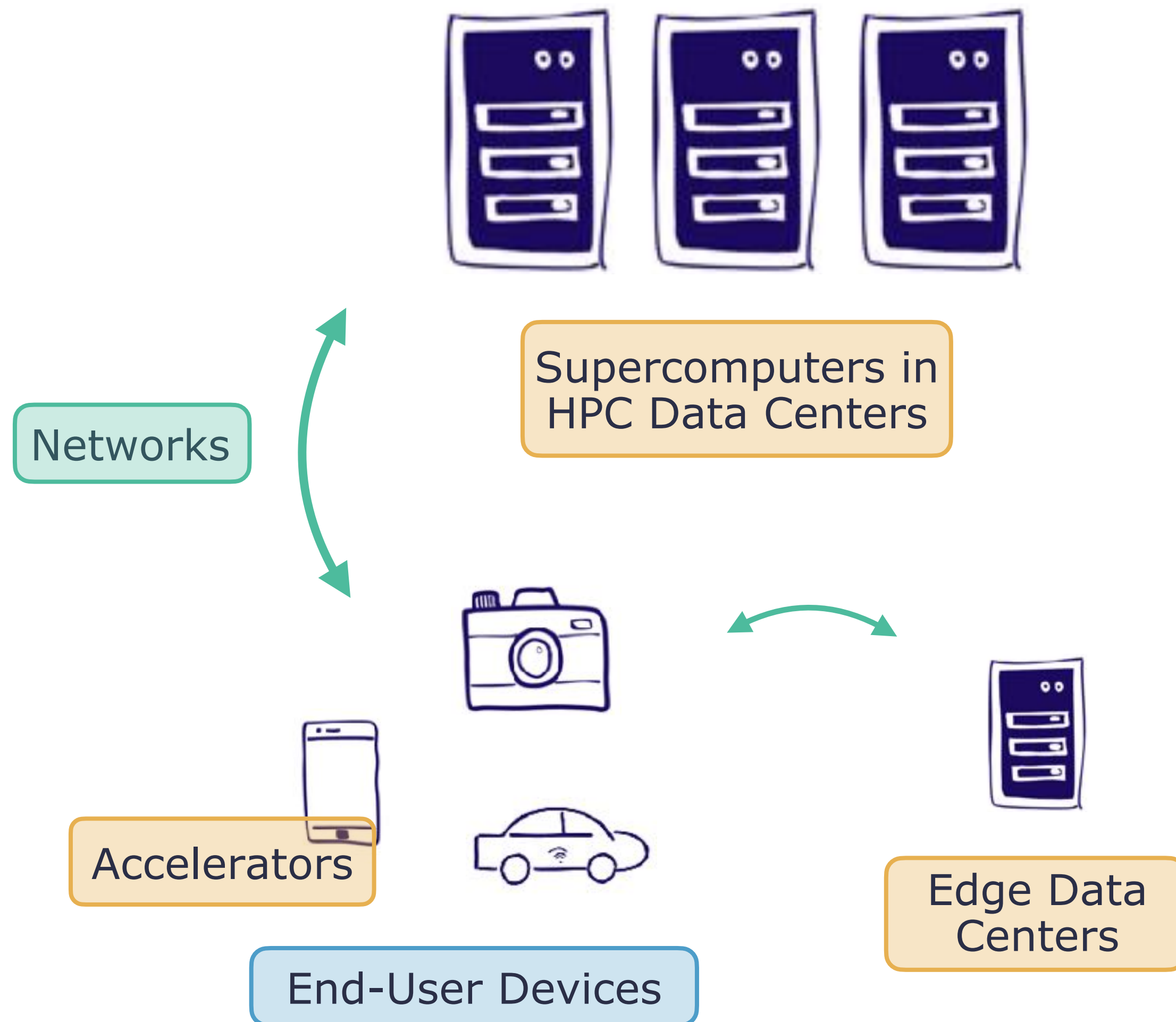


Need to assess footprint of machine learning services



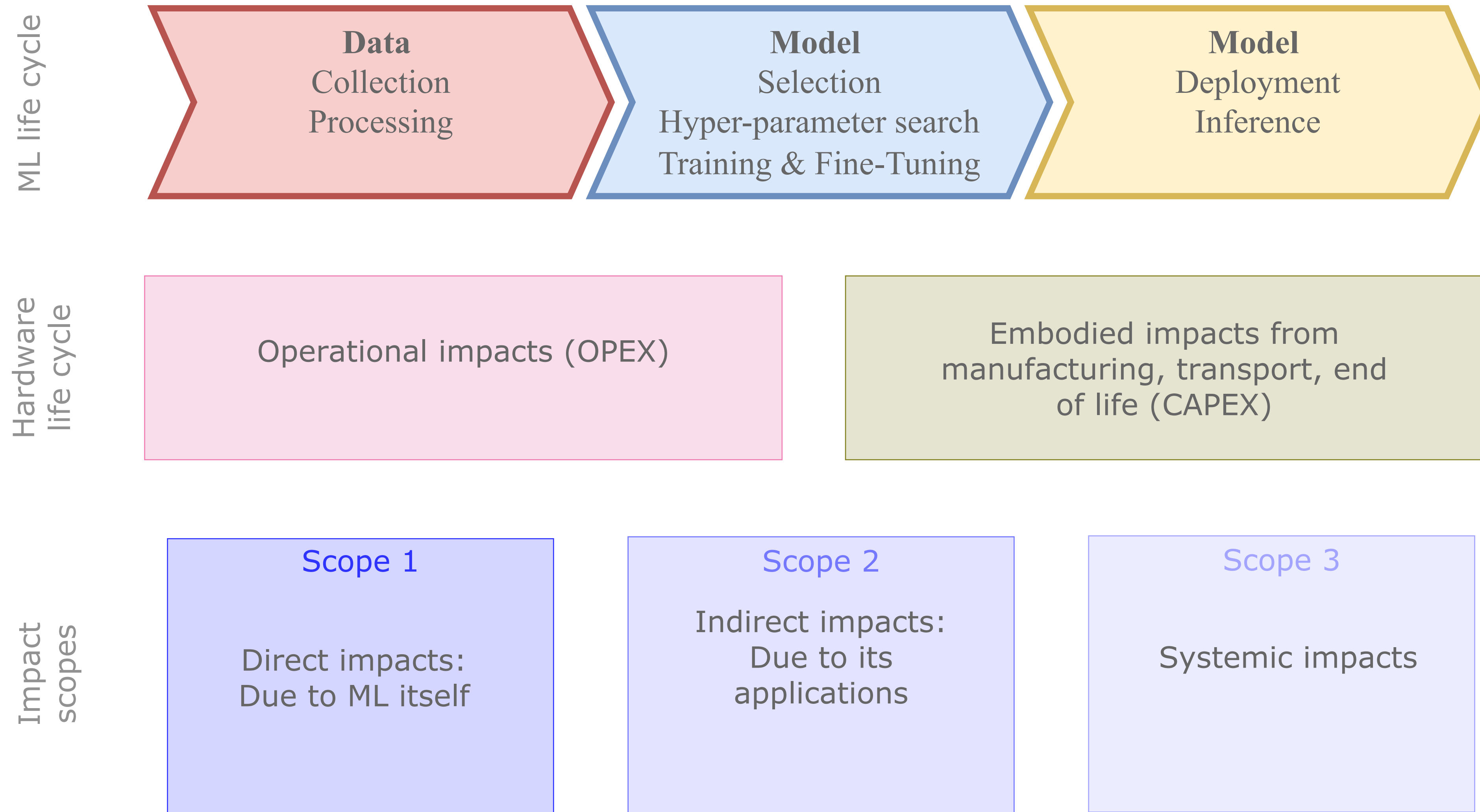
Estimated electricity demand from traditional data centres, dedicated AI data centres and cryptocurrencies in 2022 and 2026. [IEA2024]

Machine Learning services and materiality



Estimates for global ICT's carbon footprint in 2020 according to 3 studies [Freitag2021]

The multiple facets of an ML service



Research questions & objectives

How can we accurately **report** impacts of ML services?

How can those impacts be reduced?

Can **decentralizing** computations reduce the impacts?

Design a **methodology** to assess the impacts of training a ML model

Show its **versatility** by applying it on various models and infrastructures

Provide a better **understanding** of the impacts of ML training infrastructures

Compare a **Supercomputer** and an **Edge** node on model training

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Existing literature on ML service impact assessments

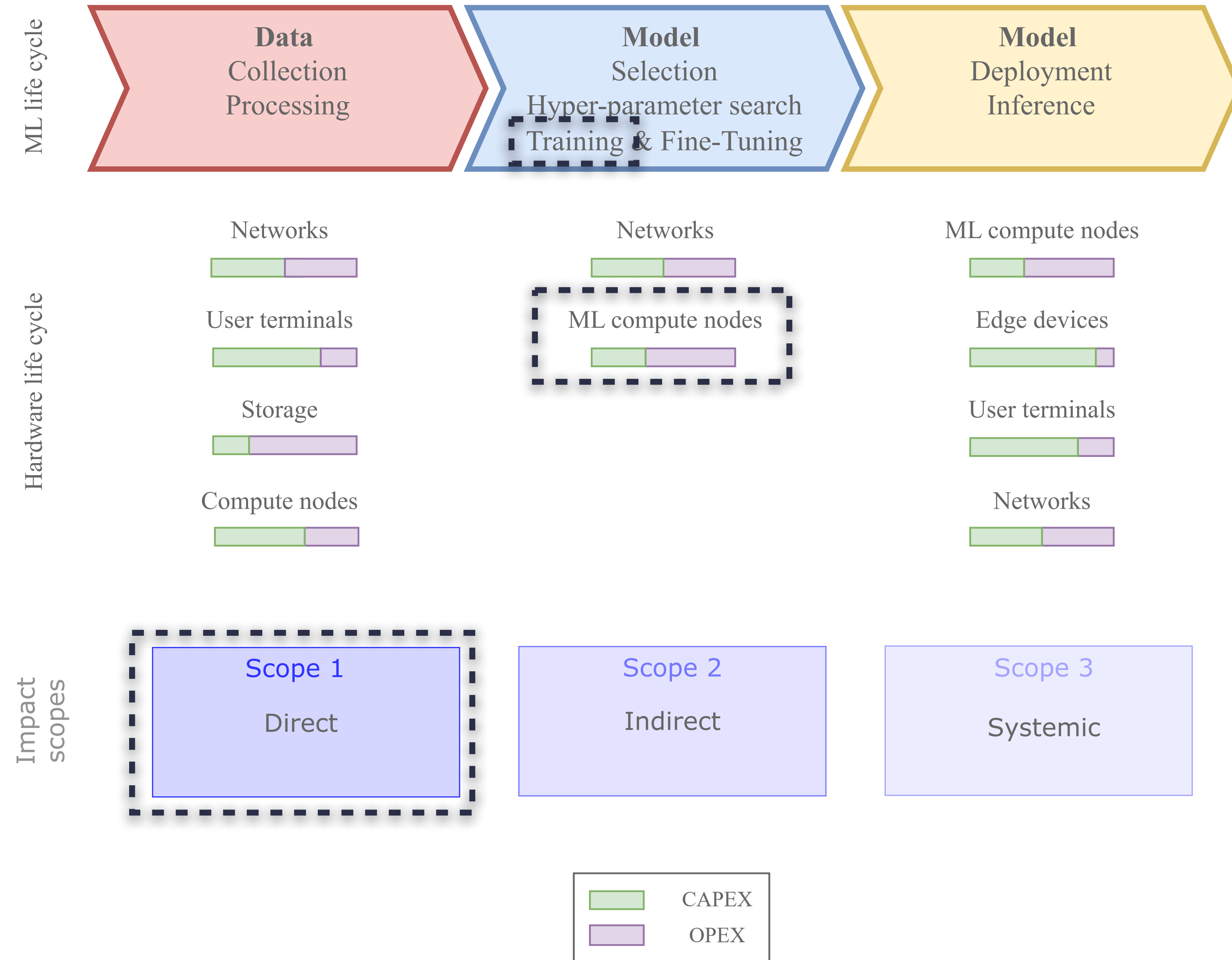
| | | Alert on the carbon footprint of NLP training | Same on other tasks | Federated Learning/ML at the Edge | Addition of the embodied footprint | ML deployment | Our methodology |
|---------------------|----------------------------|---|--|---------------------------------------|--|---------------------------------------|-----------------|
| | | [Strubell2019] | [Henderson2020, Patterson2020, Wu2022] | [Savazzi2021, Qiu2024, Patterson2024] | [Ligozat2022, Dodge2022, Luccioni2023] | [Patterson2022, Wu2022, Luccioni2023] | |
| Impact Indicators | Electricity consumption | | | | | | |
| | Carbon emission | | | | | | |
| | Primary energy | | | | | | ✓ |
| | Metal and mineral scarcity | | | | | | ✓ |
| Hardware life cycle | OPEX | | | | | | |
| | CAPEX | | | | ✓ | | ✓ |
| ML system scope | Supercomputer | | | | | | |
| | Edge | | | ✓ | | | ✓ |
| ML life cycle | Training | | | | | | |
| | Deployment | | | | | ✓ | ✓ |

Methodology

- Life Cycle Assessment (LCA)
 - ISO standards (14040 and 14044)
 - Standards from the International Telecommunication Union
 - Multi-criteria & multi phases
- We apply Attributional LCA to ML training

Methodology

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- Scope
 - The CAPEX and OPEX impacts of the ML compute nodes during the training phase

- Functional Unit

Train the Model on the Dataset until the Quality Target is reached

Methodology

- Life Cycle Assessment (LCA)
 - ISO standards (14040 and 14044)
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 - Multi-criteria & multi phases
- We apply Attributional LCA to ML training
- Scope
 - The CAPEX and OPEX impacts of the ML compute nodes during the training phase
- Functional Unit
 - Train the model on the dataset until the quality target is reached
- Impacts
 - **Primary Energy** (PE) measured in mega joule (MJ)
 - **Global Warming Potential** (GWP) measured in equivalent CO₂ emission (kg.CO₂.eq)
 - **Abiotic Depletion Potential** (ADP) of minerals and metals measured in equivalent antimony (kg.Sb.eq)

Methodology

Operational phase (OPEX)

- Power measurement
 - Of each components
 - With a frequency high enough to capture evolution
- Software-based power meters
- Electricity impact factors
- Repeatability of experiments
- Fixed and controlled environments

Evaluated Metrics

How

Reproducibility

Embodied phase (CAPEX)

- Embodied impacts of each component of the ML compute node
- Time-based allocation
- LCA databases
- Public databases

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Infrastructures

HPC

Apollo Node
From the
Champollion
cluster



EDGE

Nvidia Jetson
AGX Xavier



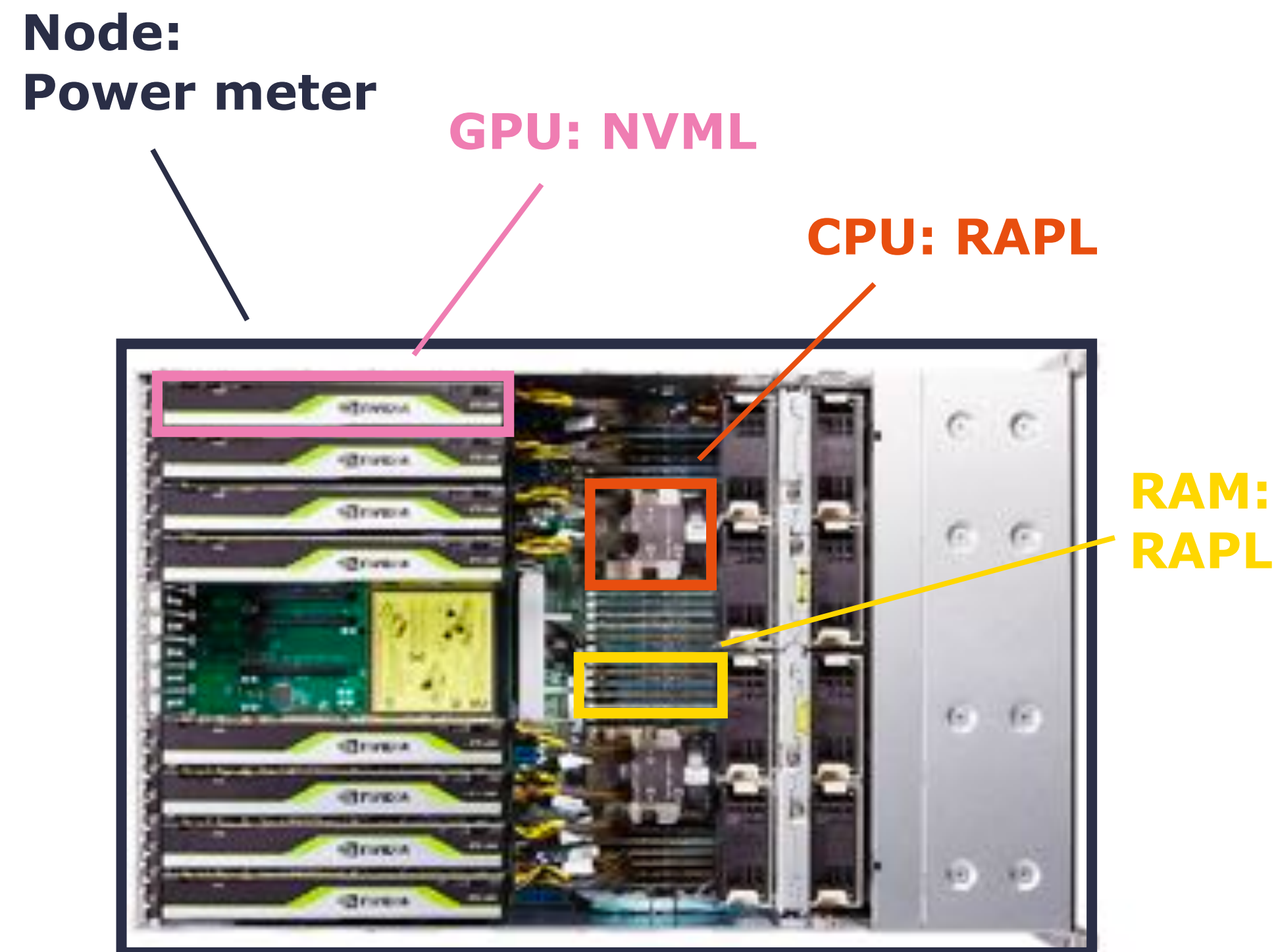
Infrastructures

HPC: APOLLO

EDGE: JETSON

| | | |
|------------------------------|---------------------------|--|
| Node model | Apollo 6500 Gen10 | Nvidia Jetson AGX Xavier |
| FL32 performance (FLOP/S) | $125 * 10^{12}$ | $1.41 * 10^{12}$ |
| GPU model | NVIDIA A100-SXM-80GB | NVIDIA GV10B, Volta architecture |
| Number of GPU per node | 8 | 1 |
| GPU TDP (W) | 400 | |
| CPU model | AMD EPYC 7763, 64 cores | Nvidia Carmel (Carmel), aarch64, 8 cores |
| Number of CPU per node | 2 | 1 |
| CPU TDP (W) | 280 | |
| Memory | 1 TB | 32 GB |
| Installation year | 2022 | 2023 |
| Available thought | HPE local network - slurm | Grid'5000 Estats cluster - OAR |
| Power meter | HPE iLO 5, RAPL, NVML | Jetson-stats |
| Node TDP (W) | 3760 (GPUs + CPUs) | 30 |
| Energy efficiency (FLOP/S/W) | $3.3 * 10^{10}$ | $2.3 * 10^{10}$ |

Measuring the electricity consumption of a node

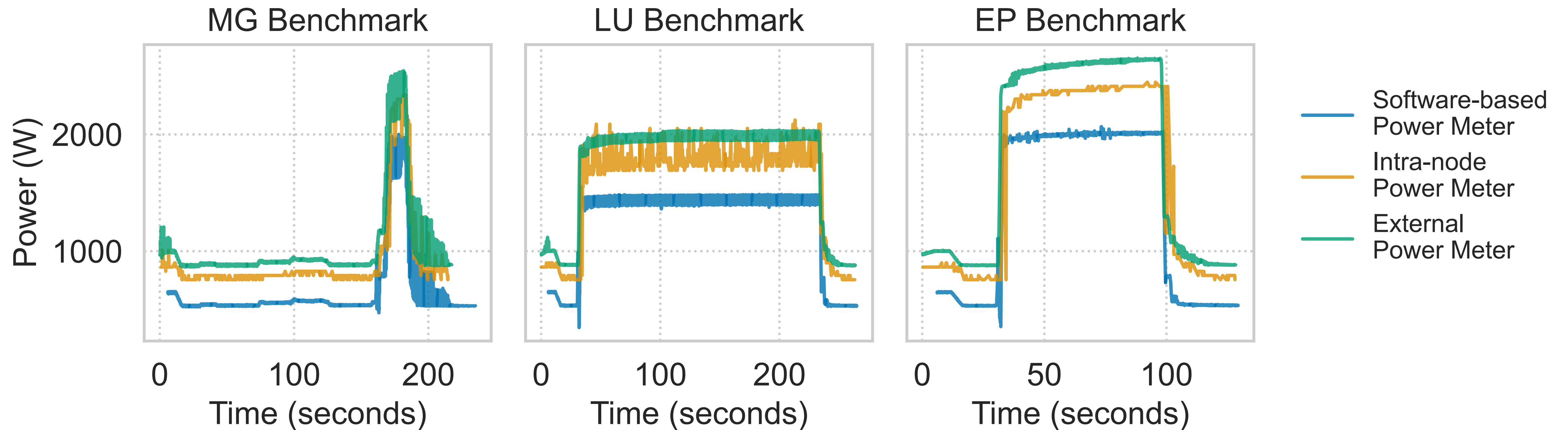


Example of a GPU node

- Power meters
 - Outside of node
 - Processor power management libraries
- Software-based power meters
 - Proven to be accurate
 - Available on most nodes
- Which one is better for our use case?

A quantitative comparison

- Compared **software-based** power meters
- Evaluated them against **external** power meters and found a significant and non-constant offset



Comparison of power meters on 3 applications of the NAS benchmark on the Gemini cluster of Grid'5000.



And a qualitative comparison

- Not suitable for our use case because of lack of
 - Configurability (frequency) for node with GPUs
 - Versatility: power management librairies depend on infrastructures



Mathilde Jay, Vladimir Ostapenco, Laurent Lefèvre, Denis Trystram, Anne-Cécile Orgerie, Benjamin Fichel. An experimental comparison of software-based power meters: focus on CPU and GPU. CCGrid 2023 - 23rd IEEE/ACM international symposium on cluster, cloud and internet computing, May 2023, Bangalore, India

 HAL
science ouverte

 49 citations
 2578 download



Open Research Objects
Reusable/Research Objects Reviewed

A software-based power meter for Apollo and Jetson

ALUMET

- **Time series** of GPU consumption as well as CPU and RAM
- **Configurable** acquisition frequency
- **Adaptive** to edge and HPC architectures
- **Modularity** (e.g. new data sources can be added by plugins)
- **Lightweight** (no significant slowdown of HPC benchmarks for RAPL+CSV)



alumet.dev

By Guillaume Raffin, BULL SAS, CNRS,
INRIA, Grenoble INP-UGA.

Licensed under the EUPL-1.2 or later.

~ 12 300 lines

Written in Rust

Estimating the embodied impacts with Boavizta



Datavizta API: Multi-indicators/Multi-phase

- Aggregates data from various databases
 - ADEME carbon database
 - Manufacturer product carbon footprints
 - Semiconductor LCA
- For GPUs, need specifications
 - Die size
 - Printed Circuit Board area
 - Memory density and capacity

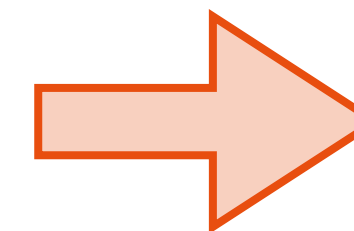
Total embodied or CAPEX impact of Jetson and Apollo

| | GWP (kg CO ₂ eq) | ADP (kg Sbeq) | PE (MJ) |
|--------|--------------------------------|------------------|---------|
| Jetson | 87 | 0.03 | 1 254 |
| Apollo | 3 858 | 0.28 | 49 660 |

x 44

x 10

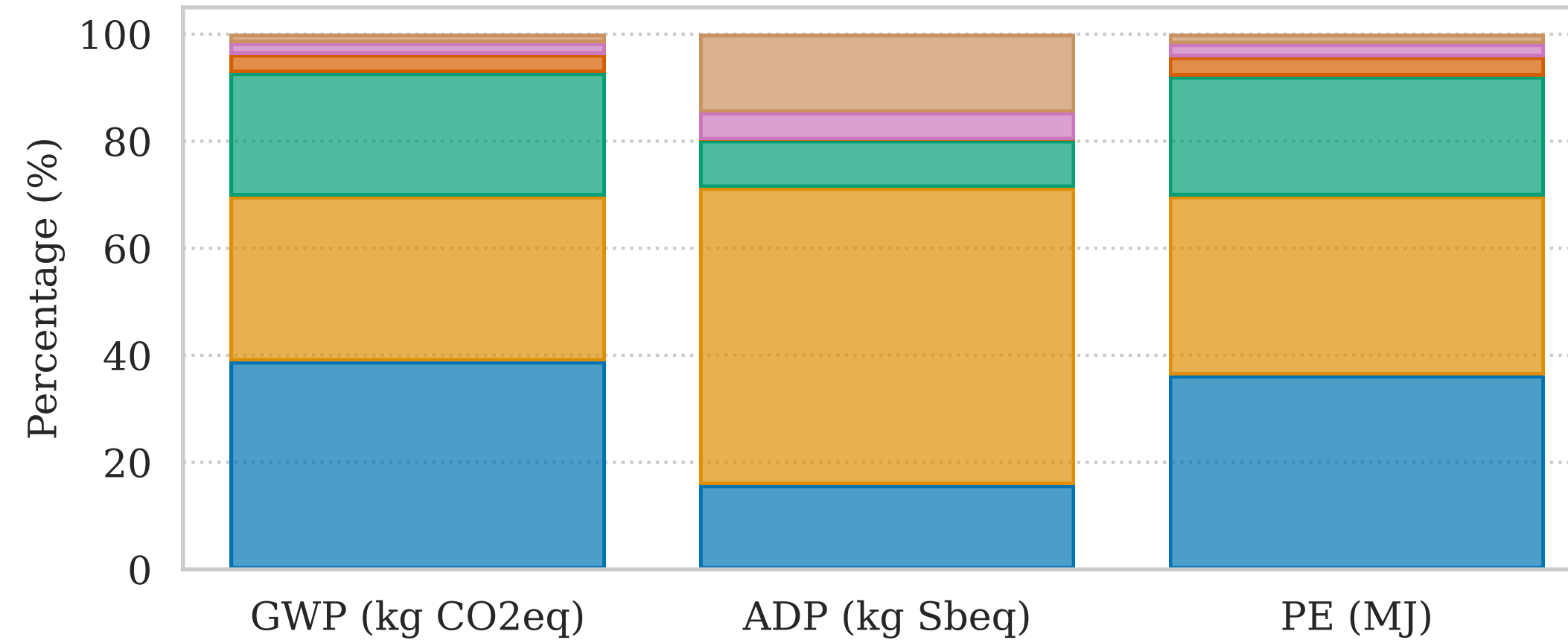
x 39



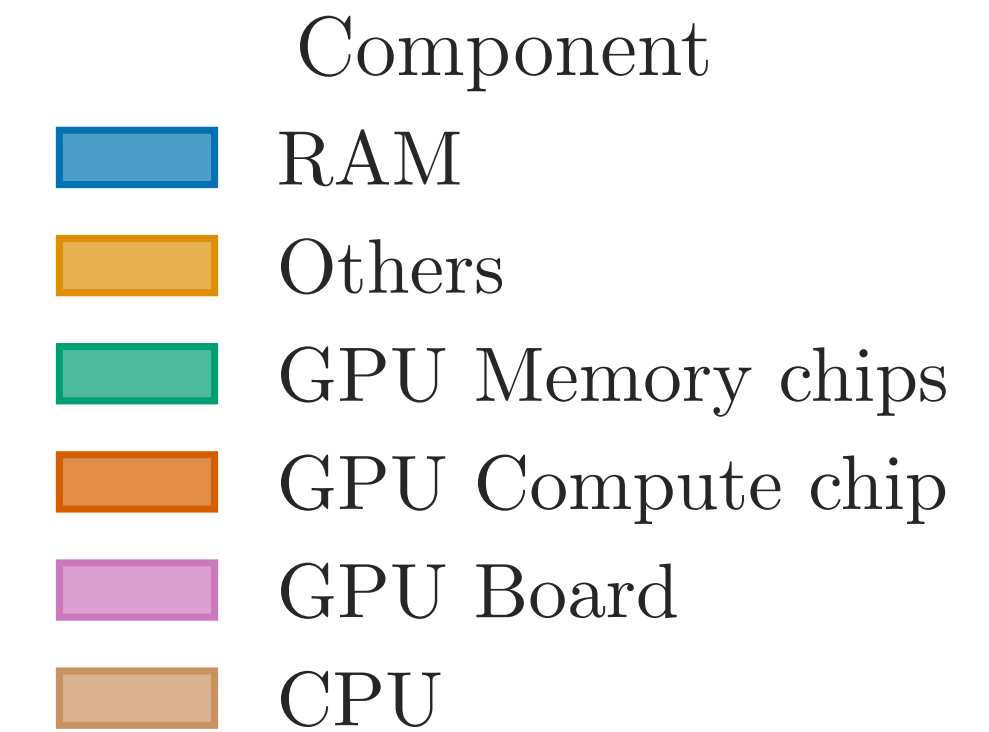
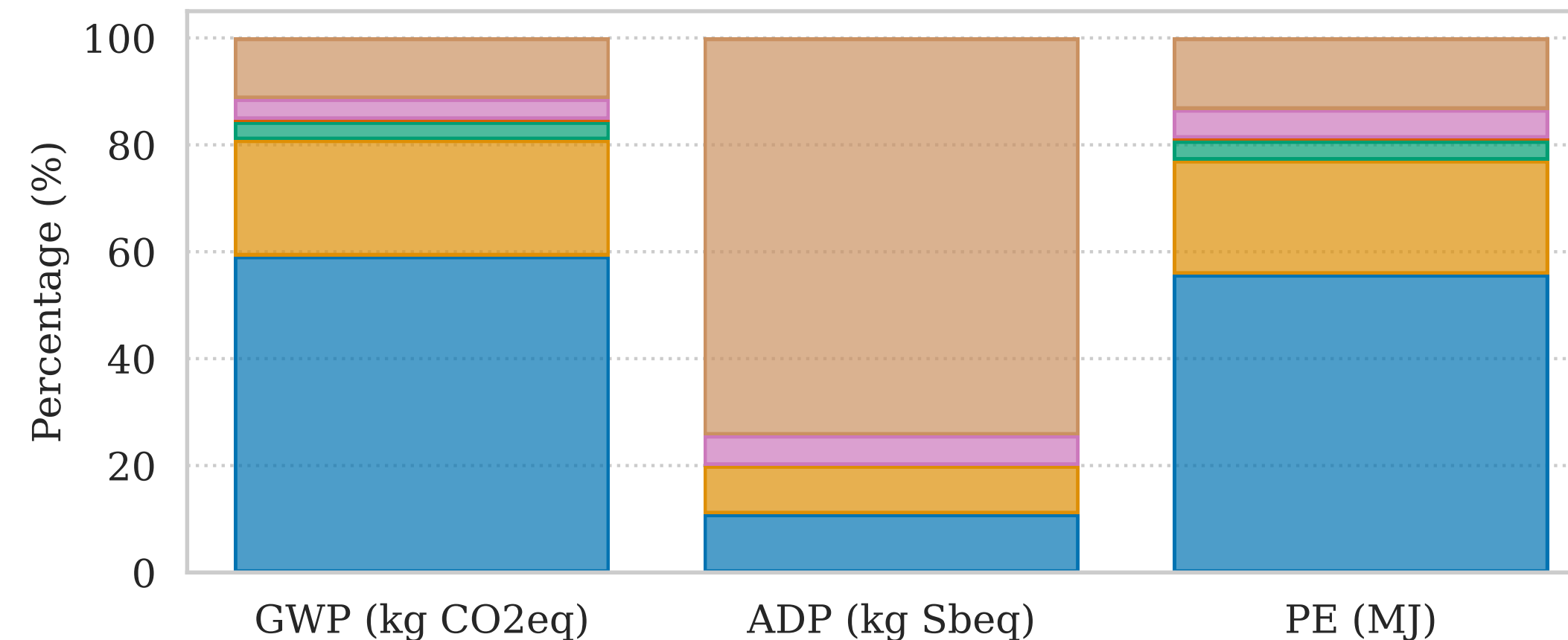
The embodied impact of one Apollo node is higher than the embodied impact of one Jetson node.

Memory dominates the embodied impacts

HPC: APOLLO



EDGE: JETSON



Share of each compute node component in the total embodied impacts.

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MLPerf Benchmark



| Area | Benchmark | Model | Dataset | Quality Target |
|----------|-----------------------------|----------------|----------------------|---|
| Vision | Image classification | ResNet-50 v1.5 | ImageNet | 75.90% classification |
| Vision | Image segmentation | 3D U-Net | KiTS19 | 0.908 Mean DICE score |
| Vision | Object detection | Mask R-CNN | COCO | 0.377 Box min AP and 0.339 Mask min AP |
| Language | Speech recognition | RNN-T | LibriSpeech | 0.058 Word Error Rate |
| Language | Natural Language Processing | BERT-large | Wikipedia 2020/01/01 | 0.72 Mask-LM accuracy |
| Commerce | Recommendation | DLRM | 1TB Click Logs | 0.8025 AUC |

HPC: APOLLO

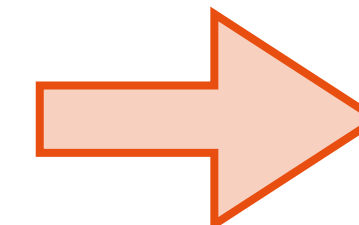


- Code provided by MLPerf
- Hyper-parameter search done by HPE

EDGE: JETSON



- Installation of software
- Memory limitations
- Long executions



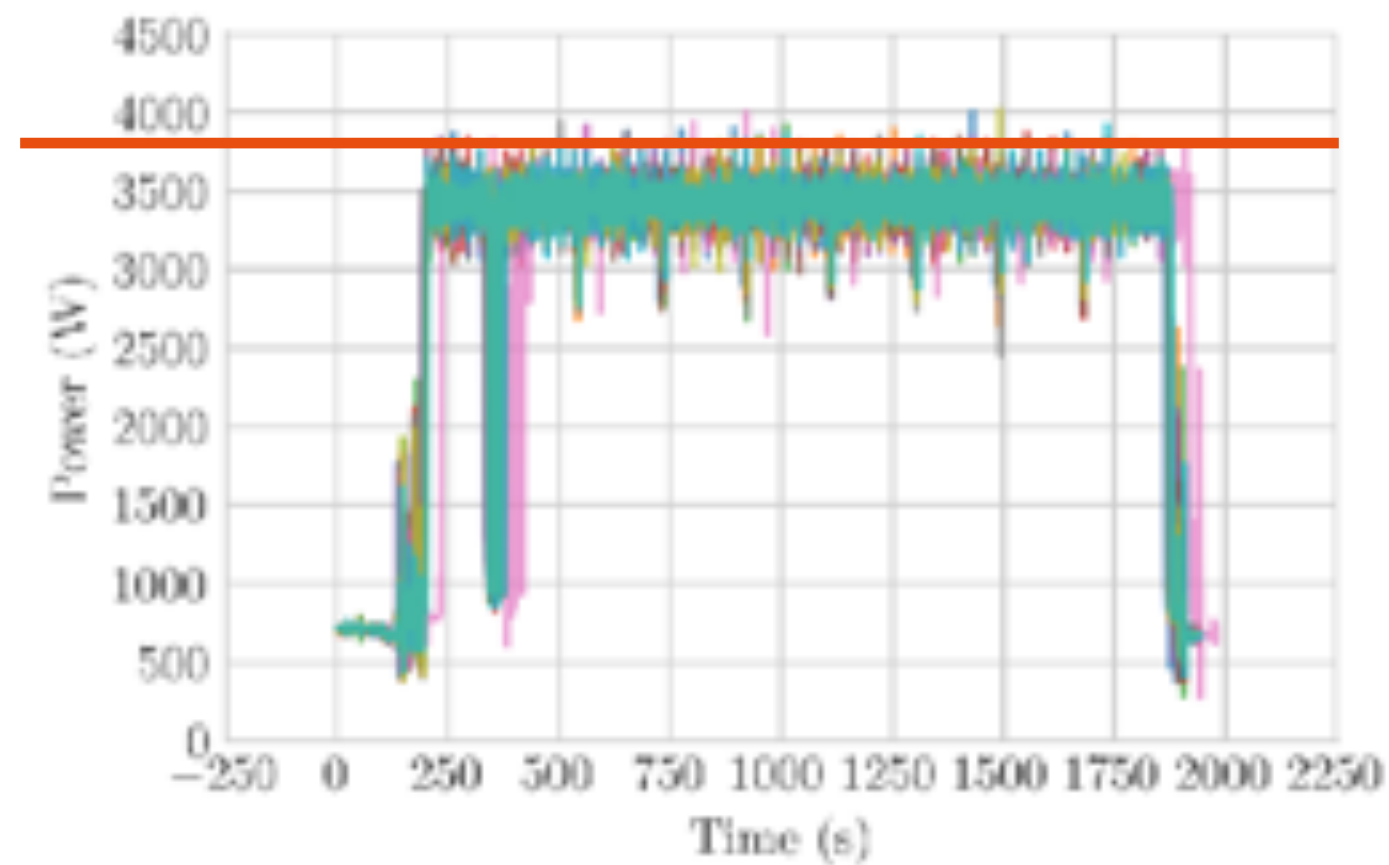
Focus on ResNet-50

Power profiles can vary significantly

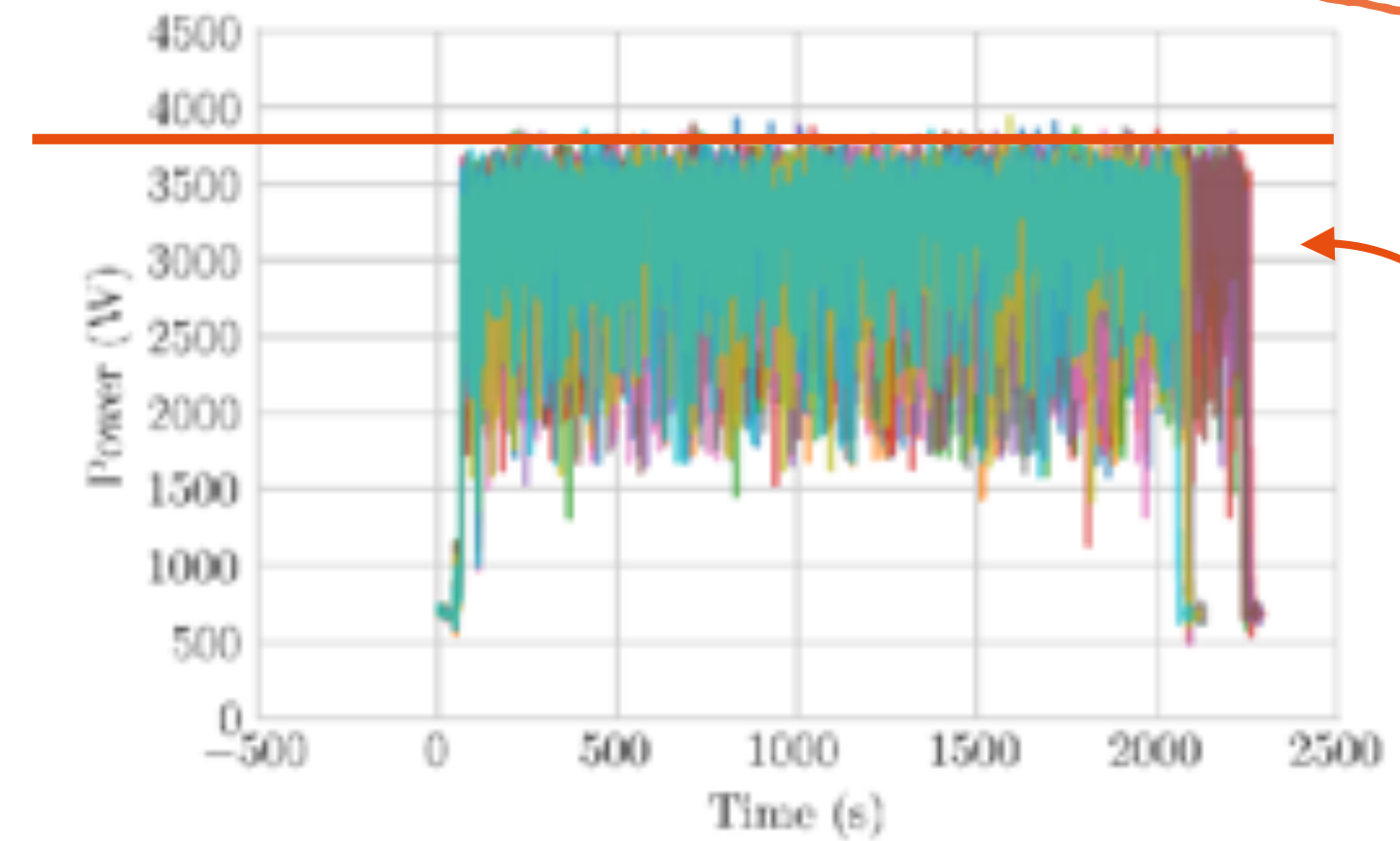
TDP = 3760 W

Power profile = Power consumed by the 8 GPUs and the 2 CPUs as measured by NVML and RAPL.

HPC: APOLLO

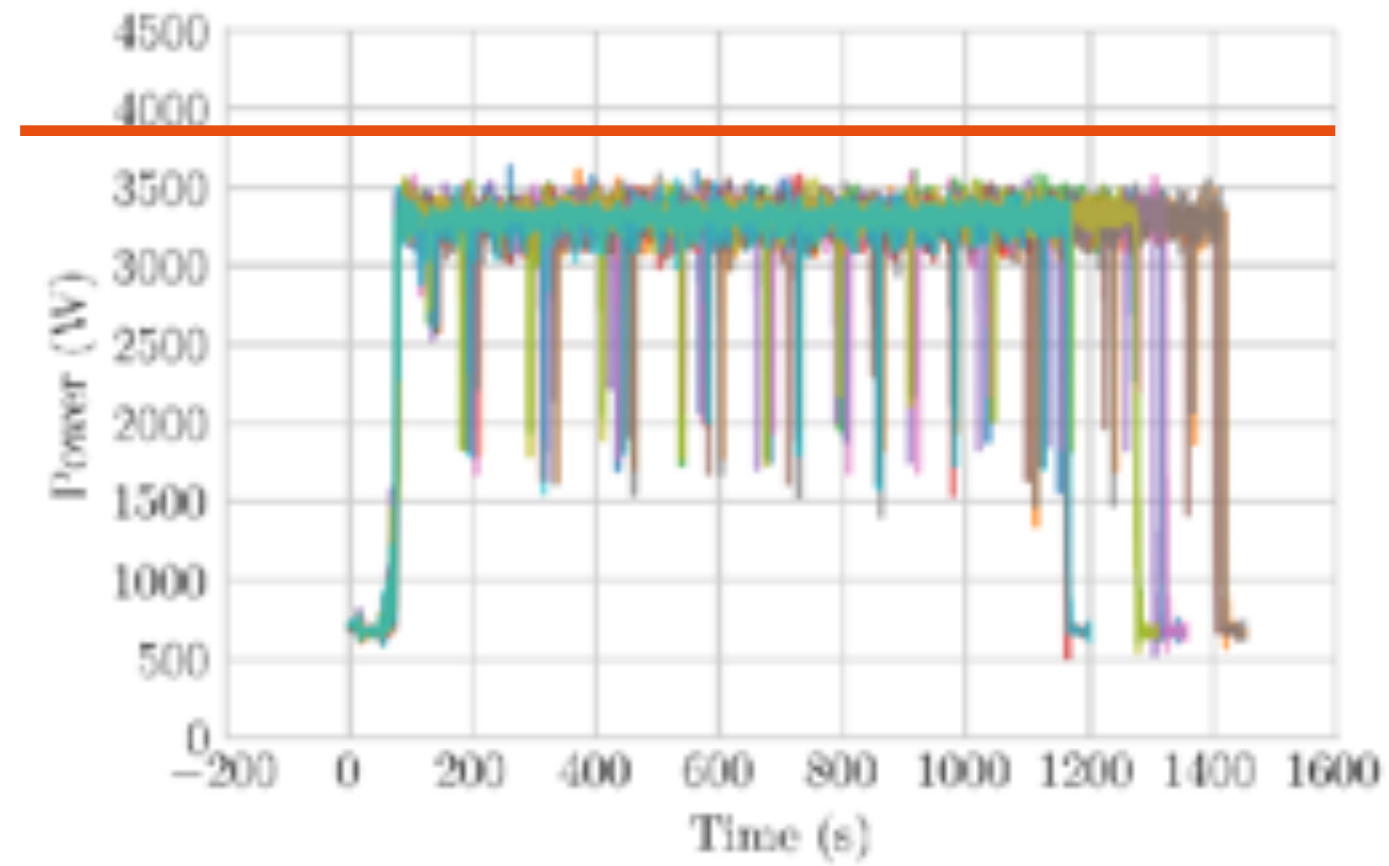


Power profile of ResNet-50 FU

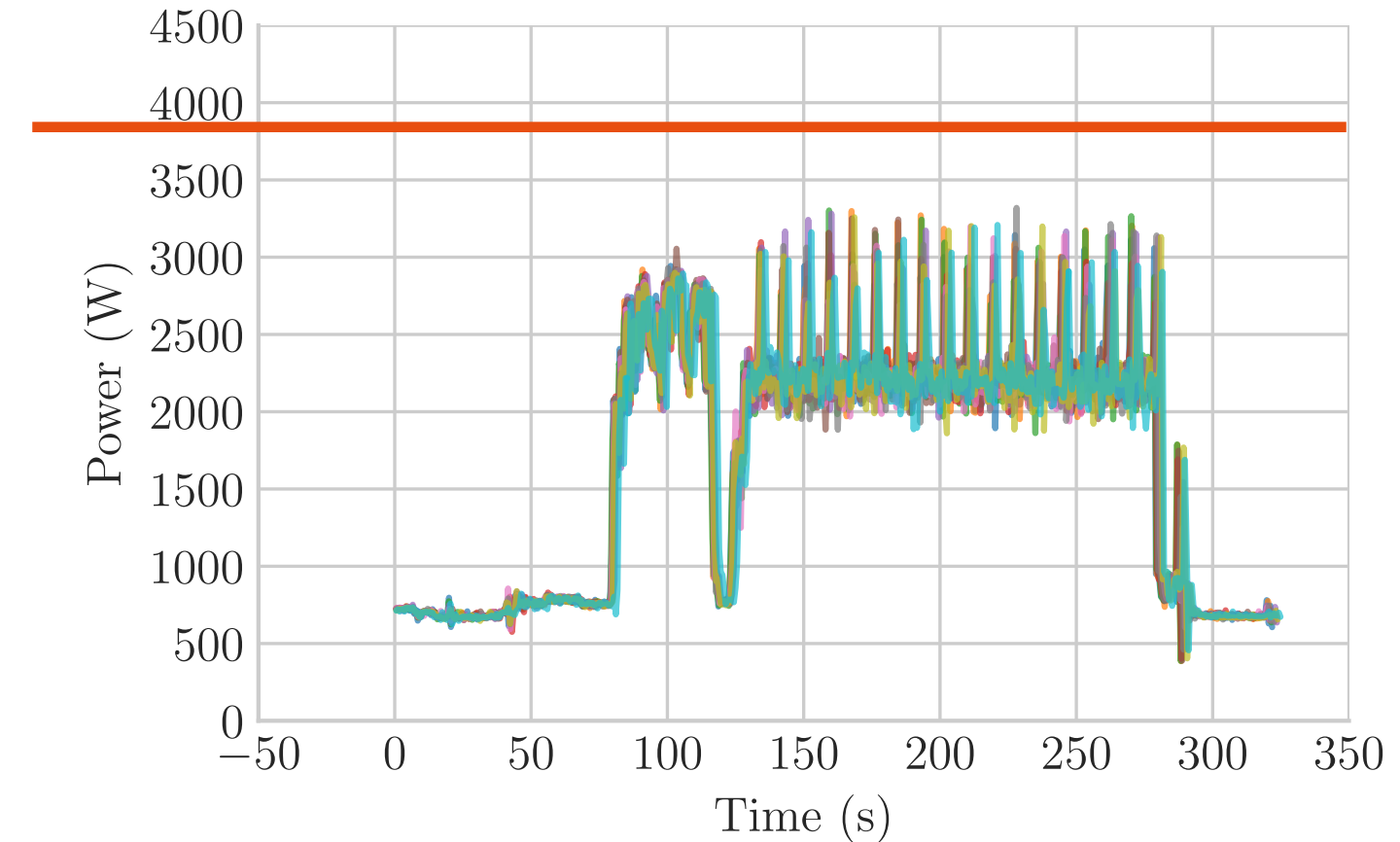


Power profile of RNN-T FU

1 color = 1 repetition of the training



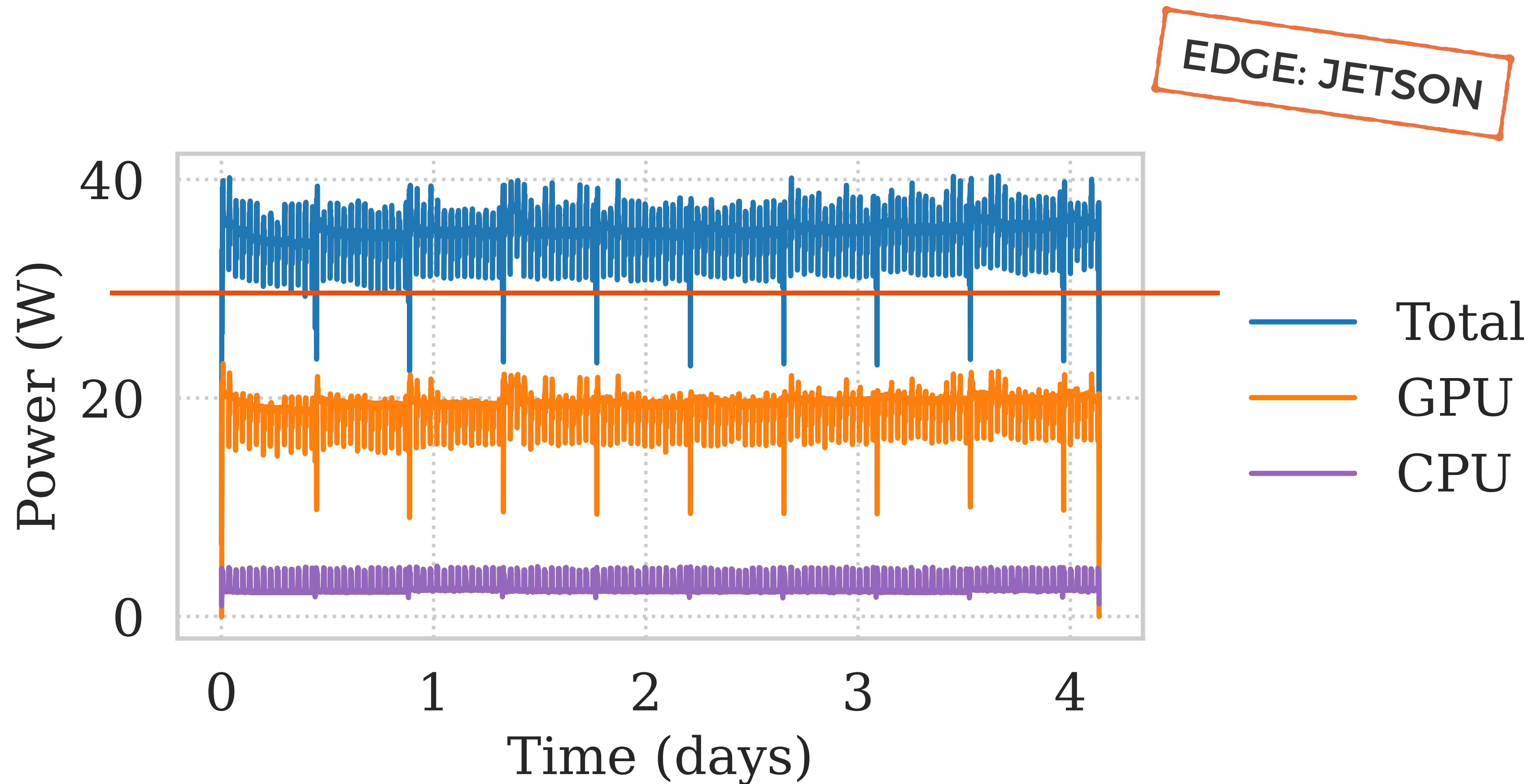
Power profile of Mask R-CNN FU



Power profile of DLRM FU

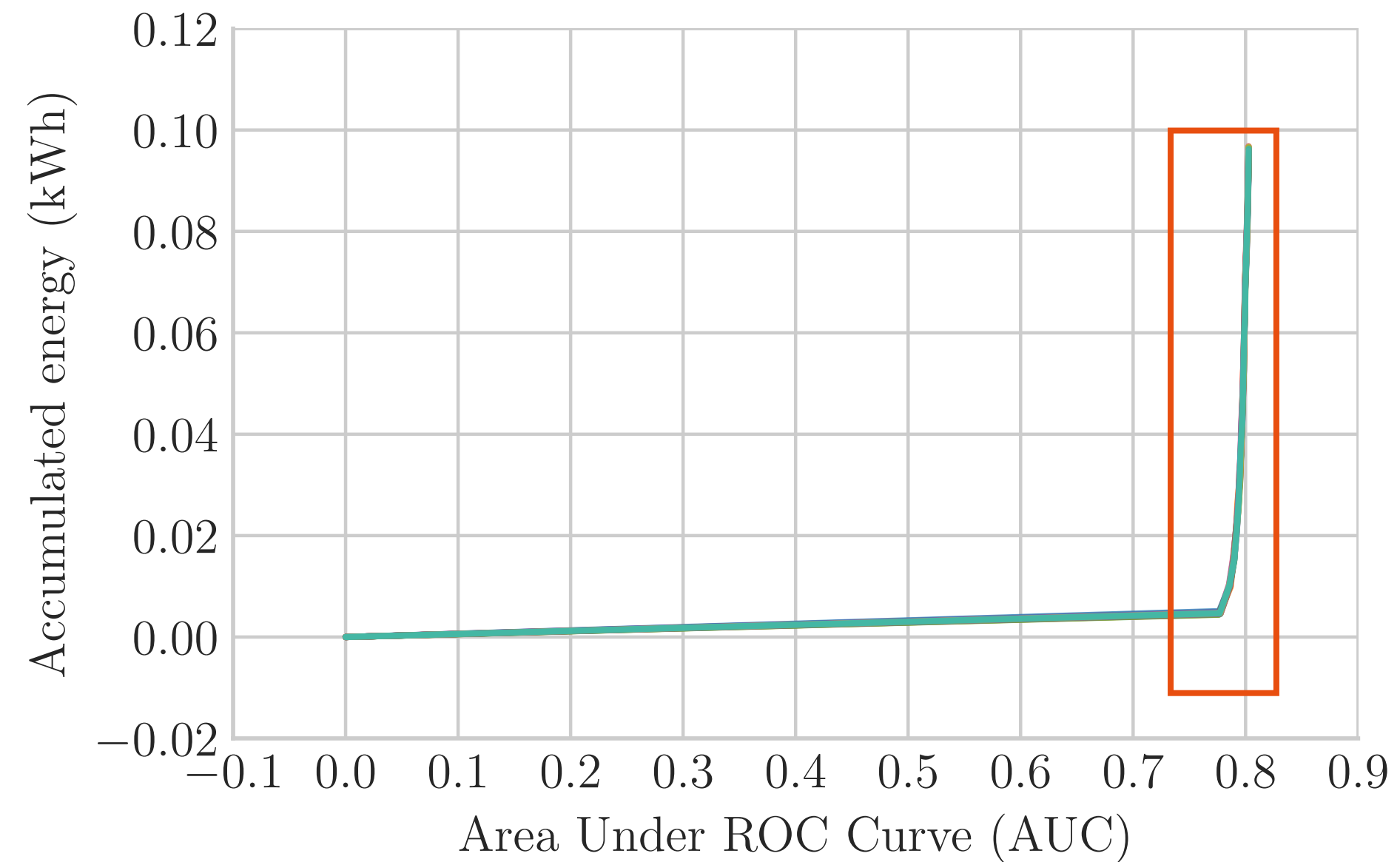
Power consumption can be higher than the TDP

TDP = 30 W

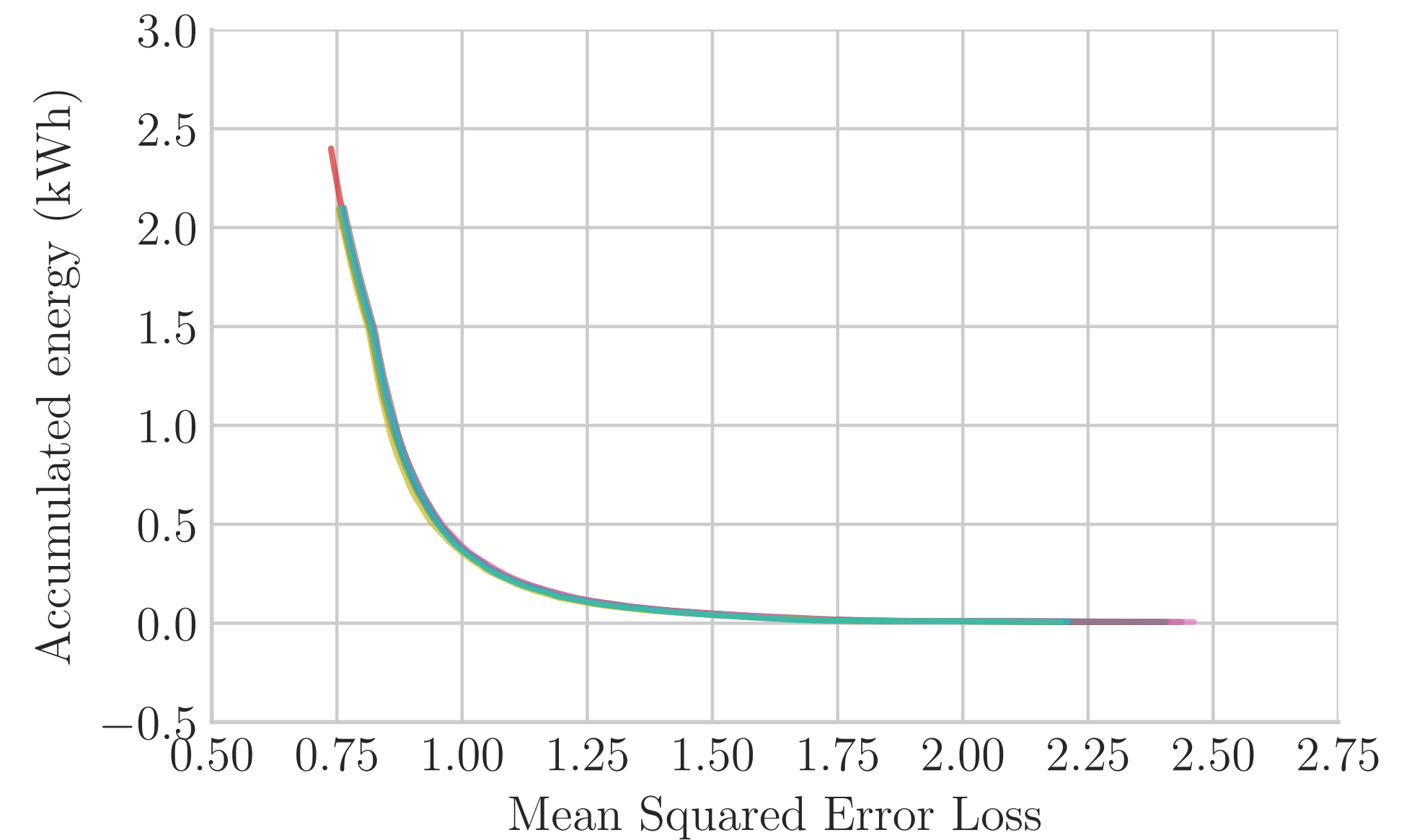


Power profile of ResNet-50 FU.

Most energy can be spent on the very last quality point



Energy required to reach each quality metric point for the DLRM FU



Energy required to reach each quality metric point for the Mask R-CNN FU

HPC: APOLLO

The ResNet FU impacts are shared between phases

$$I_{Embodied,FU} = \frac{T_{FU}}{T_{node}} * I_{Embodied,Node}$$

$$I_{FU} = IF_{elec} * E_{FU} + I_{Embodied,FU}$$

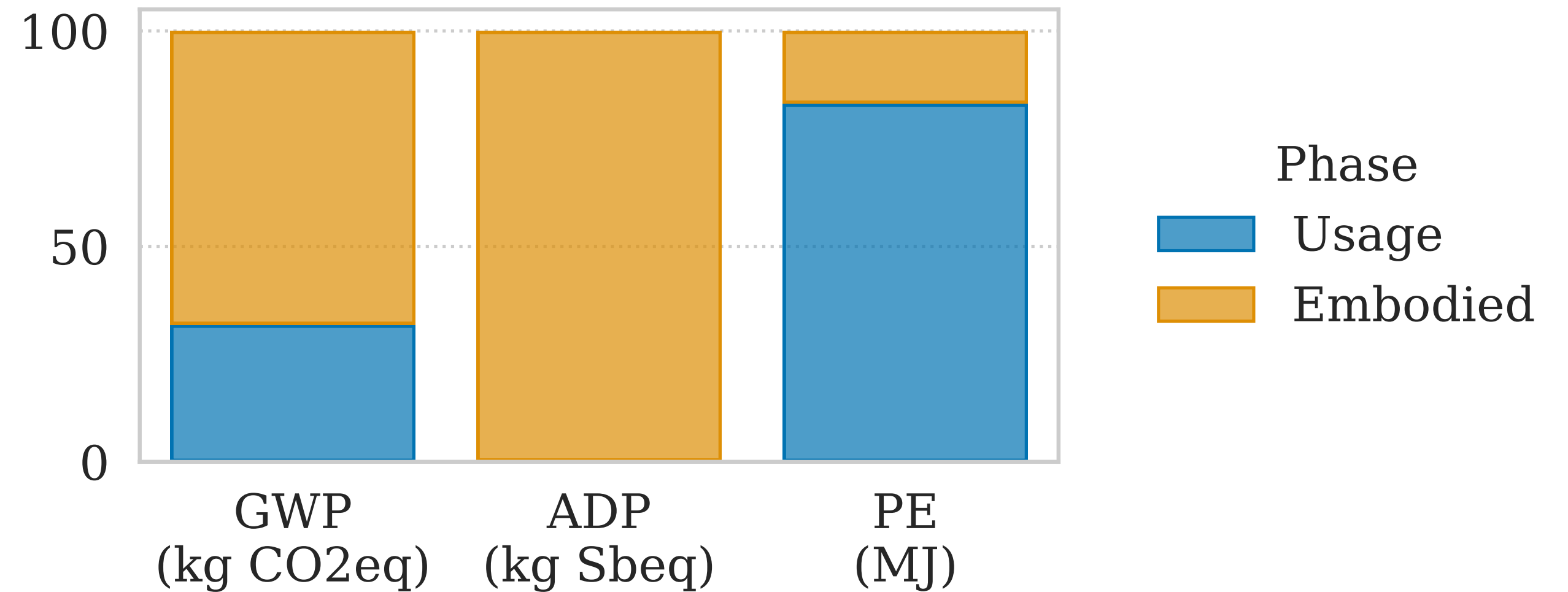
I : Environmental Impact (expressed in kg CO2 eq, kg Seb, and MJ)

T : Use time of the equipment

IF_{elec} : Electricity mix Impact Factor

E : Electricity consumption

EDGE: JETSON



Share of usage and embodied phase in the total impacts of the ResNet-50 * FU on the **Jetson** node

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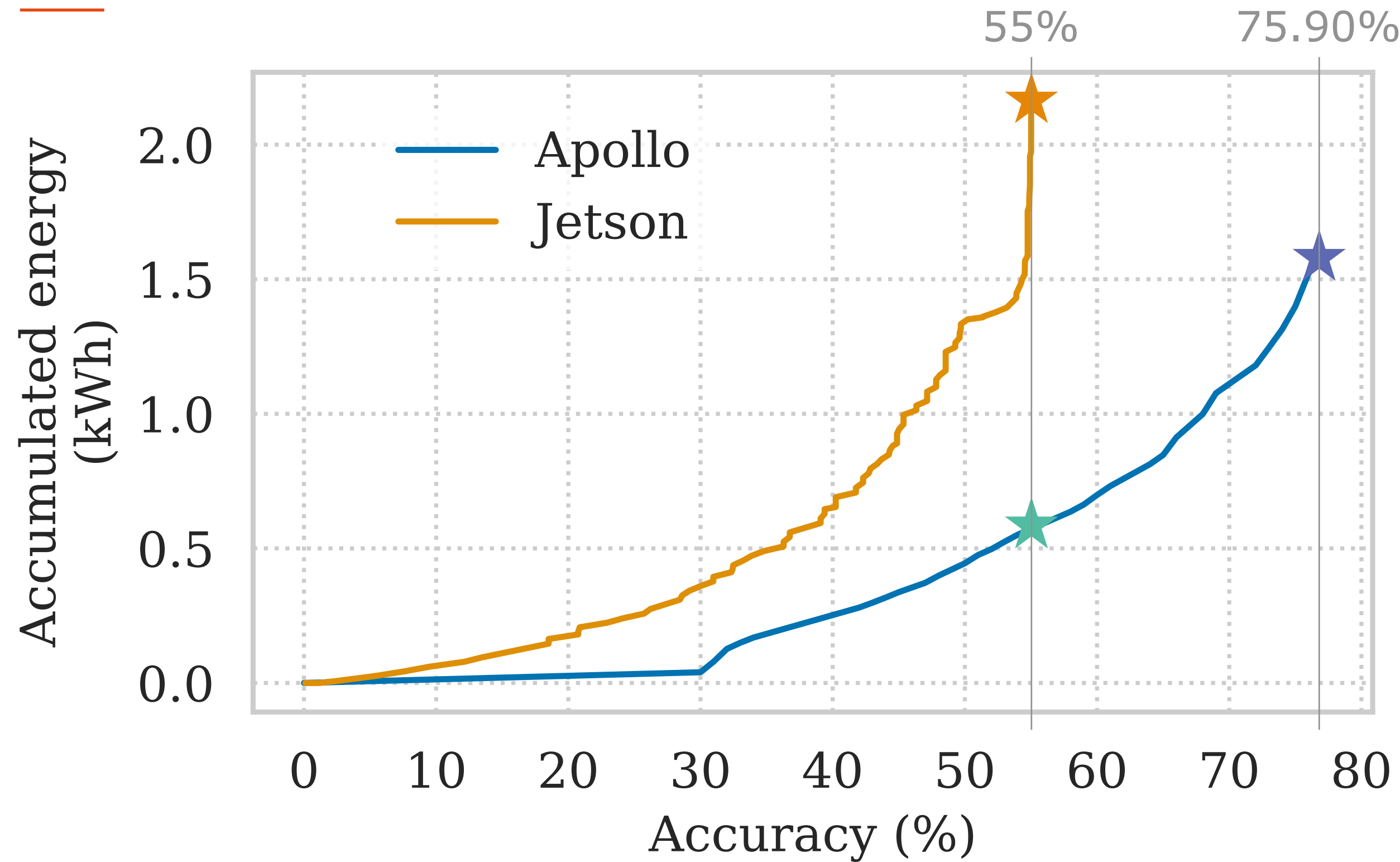
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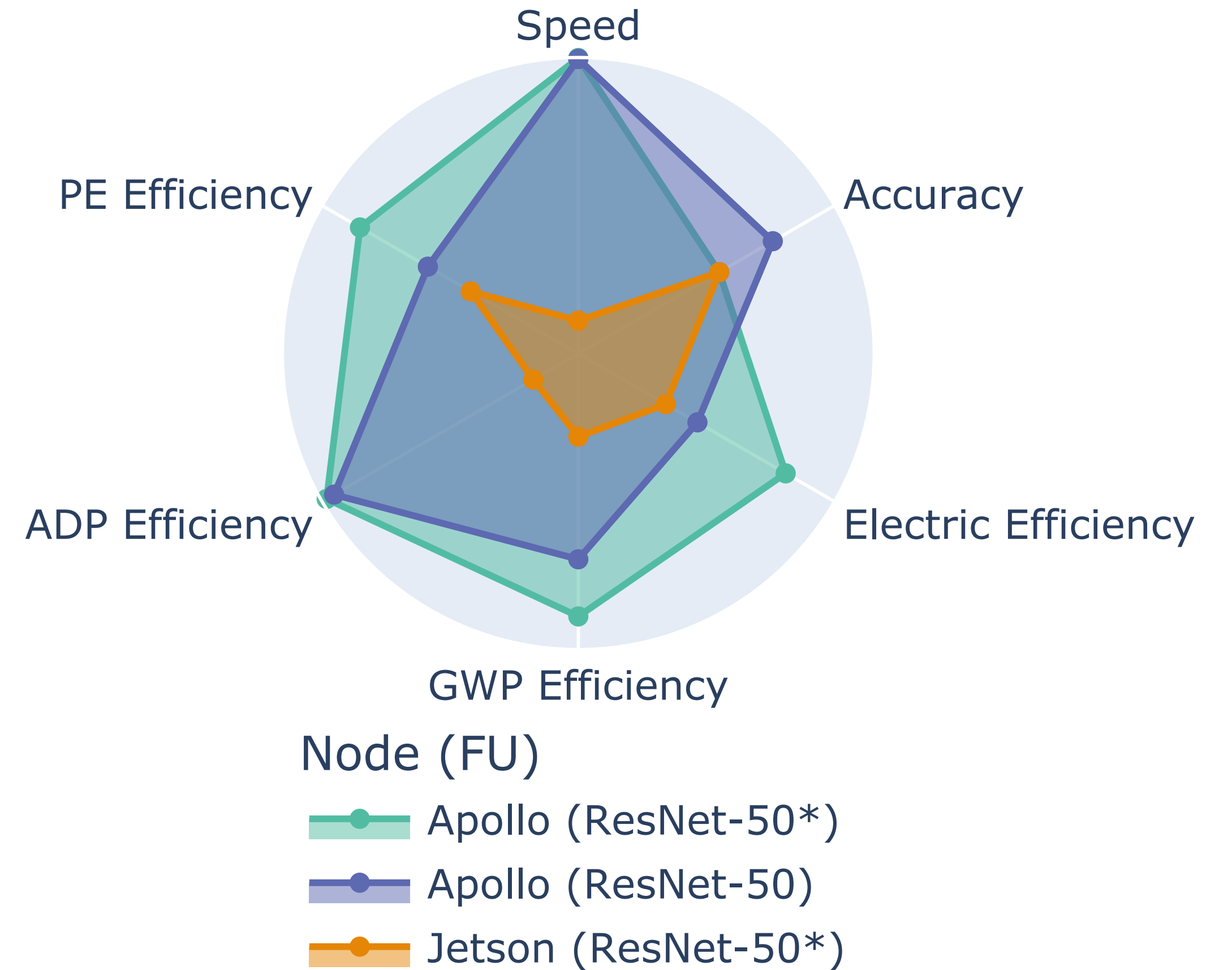
Conclusion & perspectives

Apollo outperforms Jetson on the performance and environmental criteria



ResNet-50 FU: *Train ResNet-50 on ImageNet until it achieves a **75.90%** classification score*

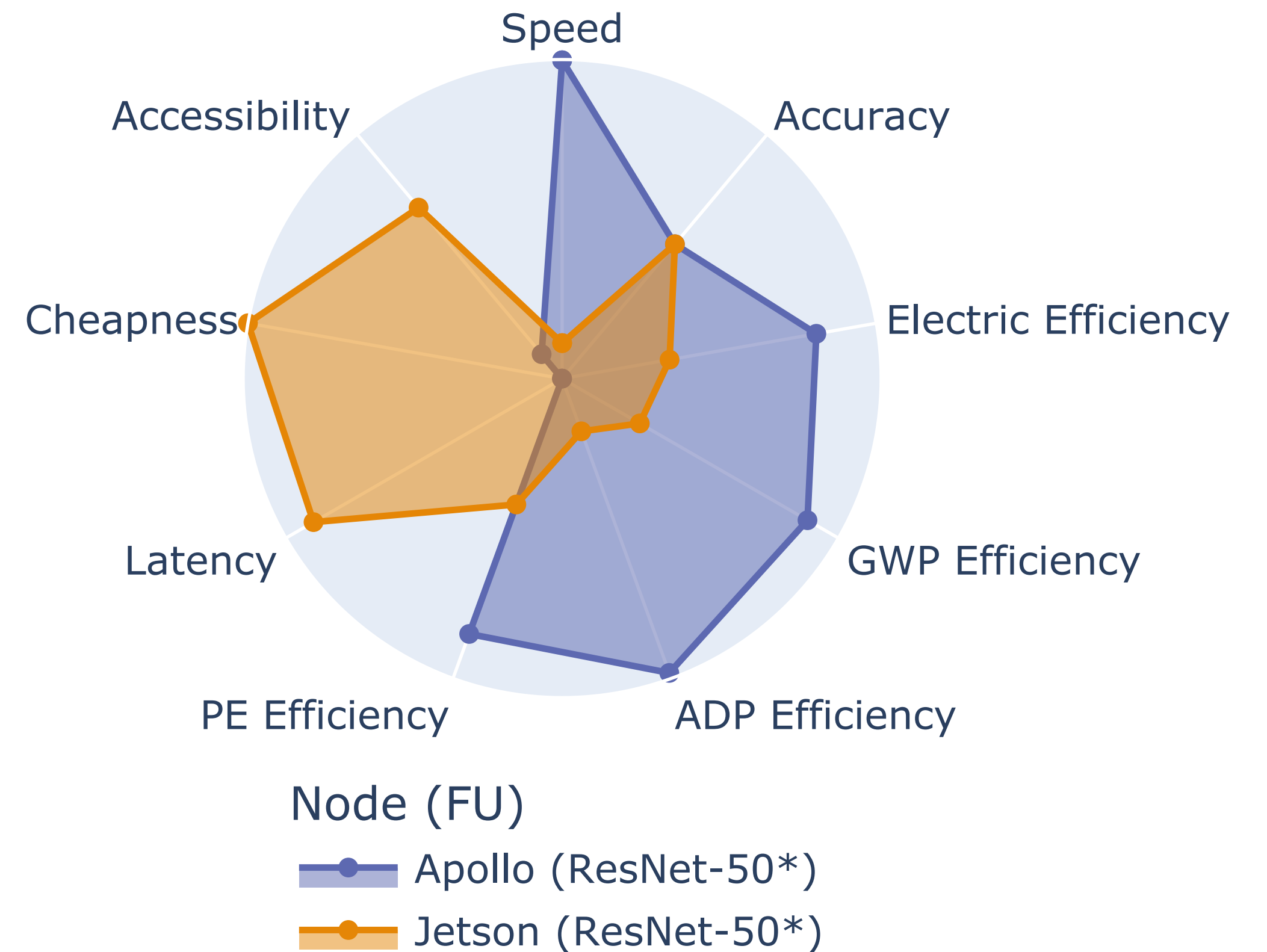
ResNet-50* FU: *Train ResNet-50 on ImageNet until it achieves a **55%** classification score*



Multi-criteria comparison including performance metrics and environmental metrics

Comparing infrastructures requires more criteria

- Jetson was designed for the edge and its associated constraints
 - Price
 - Latency
- Edge computing can be an opportunity for constraining computations



Multi-criteria comparison including performance, environmental, and qualitative metrics



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Advantages of our approach

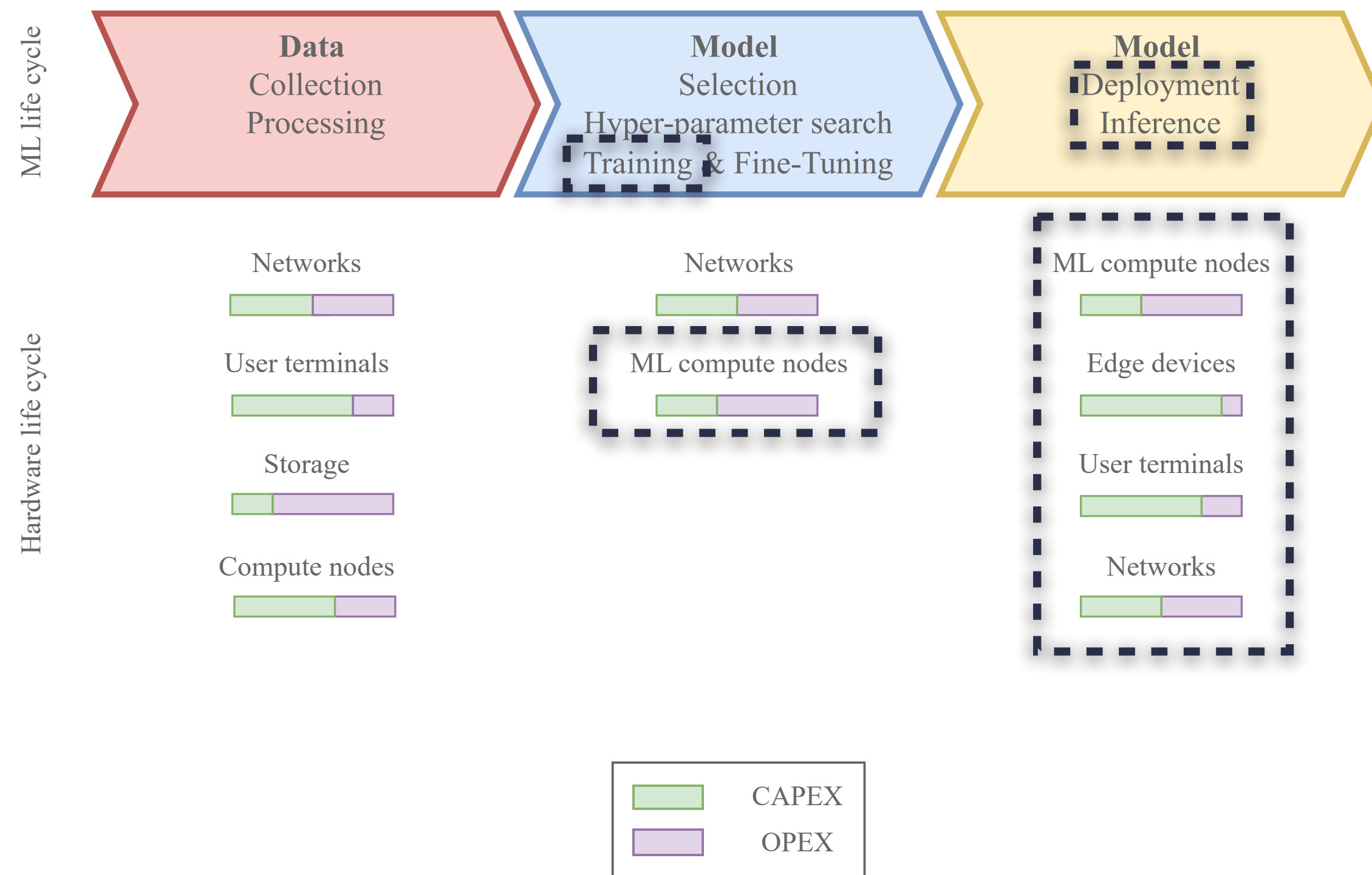
- Versatility
 - Can do both **operational** and **embodied** assessments on most infrastructures
- Reproducibility
 - Rely on **open** databases and **open source** measuring tool
 - Code is available and reusable
- Insightfulness
 - Power profile, accuracy/power tradeoff, details of component embodied footprint provide a **better understanding** and the possibility to find **actionable reduction plans**
- Enables a **fair comparison** between infrastructures and ML models

Limits

- Accuracy
 - Lack and **uncertainty** of LCA databases
 - **Offset** between software-based and external power meters not included
- Scope 2 and 3 outside of assessment
- Changes in learning
 - Focus on centralized training when other training approach are developed such as **Federated Learning**
 - Requires **replication** when trainings can last for days
- Other phases of ML life cycle
 - Focus on the training phase, omitting **deployment** and **data collection**

Estimating the environmental impacts of a Generative AI service

Enlarge the scope

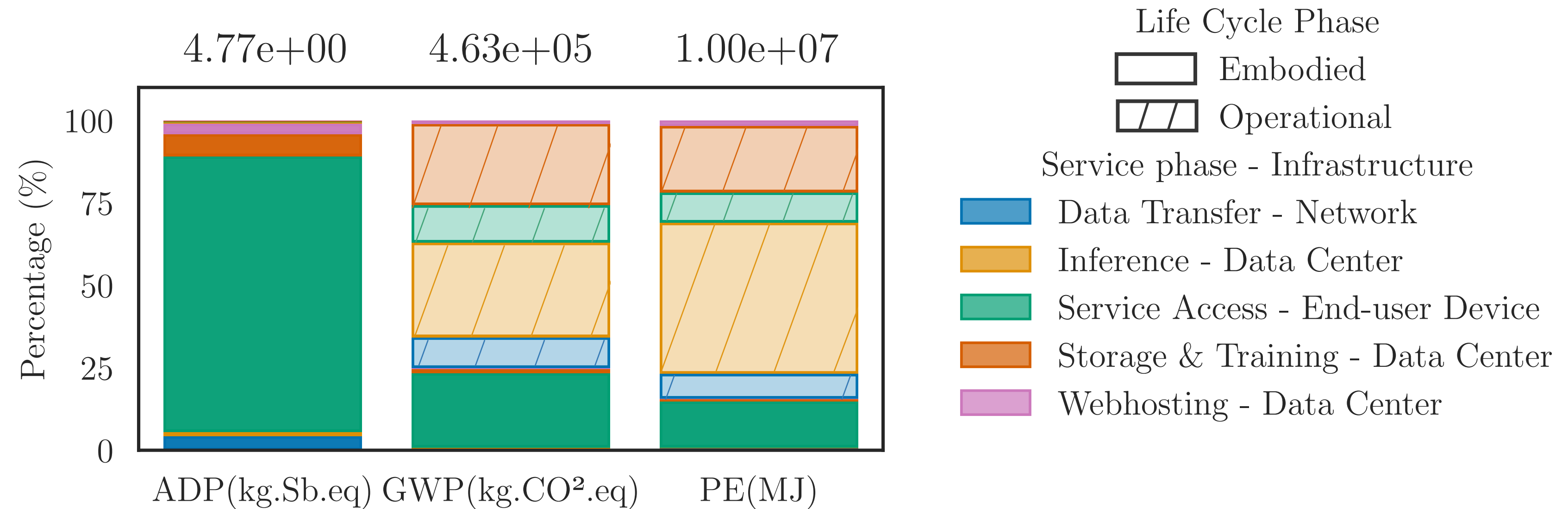


- Application: Stable Diffusion
 - Open source
 - **Deployed** online as a service
- Combinaison of
 - **Measurements** (Training, Inference)
 - **Allocations from LCA databases**
- Training too long to replicate
 - Measurement of a **fraction** of training
 - Linear **regression** from number of steps

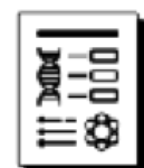


Each phase of the ML and hardware life cycles is significant

- The ADP impact is dominated by the embodied phase of hardware.
- The GWP and PE impacts come from the operational phase.
- The deployment causes most of the impacts.



Share (in percentage) of the life cycle phases of each digital infrastructure in the total impacts of the Stable Diffusion service for one year.



Adrien Berthelot, Eddy Caron, Mathilde Jay, Laurent Lefèvre. Estimating the environmental impact of Generative-AI services using an LCA-based methodology. *CIRP LCE 2024 - 31st Conference on Life Cycle Engineering*, Jun 2024, Turin, Italy.



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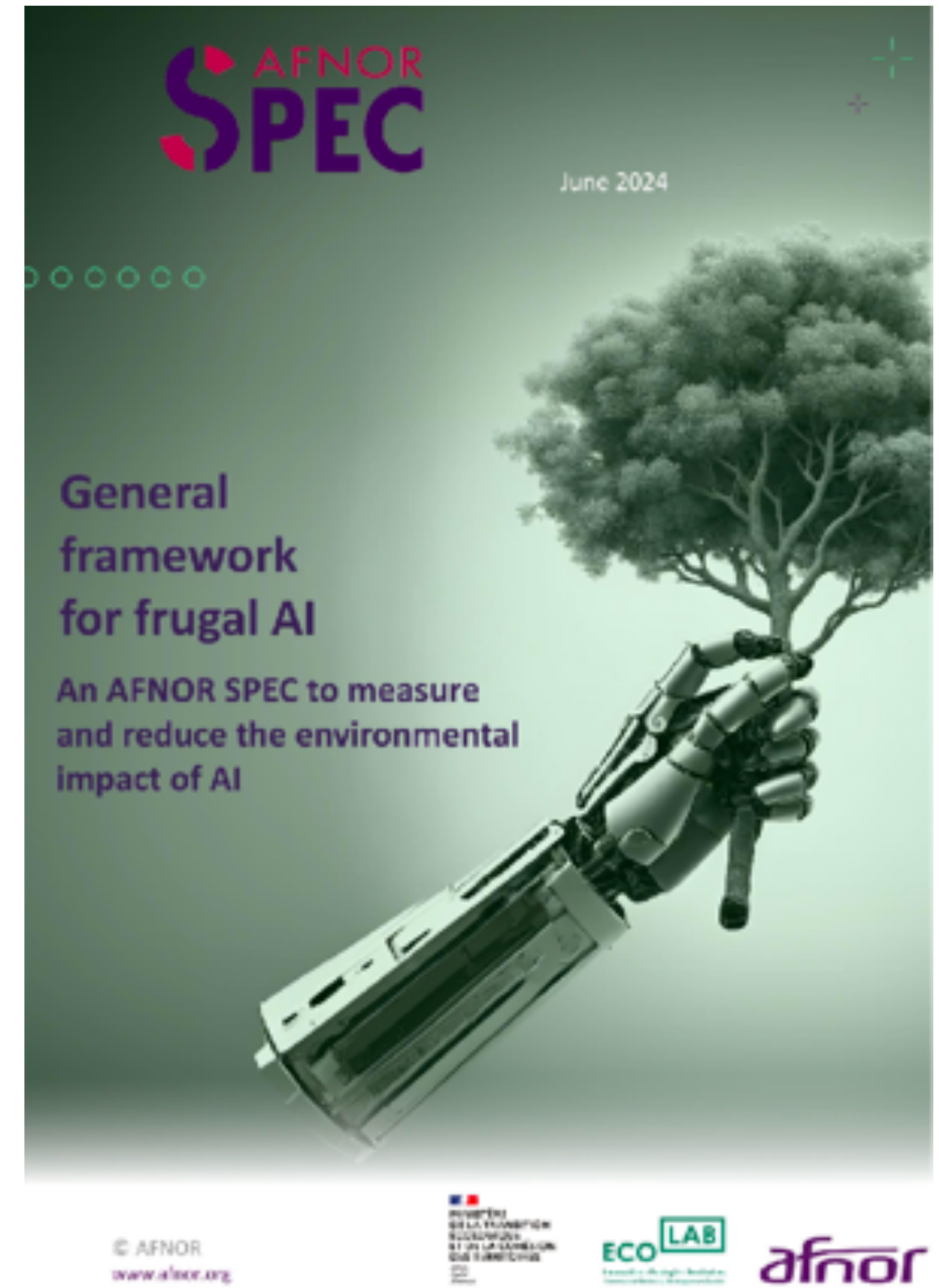
Conclusion & perspectives

Conclusion

- Impacts of Machine Learning are booming when they should be reduced
- Need of reporting and controlling those impacts
- Methodology: LCA for training
 - 3 LCA impact indicators
 - Operational, resource extraction, manufacturing & distribution phases
 - Insightfulness, Versatility, Reproducibility
- Multi-criteria comparison of an Edge Device and a Supercomputer
- A significant offset between power meters
- Quality target/energy tradeoff
- For bigger models, electricity consumption can be estimated
- Scope can be extended to other ML life cycle phases

Perspectives

- Increasing the scope
 - Full node, storage, networks, cooling
 - Data collection
- Supercomputer-Edge scenario
 - Including network
- Consequential LCA
 - Encompasses indirect effects
 - But more complex to model
- Assessing the sustainability of an ML model
 - EU AI act: security, transparency, ethics

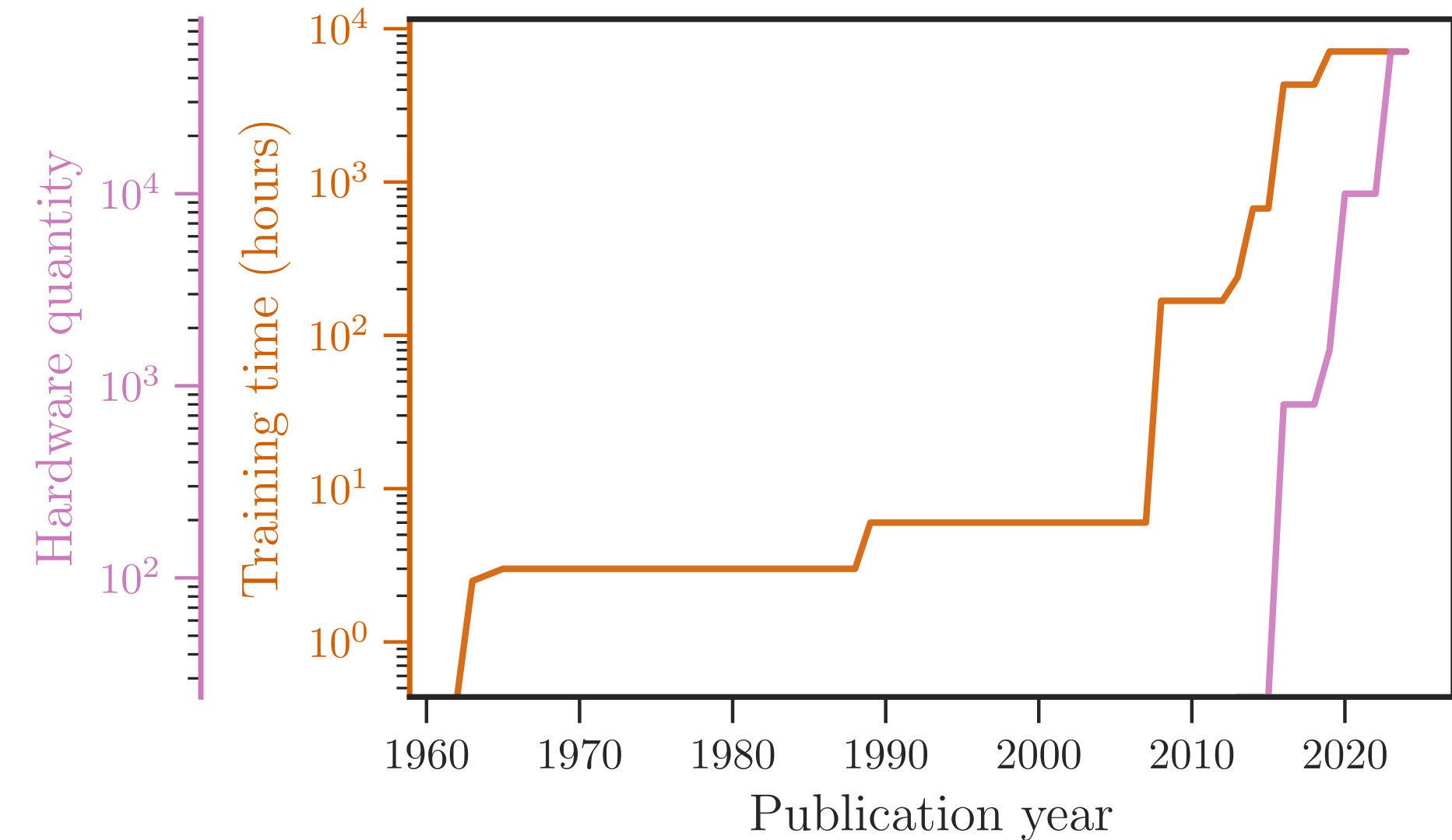
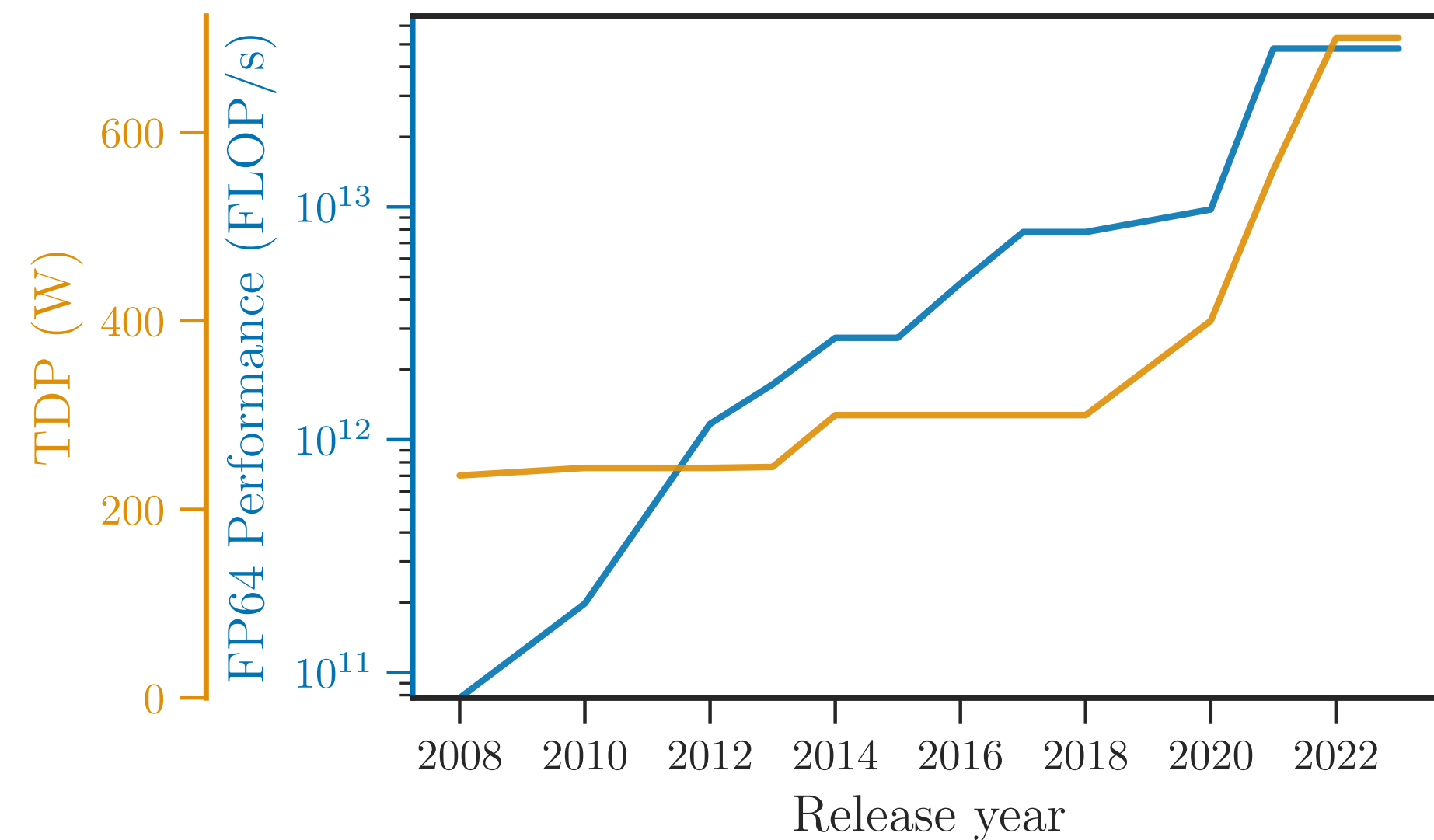


Appendix

A **versatile methodology** for assessing
the **electricity consumption and
environmental footprint** of
machine learning training:
from **supercomputers to edge devices**

Context

Machine Learning and its materiality



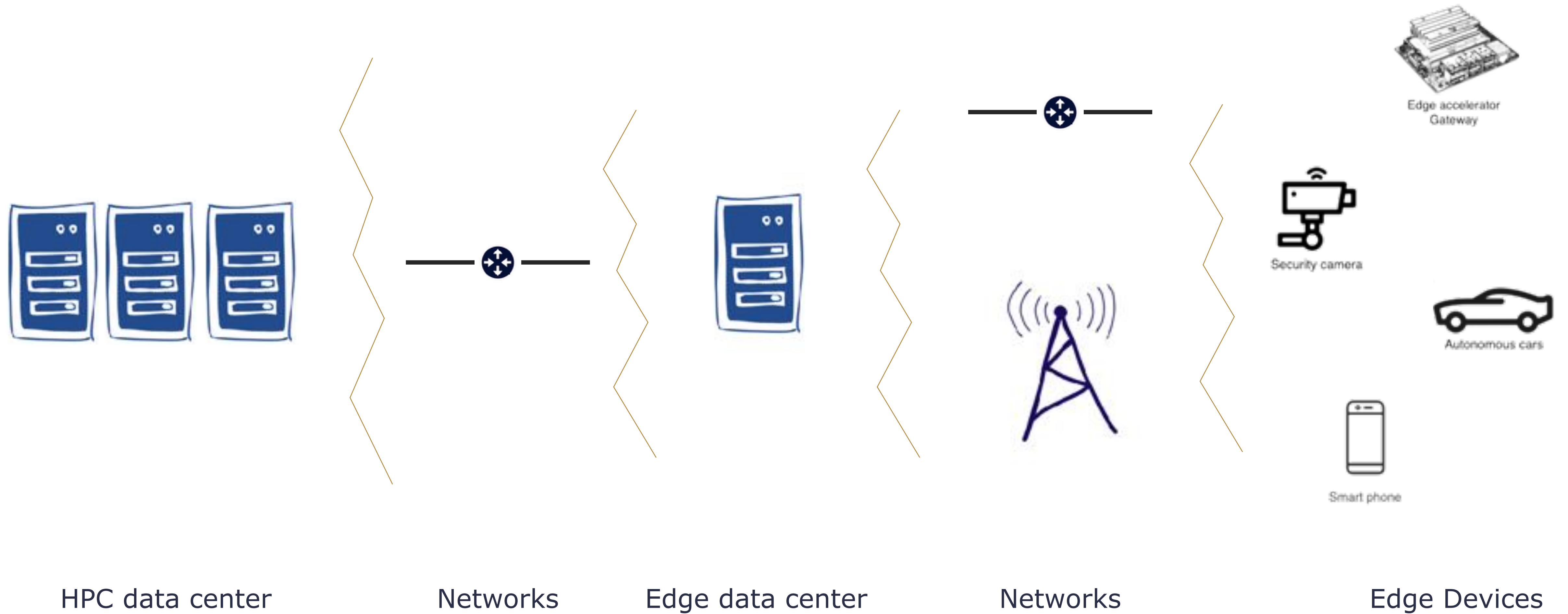
Evolutions in Machine Learning specialized hardware (GPU, TPU) metrics, as the maximum value up to the given year [Hobbhahn2023].

Evolutions in Machine Learning Model and their training, as the maximum value up to the given year. [EpochAI2024]

TDP (Thermal Design Power): A hardware characteristic provided by the manufacturer that corresponds to the maximum amount of heat that can be generated by a component under a steady workload measured in watts.

Exponential increase in the electricity consumption of training Machine Learning models

Machine Learning services and its materiality



Machine Learning and its materiality

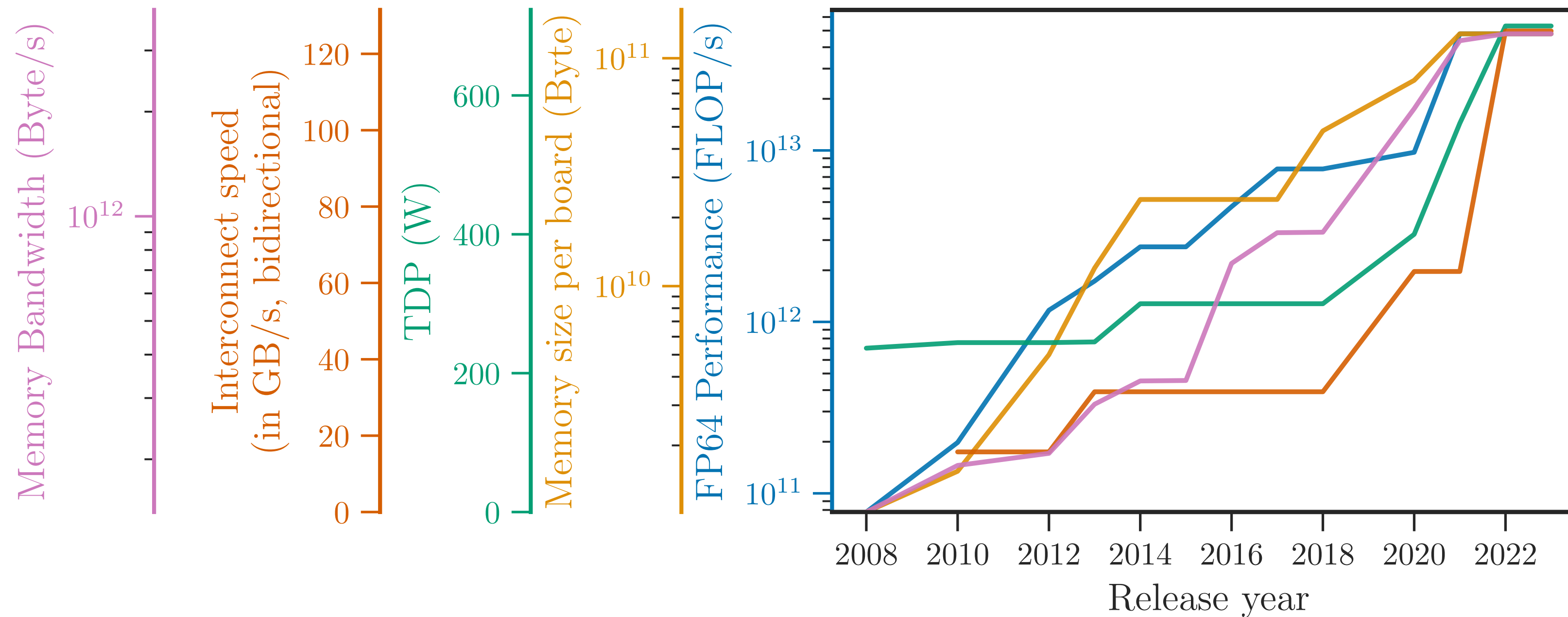
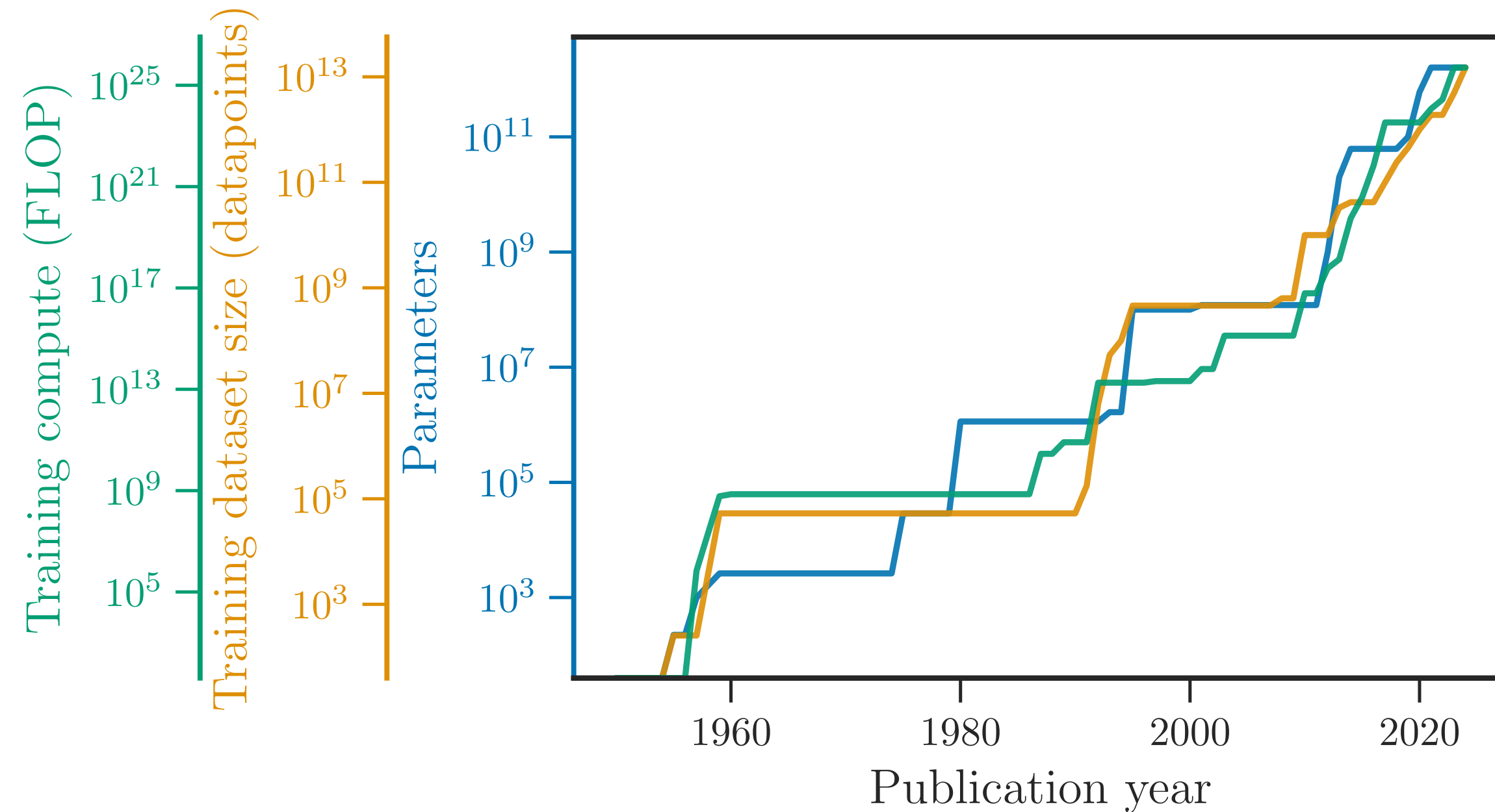


Figure: Evolutions in Machine Learning specialized hardware (GPU, TPU) metrics, as the maximum value up to the given year.

Machine Learning Boom



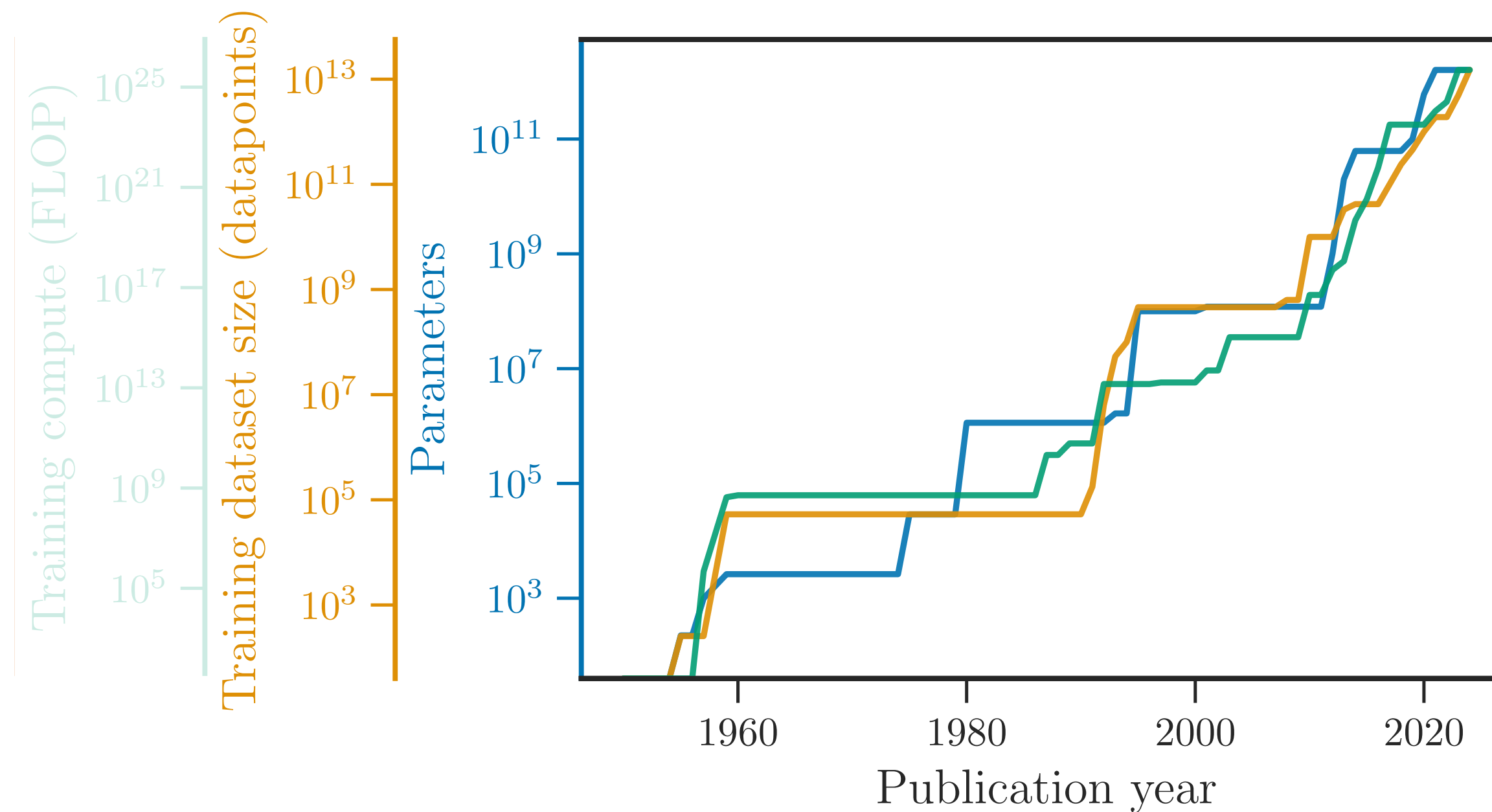
Evolutions in Machine Learning Model and their training, as the maximum value up to the given year. [EpochAI2024]

Parameters: Variables that are learned from the data during the training process. The number of parameters is a representation of the size of the model.

Training Dataset: Collection of data that the ML model is trained on.

Training computing (FLOP): number of mathematical operations (+, -, *, /) performed to train the model.

Machine Learning Boom



Evolutions in Machine Learning Model and their training, as the maximum value up to the given year. [EpochAI2024]

Parameters: Variables that are learned from the data during the training process. The number of parameters is a representation of the size of the model.

Training Dataset: Collection of data that the ML model is trained on.



→ Pembroke Welsh Corgi with Cowboy Hat

Quick definition of ML

Objective/Task

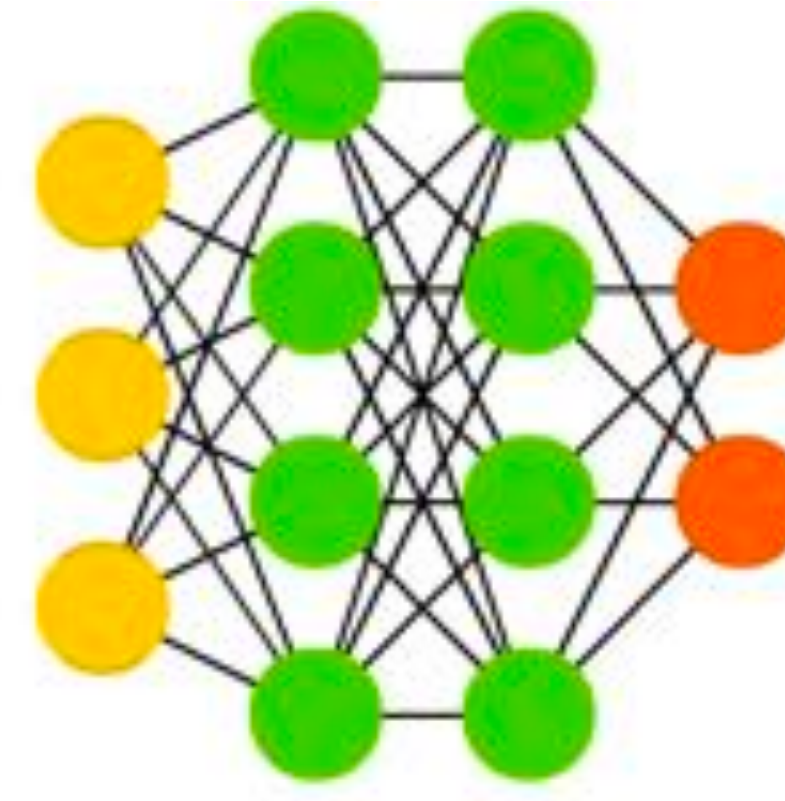
Generating image from text

Data

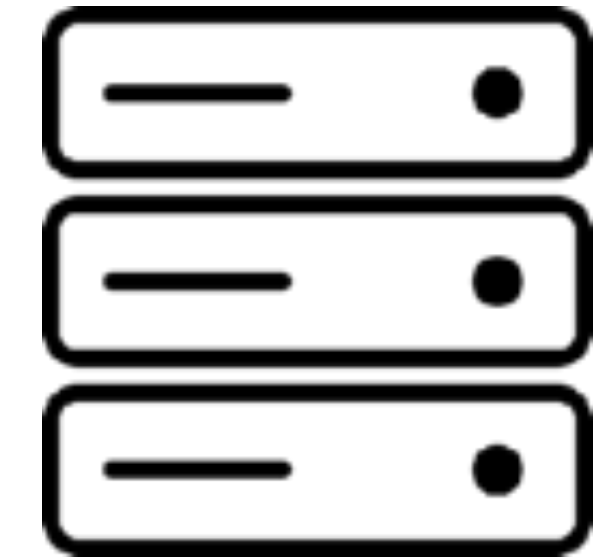


**Pembroke Welsh
Corgi with Cowboy
Hat**

Model



Learning



Machine Learning and its materiality

CPU
Central Processing Units



RAM
Random Access Memory

+

SSD
Solid State Drive



GPU
Graphic Processing Units

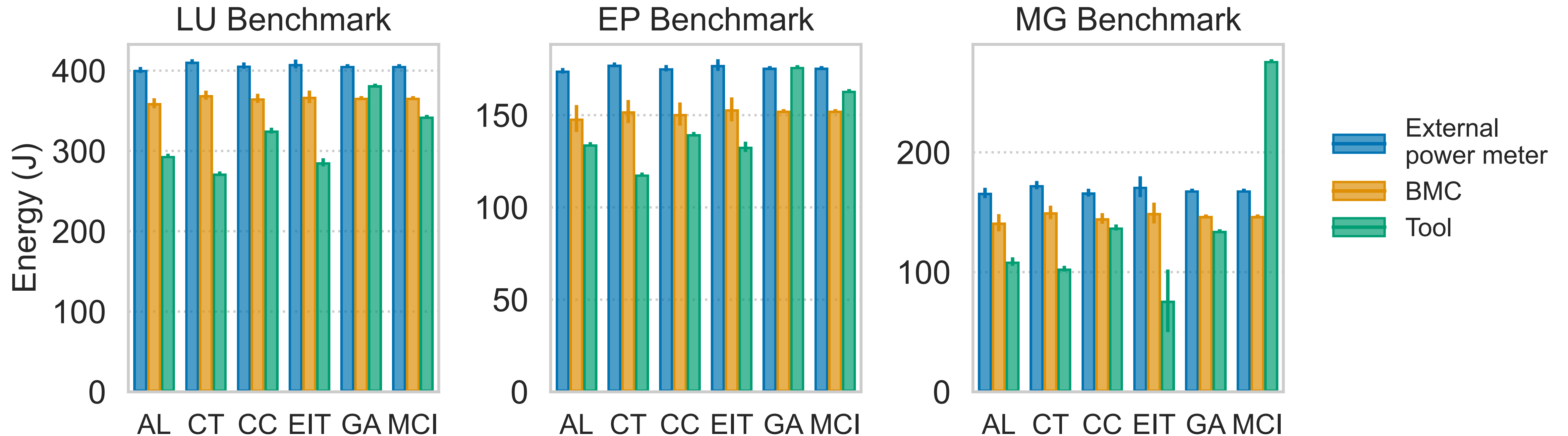


Example of a supercomputer in a Data Center

CCGRID

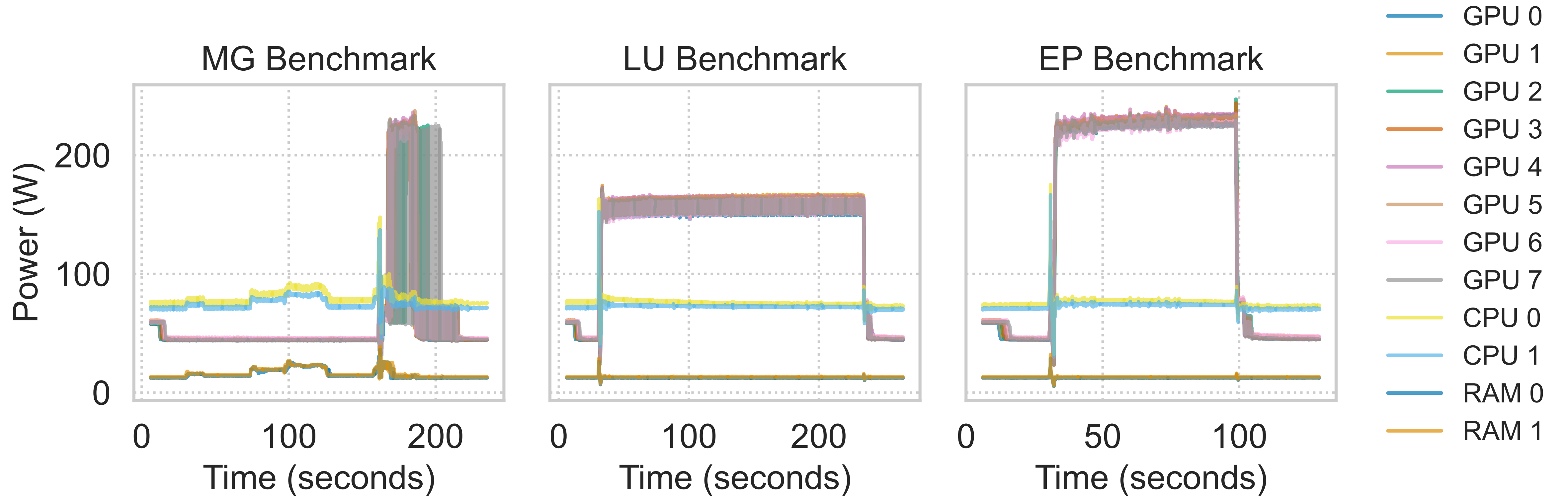
| | External and intra-node devices | | Power profiling software | Energy measurement software packages | | | Energy calculators | |
|---------------------------------------|---------------------------------|--------------------|--------------------------|--------------------------------------|----------------------------------|--------------------------|-------------------------|----------------------------|
| | <i>OmegaWatt</i> | <i>BMC</i> | <i>Alumet</i> | <i>Code Carbon</i> | <i>Experiment Impact Tracker</i> | <i>Carbon Tracker</i> | <i>Green ribbons</i> | <i>Algo- ML CO2 Impact</i> |
| Development | | | | | | | | |
| Origin | | | Eviden, LIG | MILA | University of Stanford | University of Copenhagen | University of Cambridge | MILA |
| First (latest) release date | | | Mar. 2023 (May 2024) | Nov. 2020 (Jan. 2024) | Dec. 2019 (Jan. 2020) | Apr. 2020 (Sept. 2023) | Jul. 2020 (Apr. 2023) | Aug. 2019 (Jul. 2022) |
| Environment | | | | | | | | |
| Hardware compatibility | Any | Any | Intel RAPL, Nvidia NVML | Any | Intel RAPL, Nvidia NVML | Intel RAPL, Nvidia NVML | Any | Any |
| Scope | Node | Node | CPU, DRAM, GPU | CPU, DRAM, GPU | CPU, DRAM, GPU, process | CPU, DRAM, GPU | Node | Node |
| Job management support | | | No | No | No | No | | |
| Functional | | | | | | | | |
| Hardware technology used | | | RAPL, NVML | RAPL, NVML, TDP | RAPL, NVML | RAPL, NVML | TDP | TDP |
| Software power model used | | | | | GPU, CPU and RAM usage-based | | | |
| Default sampling frequency (Hz) | 1 | 0.2 | 2 | 1/15 | 1 | 0.1 | | |
| Online reporting | Yes | Yes | Yes | No | No | No | No | No |
| Power profiling | Yes | Yes | Yes | No | No | No | No | No |
| User-friendliness | | | | | | | | |
| Availability of source code (License) | | | Yes (EUPL 1.2) | Yes (MIT) | Yes (MIT) | Yes (MIT) | Yes (CC-BY-4.0) | Yes (MIT) |
| Ease of use | Poor | Poor | Good | Good | Good | Good | Very good | Very good |
| Quality of documentation | | | Good | Fair | Fair | Good | Good | Fair |
| Configurability | Fair | Poor | Good | Poor | Quite good | Poor | Poor | Poor |
| Resulting data format | HTTP endpoint | HTTP endpoint | CSV | CSV | JSON, Code | File, Code | Web | Web, Latex |
| Data visualization possibilities | Grafana (Kwollect) | Grafana (Kwollect) | | Comet | | | Graphs on the web page | |

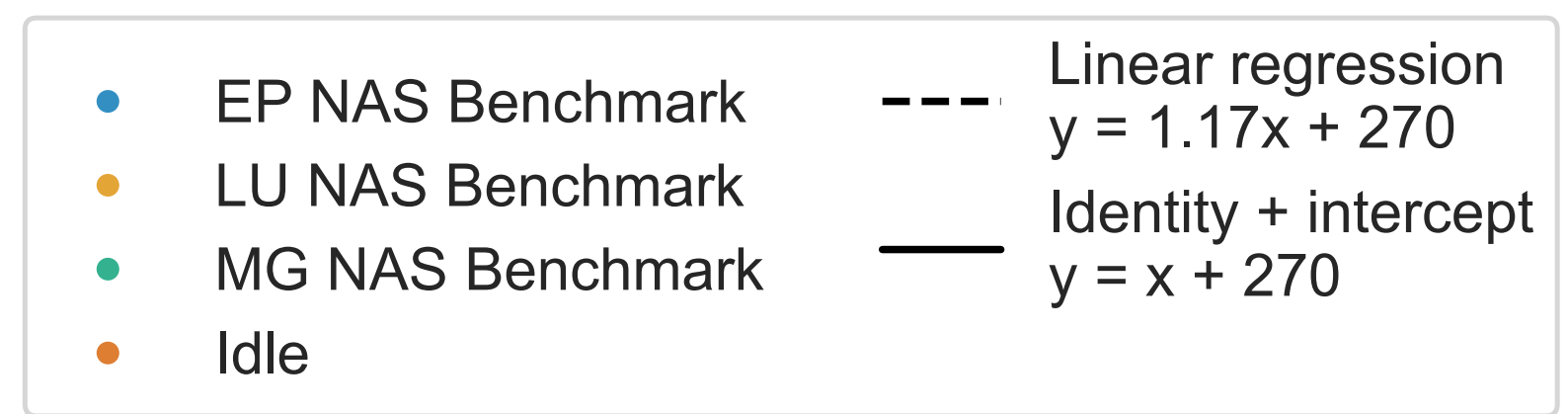
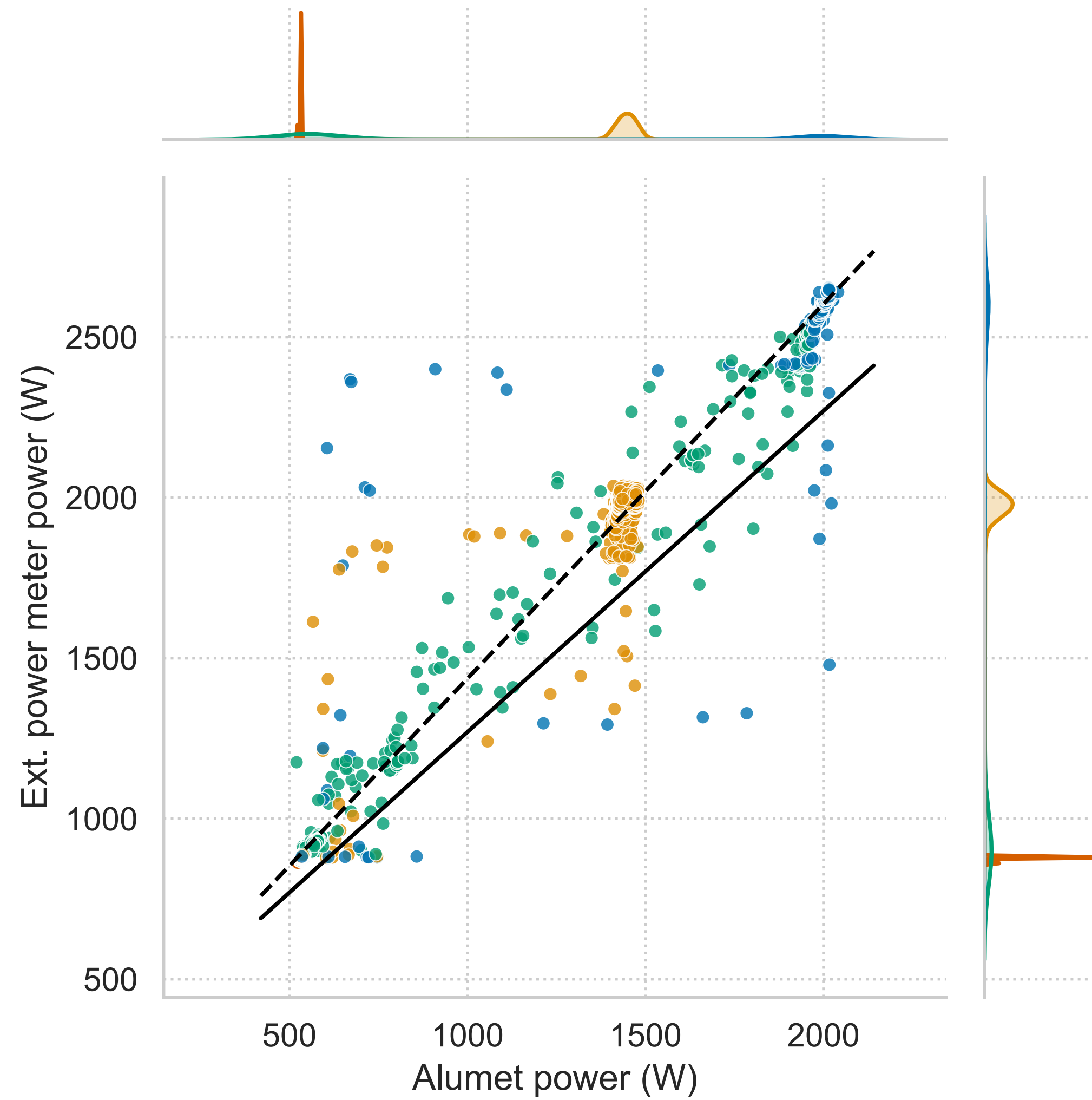
Comparing tools



AL: ALUMET, CT: Carbon Tracker, CC: Code Carbon,
EIT: Exprimet Impact Tracker, GA: Green Algorithm, MCI: ML CO2 Impact

Per component consumption





Electricity

Infrastructures

HPC: APOLLO

EDGE: JETSON

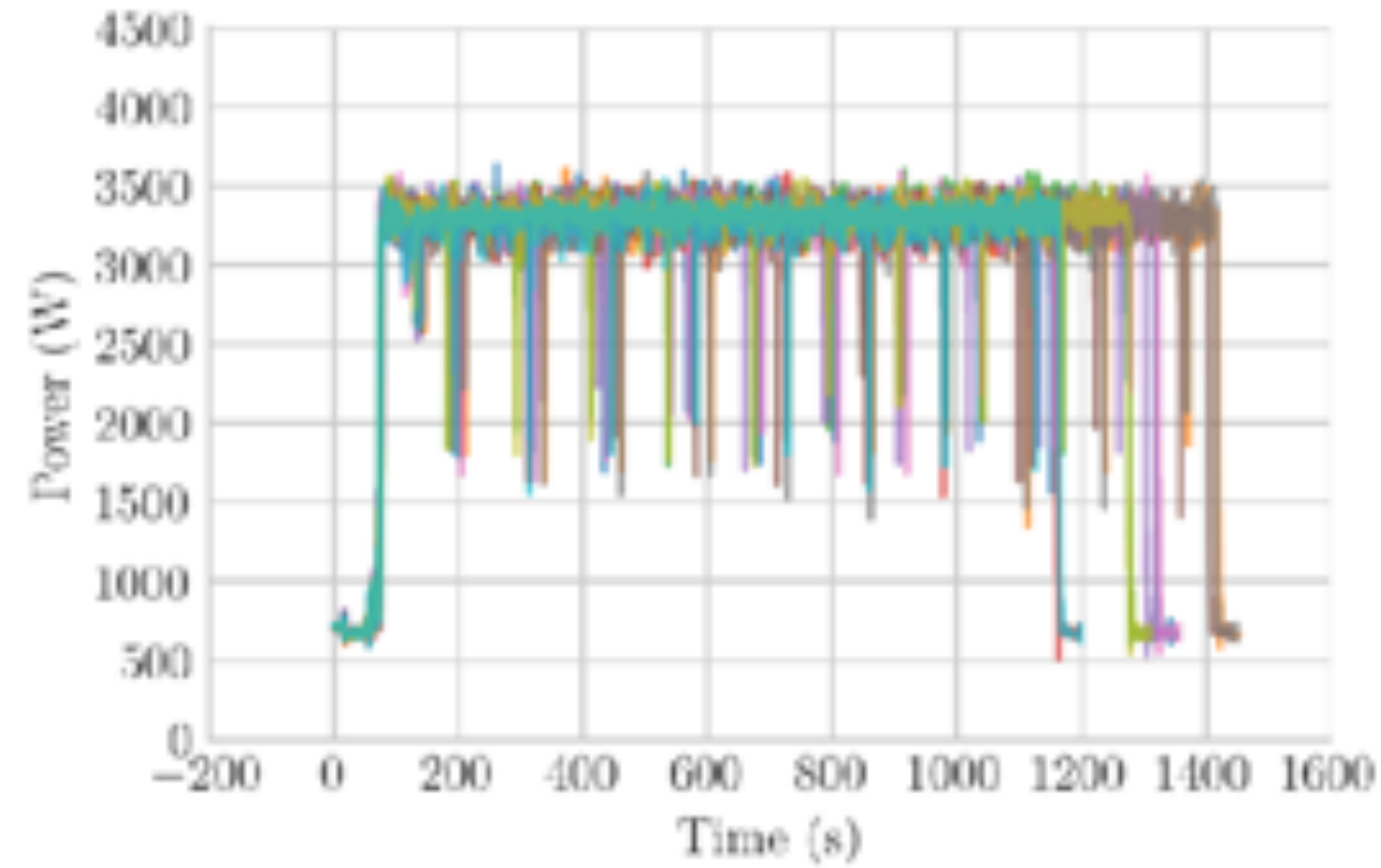
| | | |
|------------------------------|---------------------------------|--|
| Node model | Apollo 6500 Gen10 | Nvidia Jetson AGX Xavier |
| Number of nodes | 20 | 12 |
| GPU model | NVIDIA A100-SXM-80GB | NVIDIA GV10B, Volta architecture |
| Number of GPU per node | 8 | 1 |
| GPU TDP (W) | 400 | |
| CPU model | AMD EPYC 7763 64-Core Processor | Nvidia Carmel (Carmel), aarch64, 8 cores |
| Number of CPU per node | 2 | 1 |
| CPU TDP (W) | 280 | |
| Node TDP (W) | 3760 | 30 |
| Memory | 1 TB | 32 GB |
| Switch model | Mellanox HDR Infiniband | |
| Number of switch | 8 | |
| Switch power consumption (W) | 375 | |
| Installation year | 2022 | 2023 |
| Available thought | HPE local network - slurm | Grid'5000 Estats cluster - OAR |
| Power meter | HPE iLO 5 + RAPL + NVML | Jetson-stats |

Machine Learning Framework for Distributed Platforms

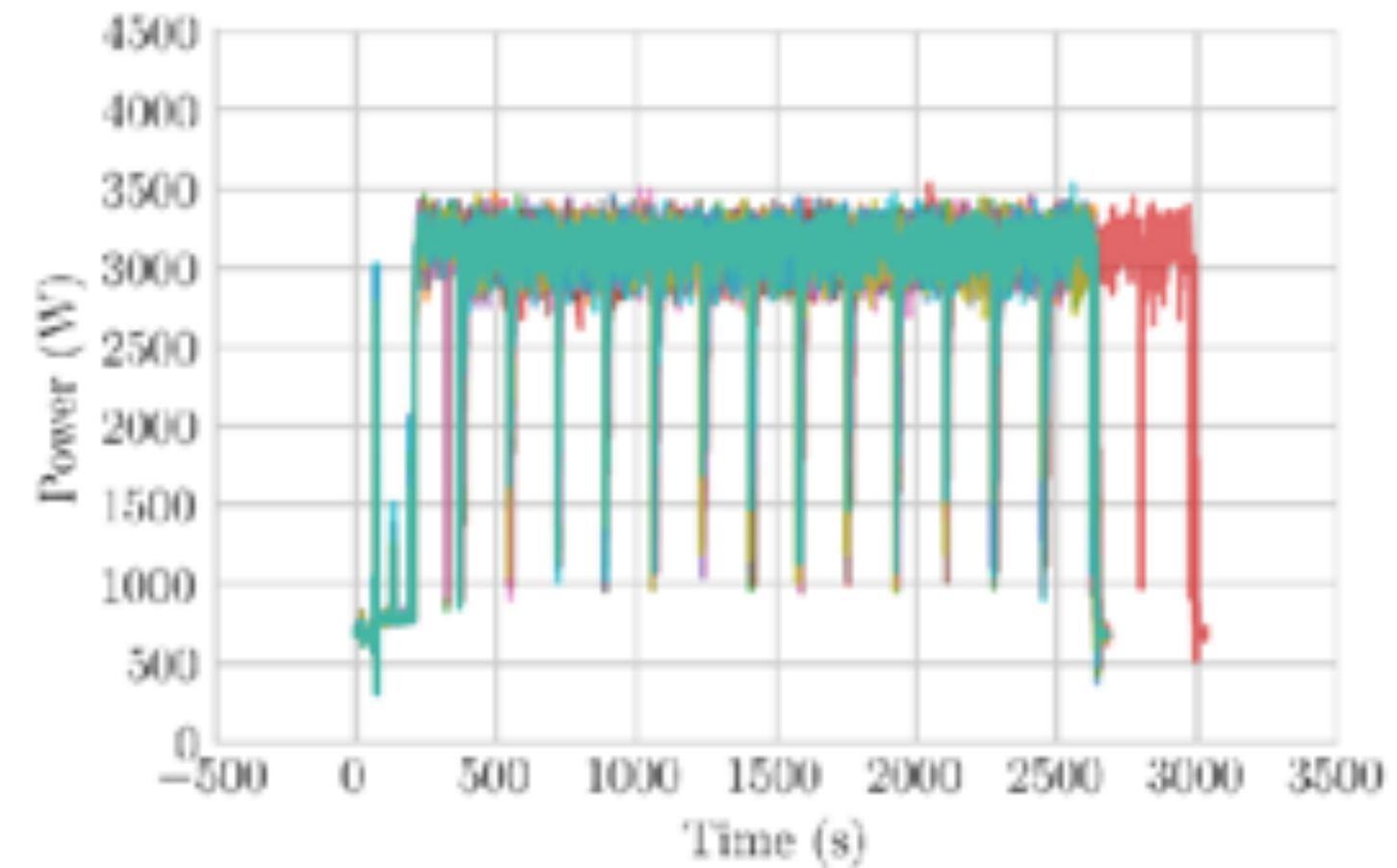
| Model | Apollo | Jetson |
|----------|-----------------|---------|
| UNet | MXNet / Horovod | |
| RNN-T | PyTorch | |
| ResNet | MXNet / Horovod | PyTorch |
| MaskRCNN | PyTorch | |
| BERT | PyTorch | |
| DLRM | HugeCTR | |

Power profile of each FU

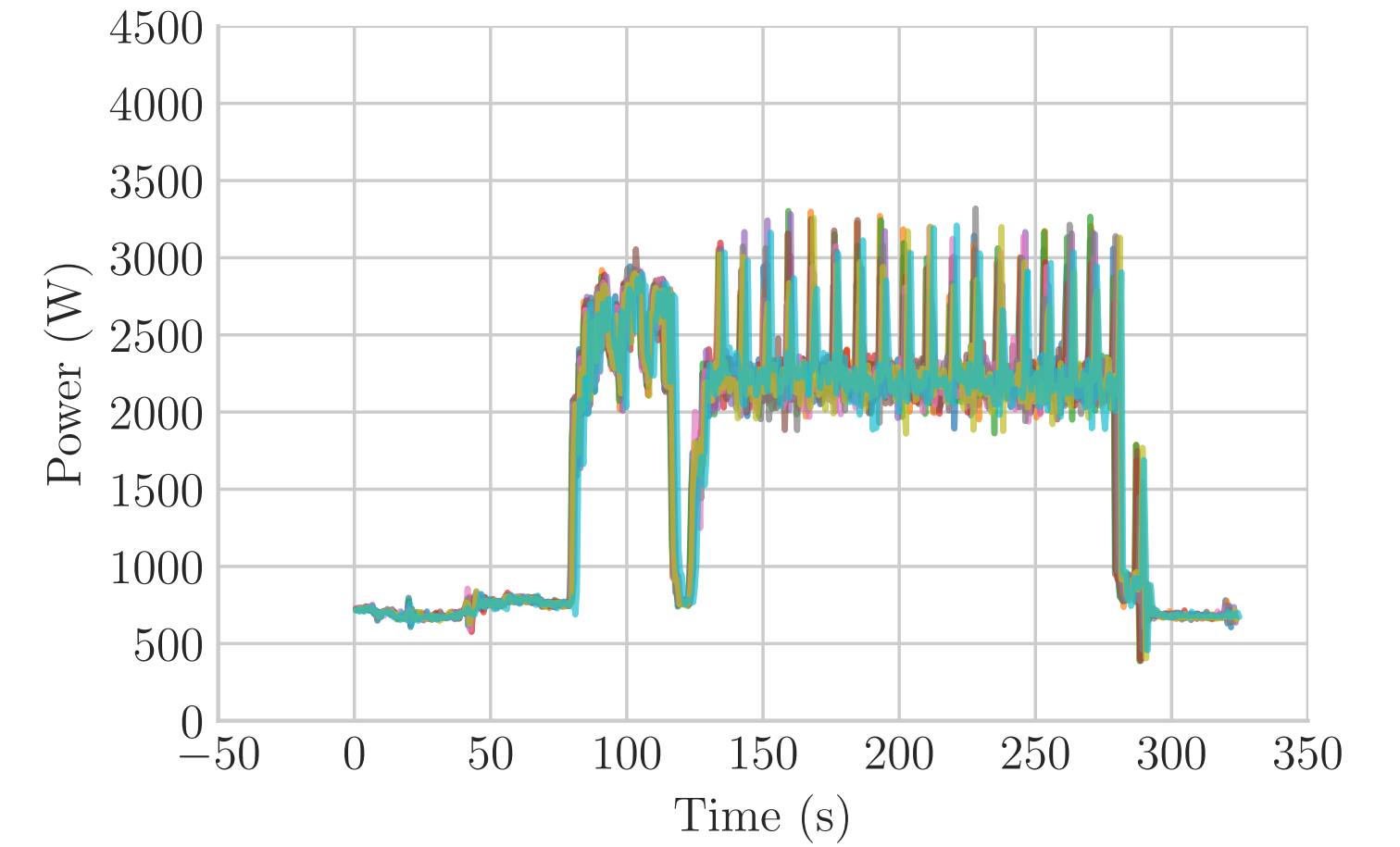
BERT FU



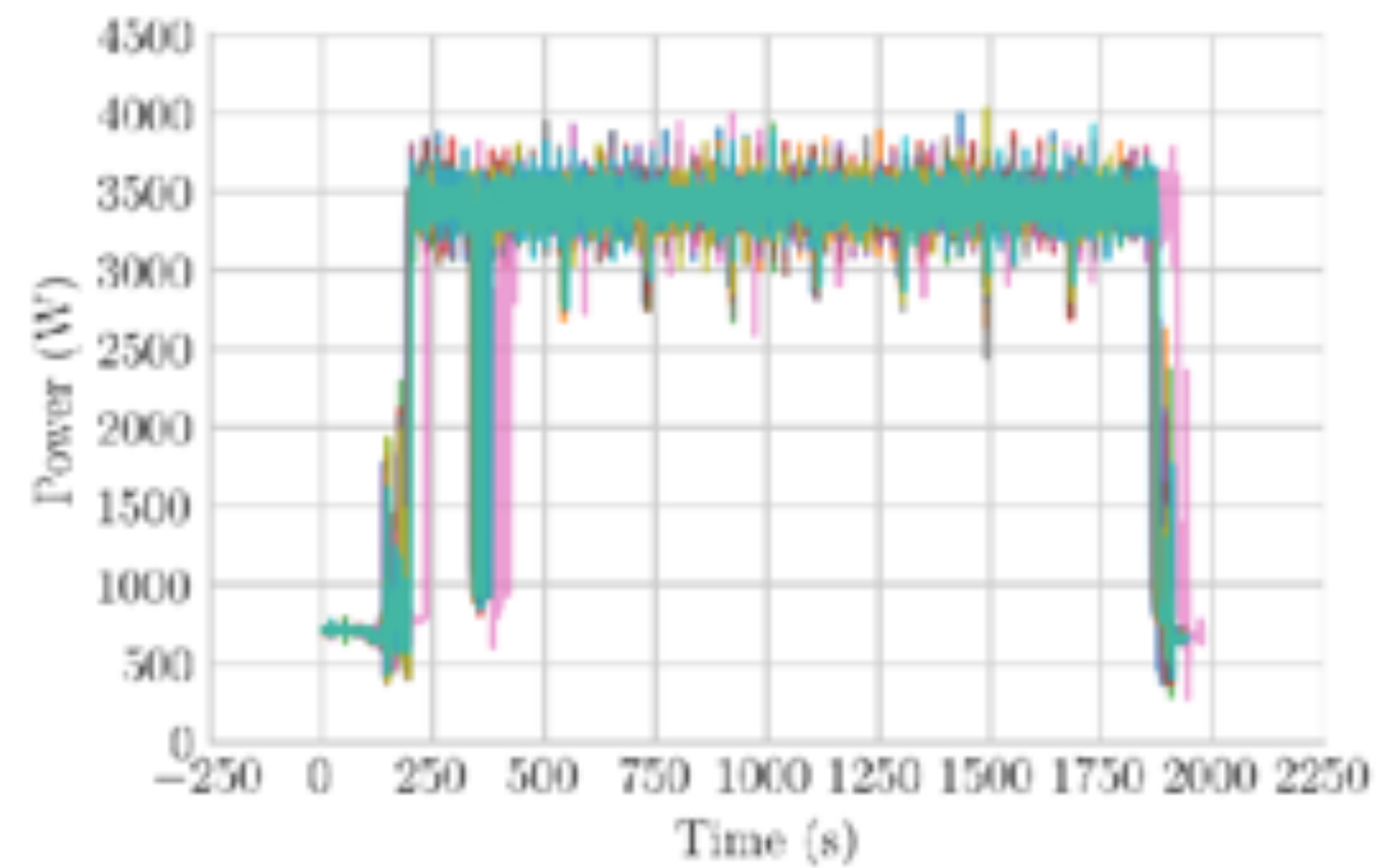
Mask R-CNN FU



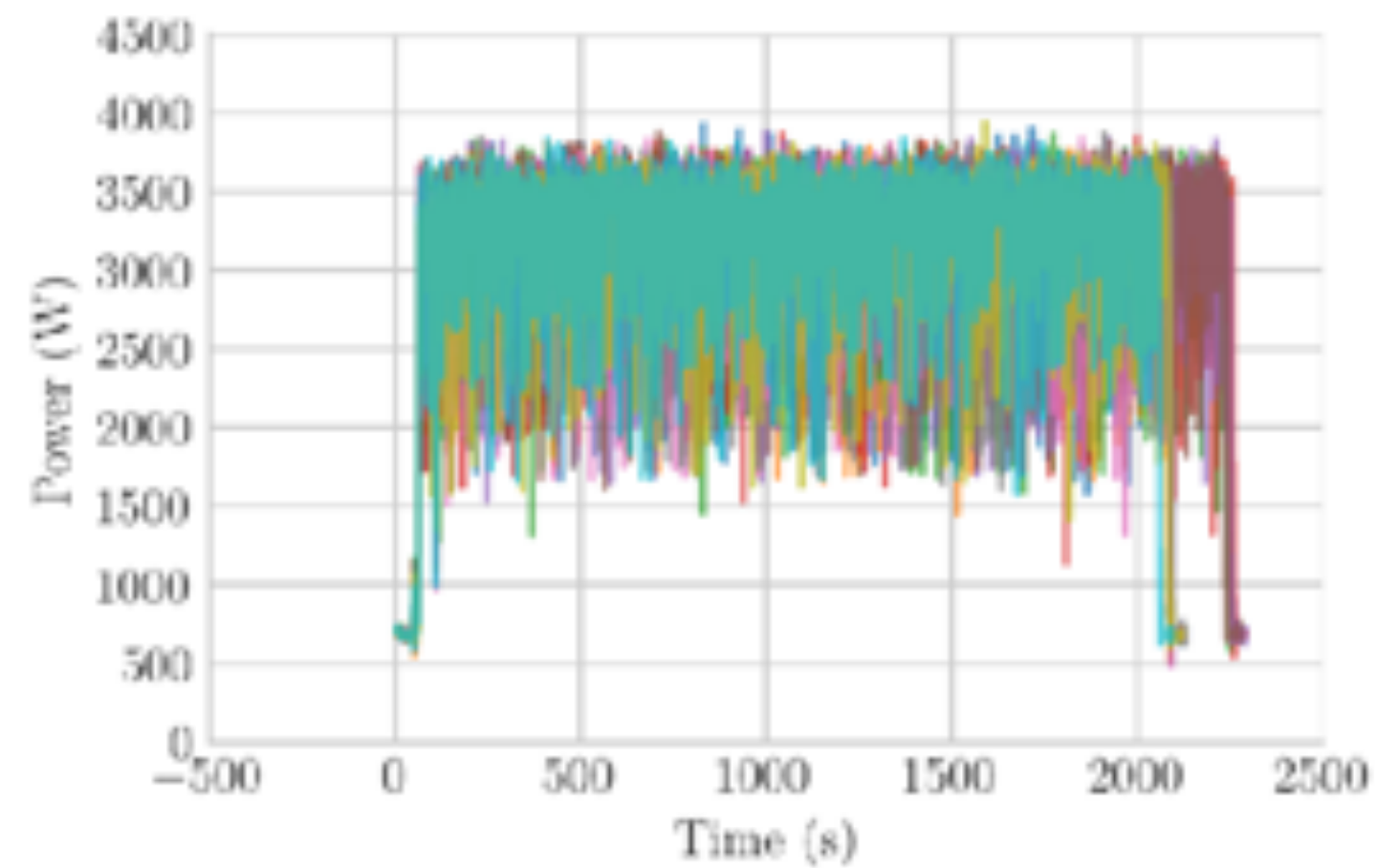
DLRM FU



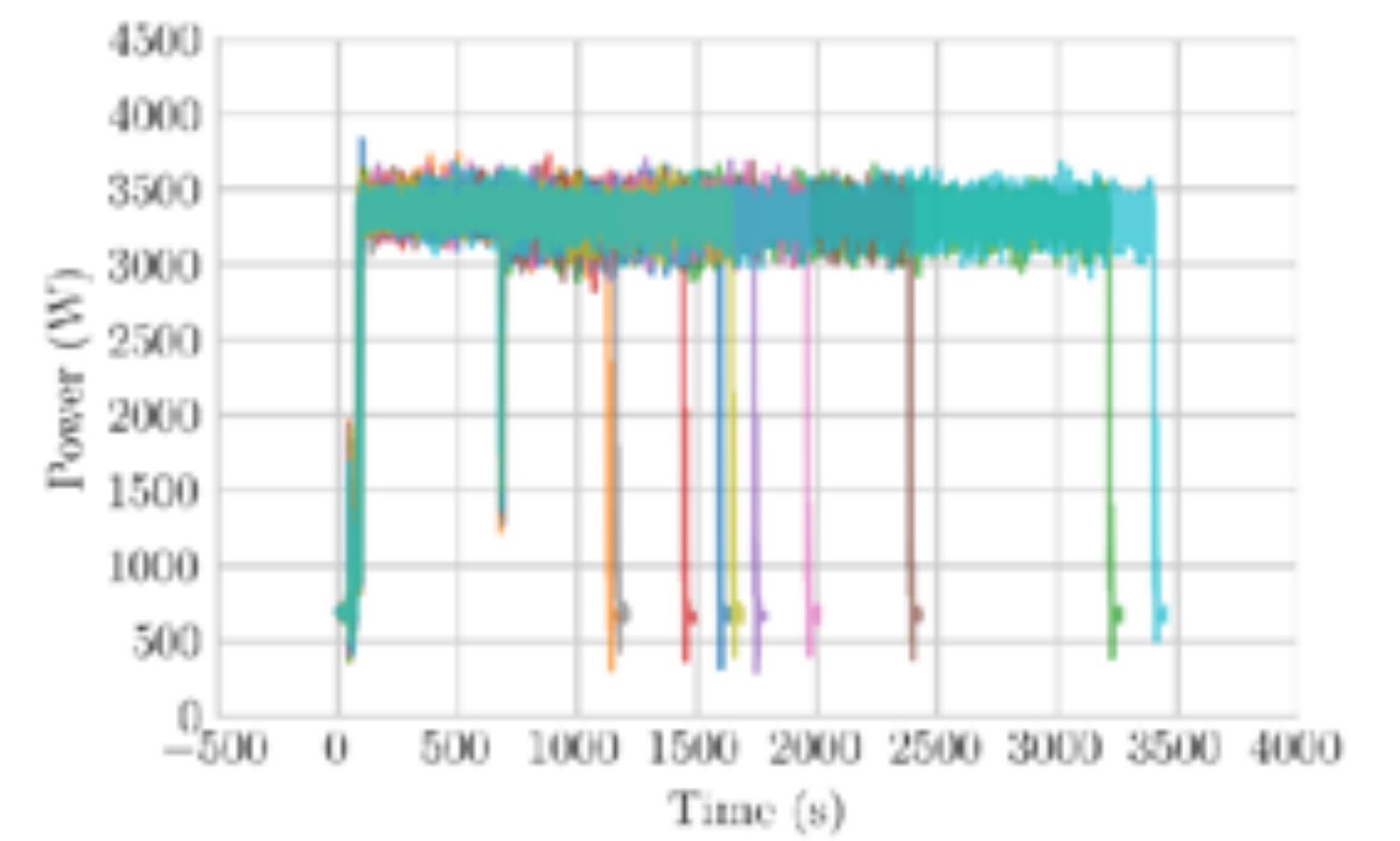
ResNet FU



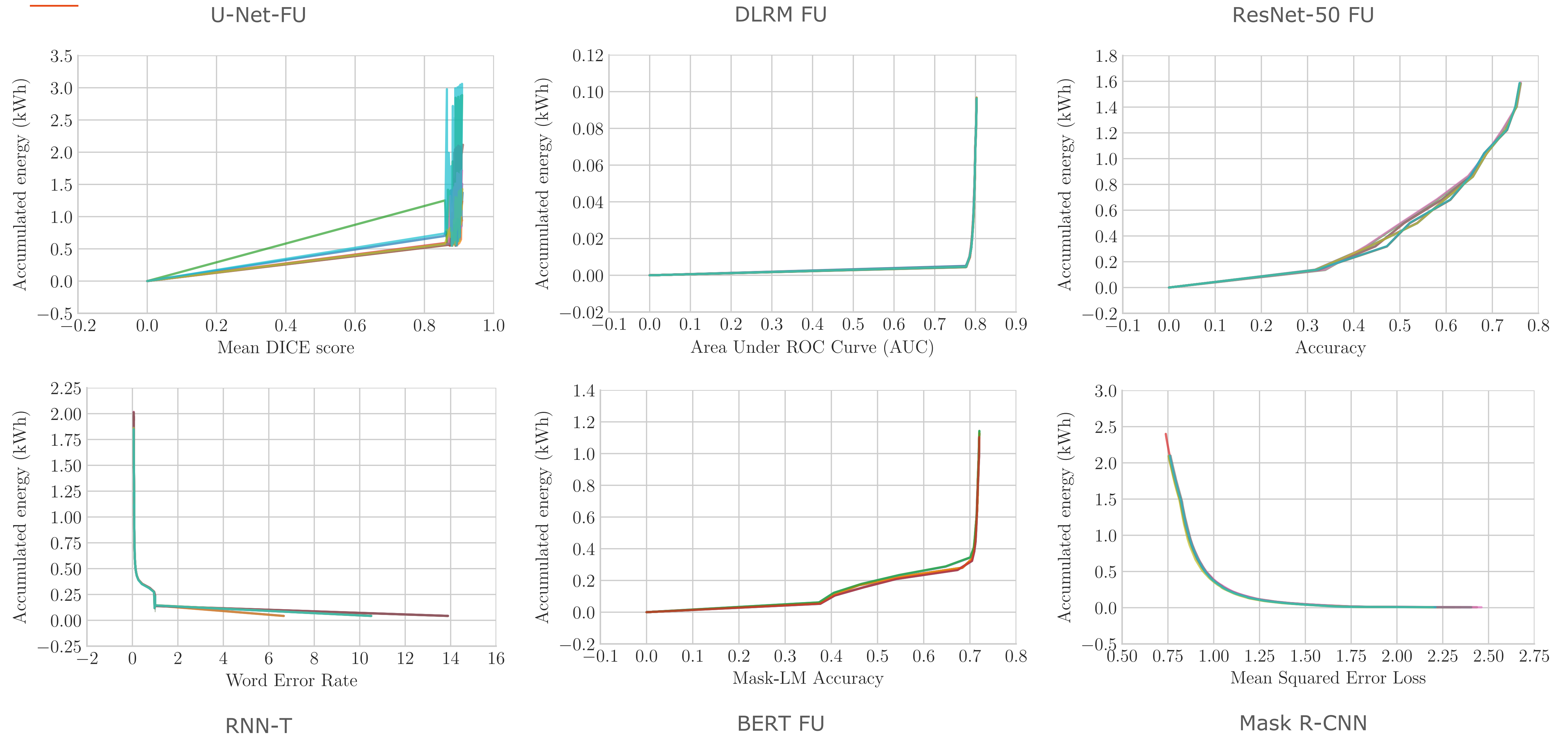
RNN-T FU



UNet FU



Accuracy/Energy tradeoff on Apollo

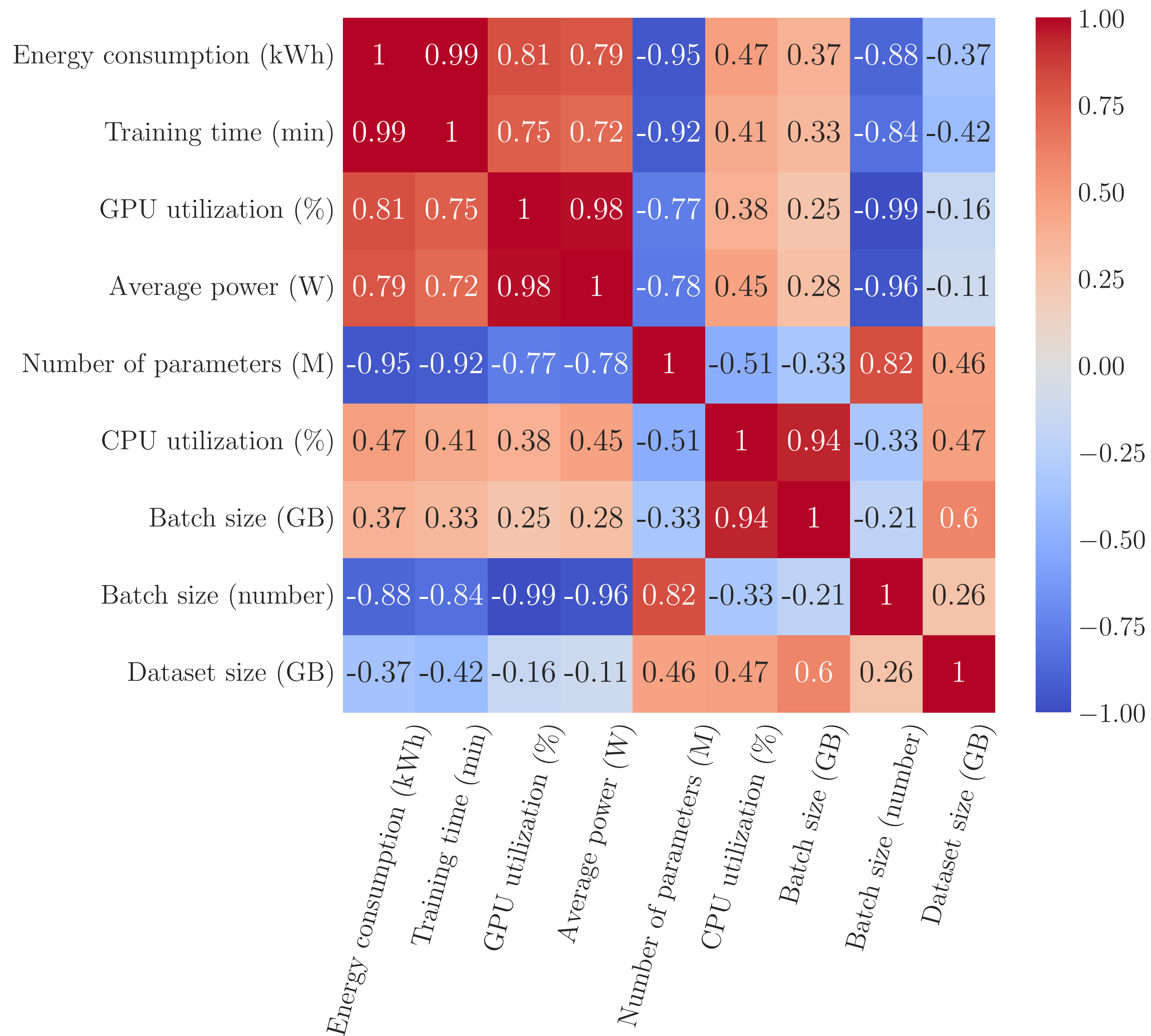


Performances of each FU

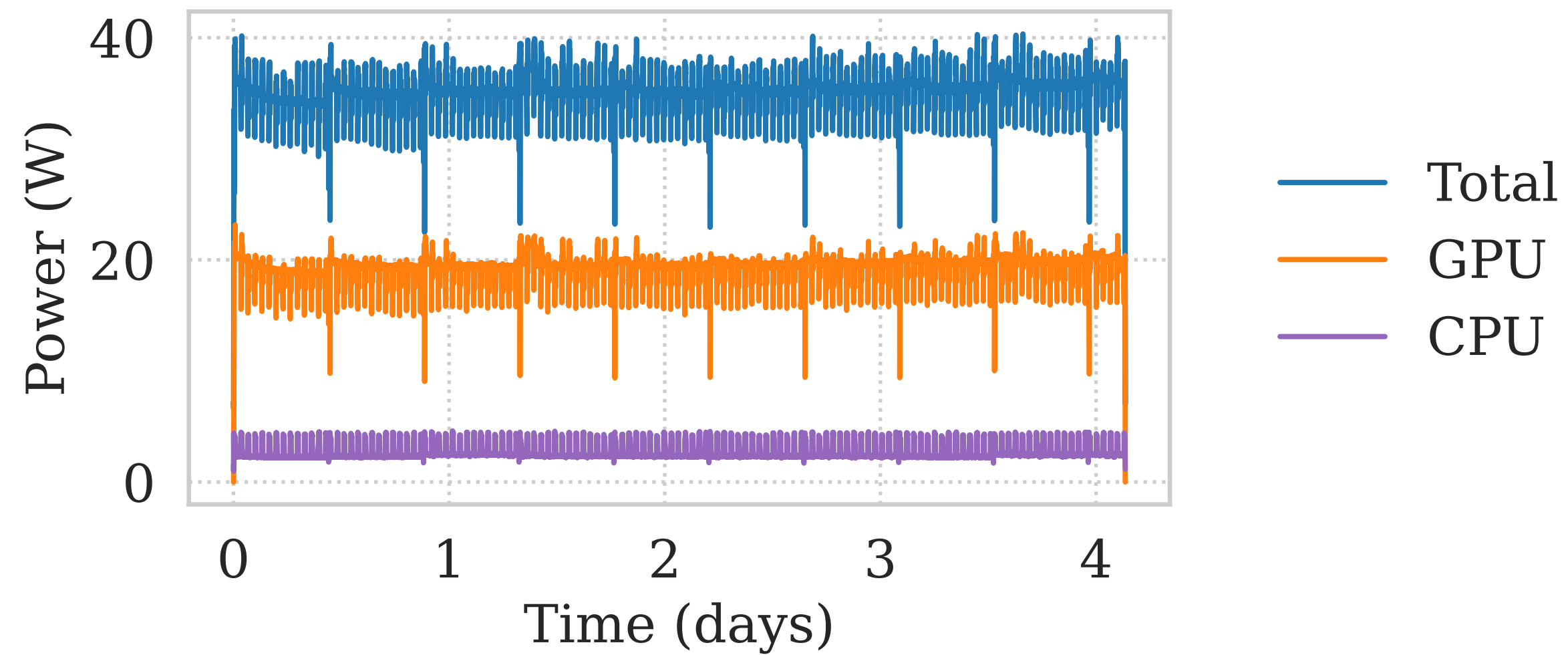
| FU | Energy (kWh) | Time (min) | Utilization (%) | |
|------------|-----------------|------------------|------------------|------------------|
| | | | GPU | CPU |
| ResNet-50 | 1.61 ± 0 | 29.42 ± 0.19 | 94.84 ± 0.71 | 28.57 ± 0.72 |
| 3D U-Net | 1.73 ± 0.7 | 31.72 ± 12.6 | 96.94 ± 0.89 | 8.2 ± 0.07 |
| Mask R-CNN | 2.16 ± 0.09 | 43.6 ± 1.69 | 89.87 ± 0.2 | 8.84 ± 0.02 |
| RNN-T | 1.97 ± 0.11 | 36.12 ± 2.21 | 95.46 ± 0.28 | 68.47 ± 0.89 |
| BERT-large | 1.13 ± 0.01 | 20.83 ± 0.25 | 96.88 ± 0.11 | 6.88 ± 0.01 |
| DLRM | 0.14 ± 0 | 4.18 ± 0.02 | 57 ± 0.46 | 5.36 ± 0.03 |

Characteristics of the MLPerf models and datasets

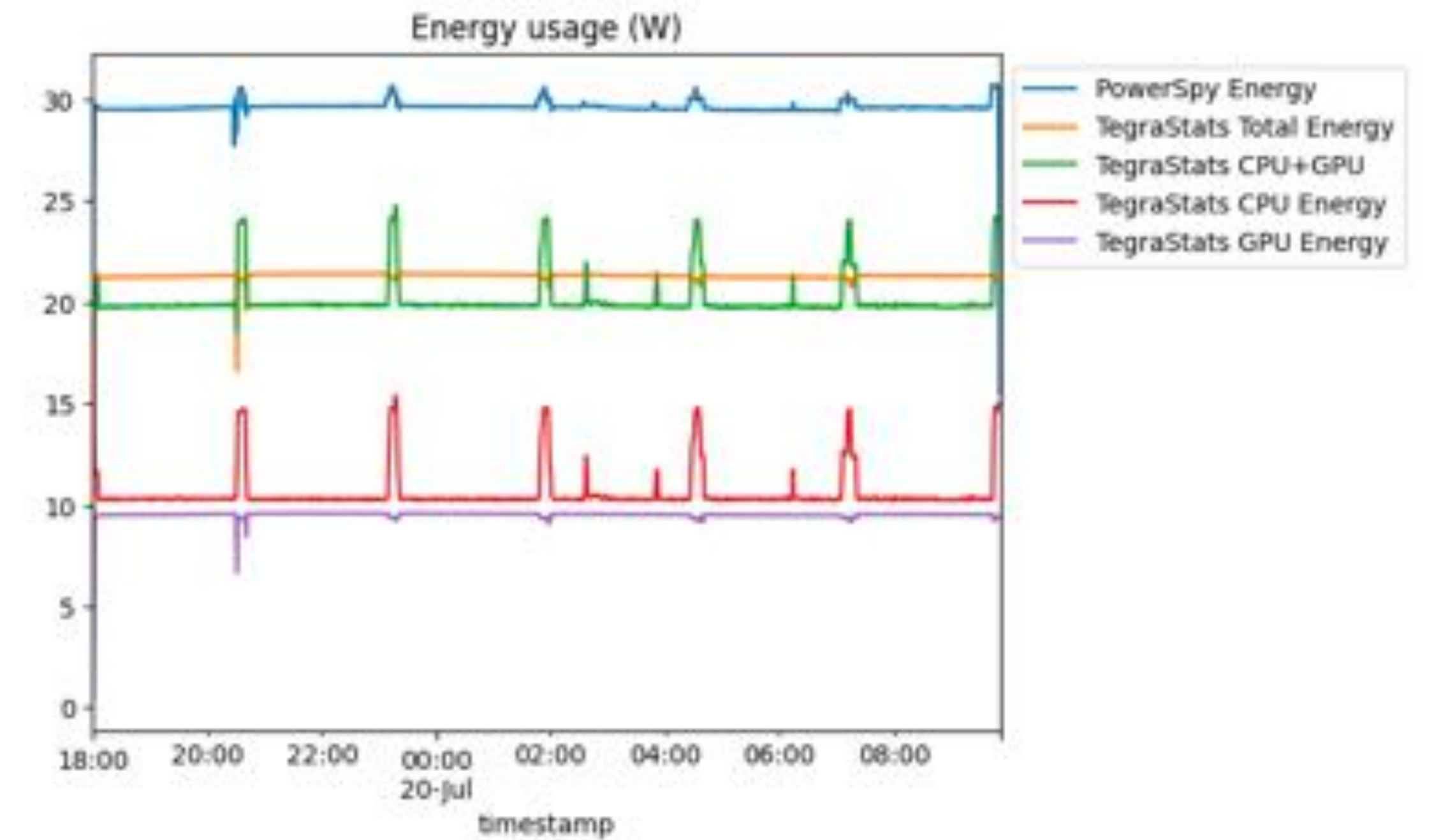
| Model | Parameter number (M) | Dataset size | | Batch size | |
|----------------|----------------------|--------------|-----|------------|-------|
| | | Sample | GB | Sample | In GB |
| ResNet-50 v1.5 | 25.6 | 1.28e+6 | 167 | 408 | 53 |
| 3D U-Net | 19 | 6.72e+4 | 40 | 56 | 229 |
| Mask R-CNN | 25.6 | 4.00e+4 | 20 | 96 | 48 |
| RNN-T | 29.8 | 2.78e+5 | 500 | 1536 | 2763 |
| BERT-large | 345 | 3.00e+6 | 400 | 384 | 51 |
| DLRM | 540 | 3.78e+9 | 342 | 55296 | 5 |



Jetson: Incoherence of electricity measurements

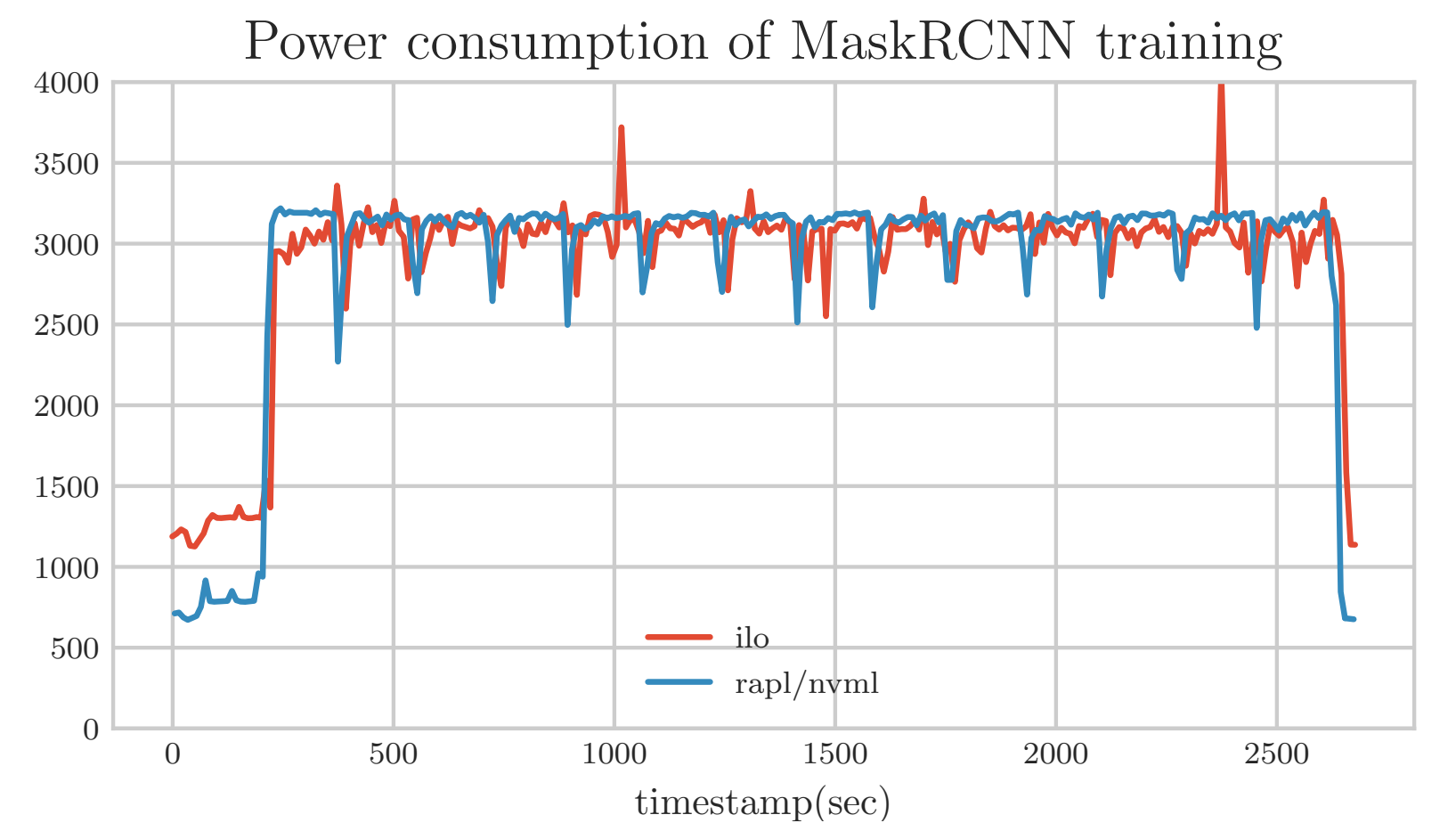
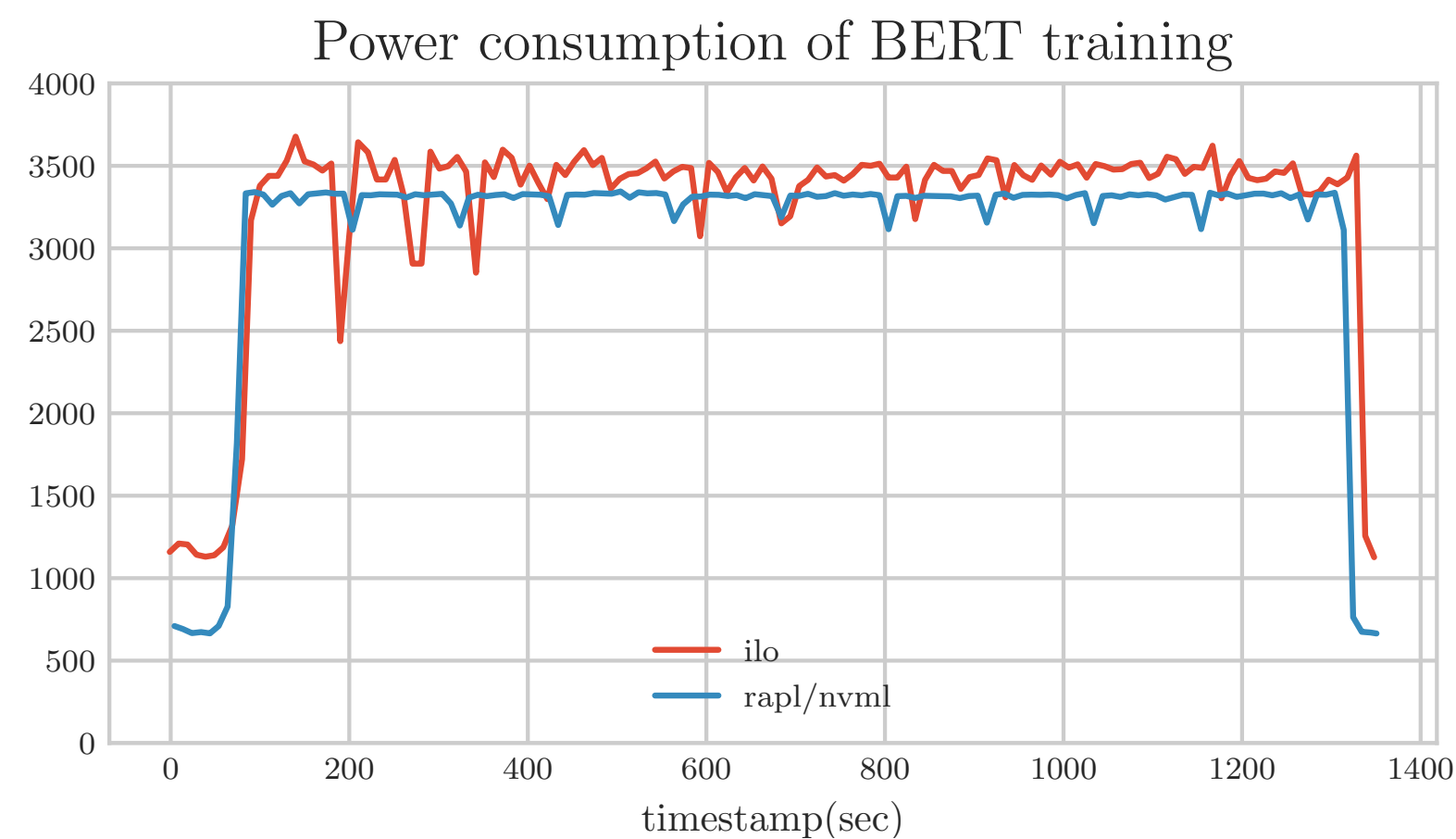
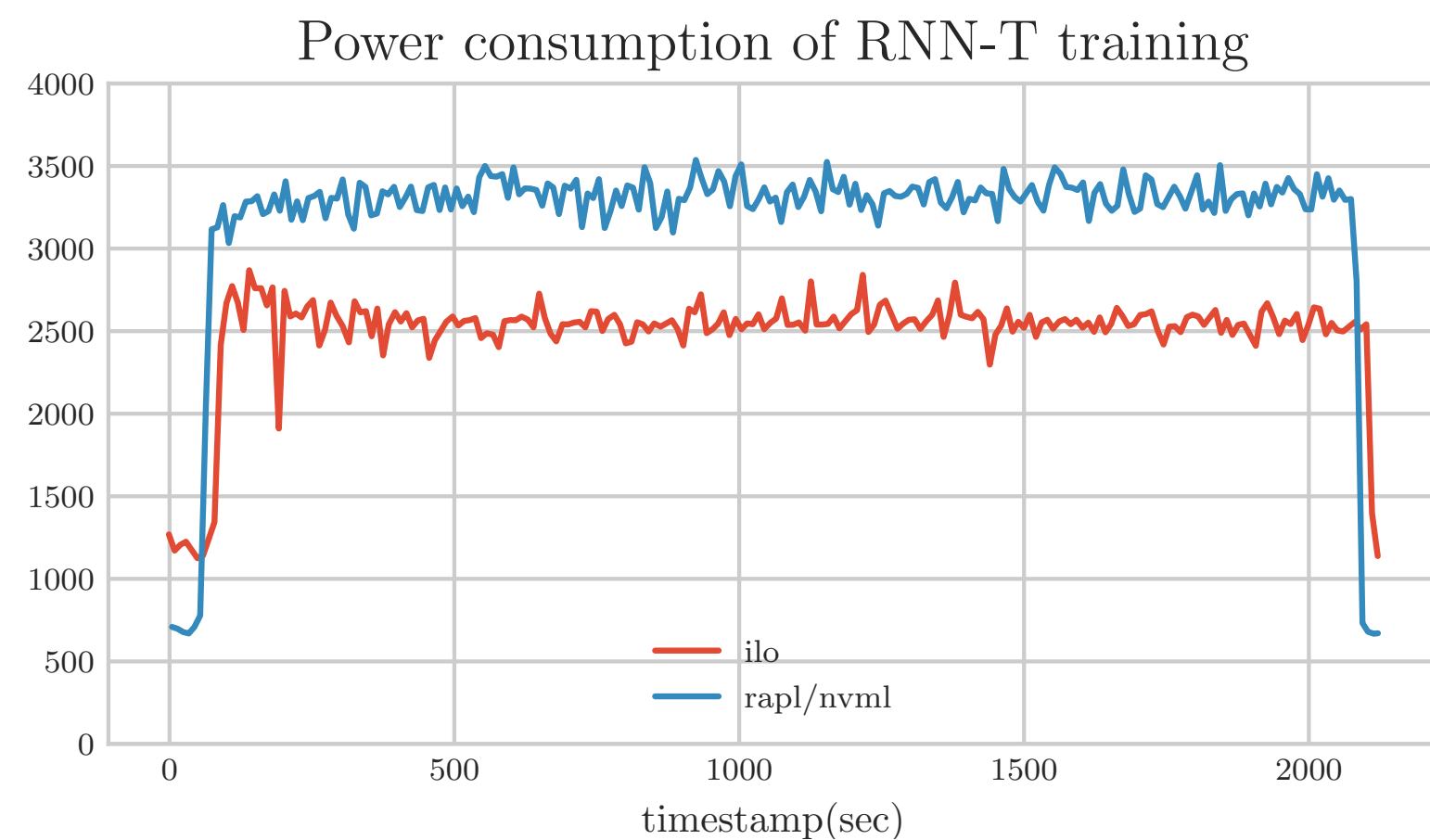
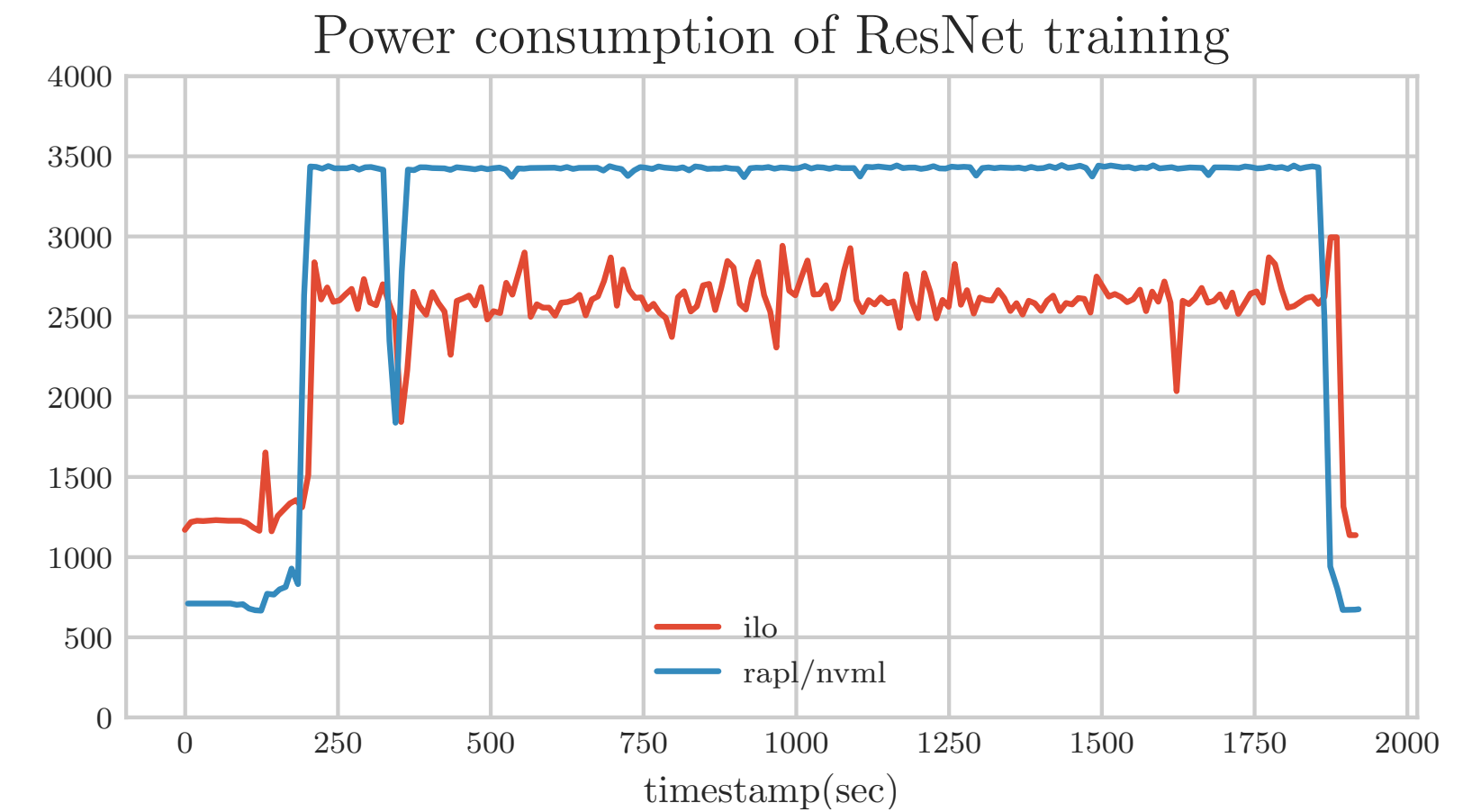
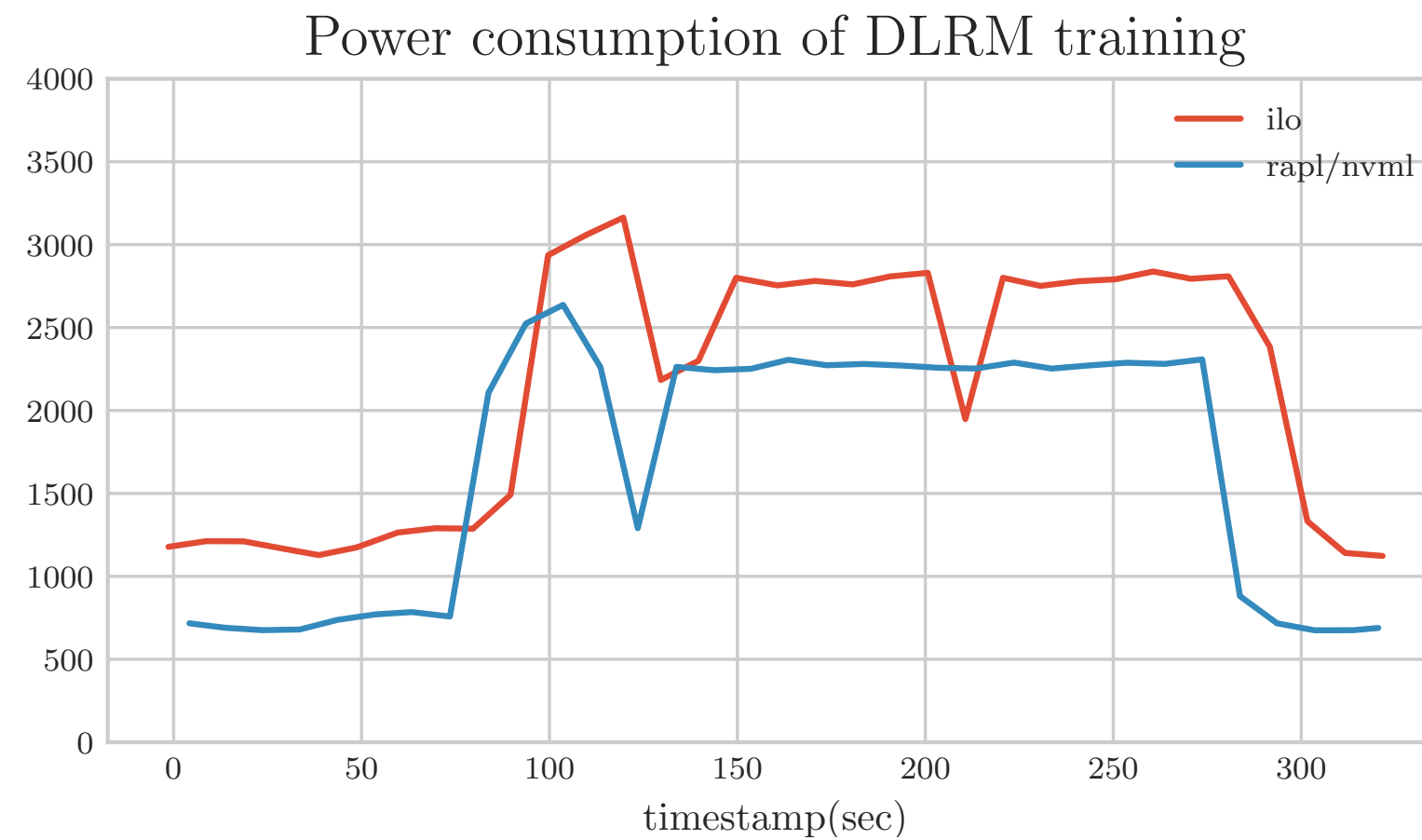
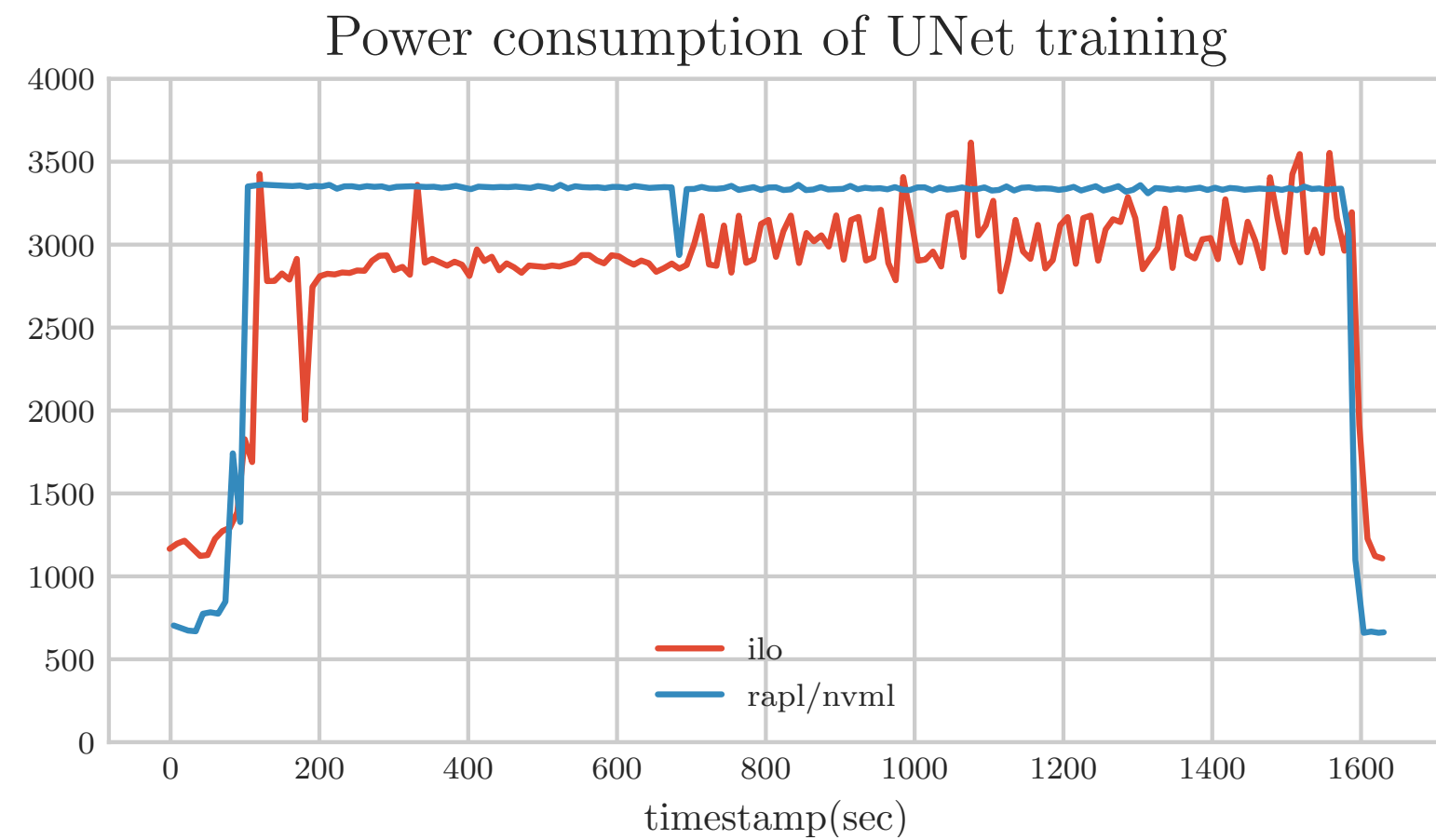


Power profile of ResNet-50 FU on Jetson.

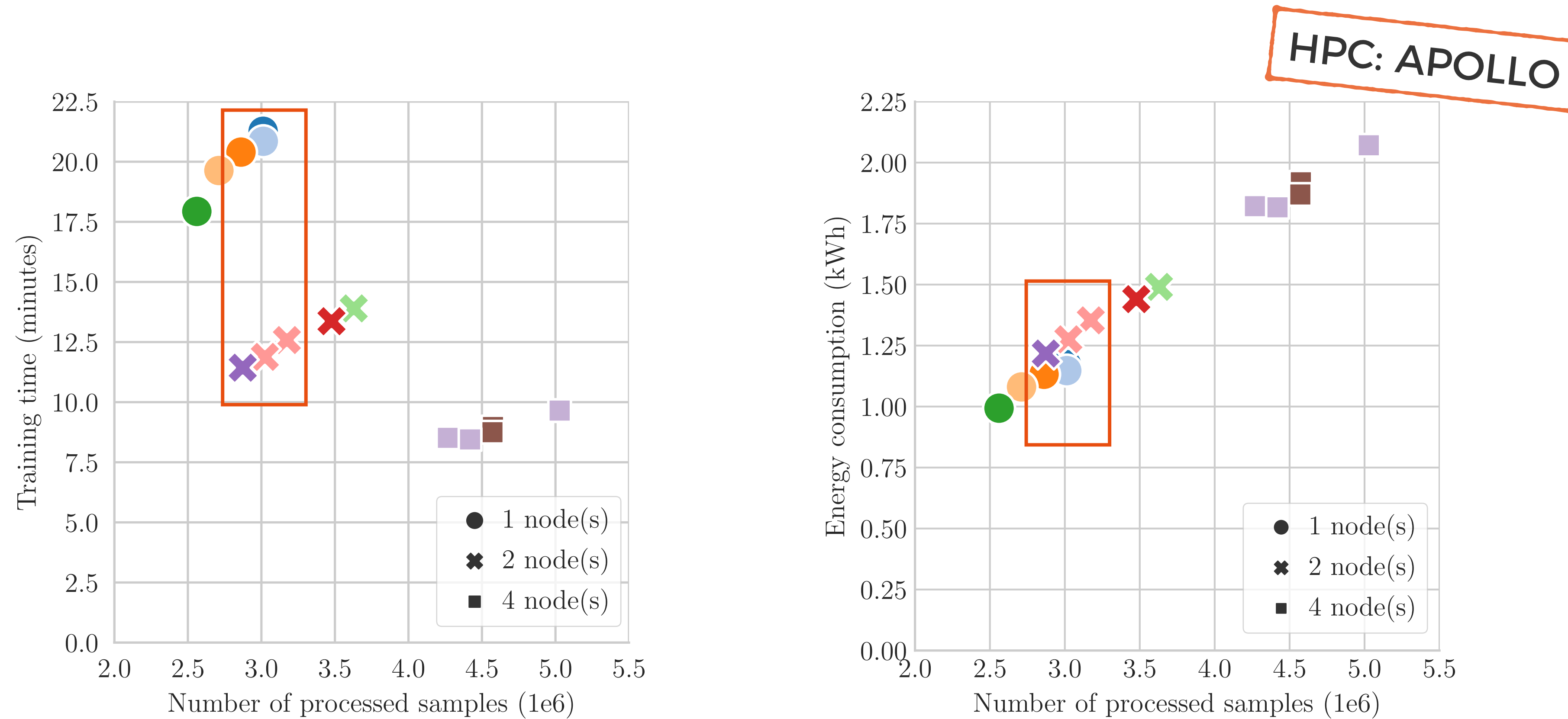


Comparing power meter and software-based power meter on Jetson (development kit, 16 Go)

Apollo: Incoherence of electricity measurements



Increasing the number of nodes can reduce the training time but can also increase the energy consumed



1 color = 1 set of nodes

Impact of sizing up the number of Apollo node of Champollion On the BERT FU

Embodied

Estimating the embodied impact

Of GPUs

Notations

| | |
|-----|---|
| I | : Environmental Impact (expressed in kg CO2 eq, kg Seb, and MJ) |
| s | : Surface or area (of the GPU die or of the board) |
| c | : Memory capacity |
| d | : Memory density |
| w | : Node weight |



$$I_{compute}(s_{die}) = s_{die} * I_{compute,manufacturing} + I_{compute,transport}$$

$$I_{memory}(c, d) = \frac{c}{d} * I_{memory,manufacturing} + I_{memory,transport}$$

$$I_{board}(s_{PCB}) = s_{PCB} * I_{board}$$

$$I_{GPU, capex} =$$

$$I_{compute}(s_{die}) + I_{memory}(c, d) + I_{board}(s_{PCB}) + I_{HeatSink} + I_{PCIConnector}$$

Estimating the embodied impact

Notations

I : Environmental Impact (expressed in kg CO2 eq, kg Seb, and MJ)

s : Surface or area (of the GPU die or of the board)

c : Memory capacity

d : Memory density

w : Node weight

Of the CPUs & RAM: Directly from database



Of other components:

$$I_{case} = \frac{w}{\bar{w}} * \bar{I}_{case}$$

Estimating the impacts of the electricity consumption

$$I_{training,opex} = PUE * IF_{elec} * E_{training}$$

Notations

I : Environmental Impact (expressed in kg CO2 eq, kg Seb, and MJ)

I_{capex} : Embodied Impact (manufacture, transport, and end of life)

I_{opex} : Operational Impact (usage)

IF_{elec} : Electricity mix Impact Factor

E : Electricity consumption

AUR : Active Utilization Rate

PUE : Power Usage Effectiveness of the data center

In this presentation, PUE = 1

Allocation on the ResNet-50 FU

Notations

I : Environmental Impact (expressed in kg CO2 eq, kg Seb, and MJ)

I_{capex} : Embodied Impact (manufacture, transport, and end of life)

I_{opex} : Operational Impact (usage)

AUR : Active Utilization Rate

T : Use time of the equipment

$$I_{training, capex} = \frac{T_{training}}{AUR * T_{lifetime}} * (I_{GPU, capex} + I_{CPU, capex} + I_{RAM, capex} + I_{Other, capex})$$

Hypothesis

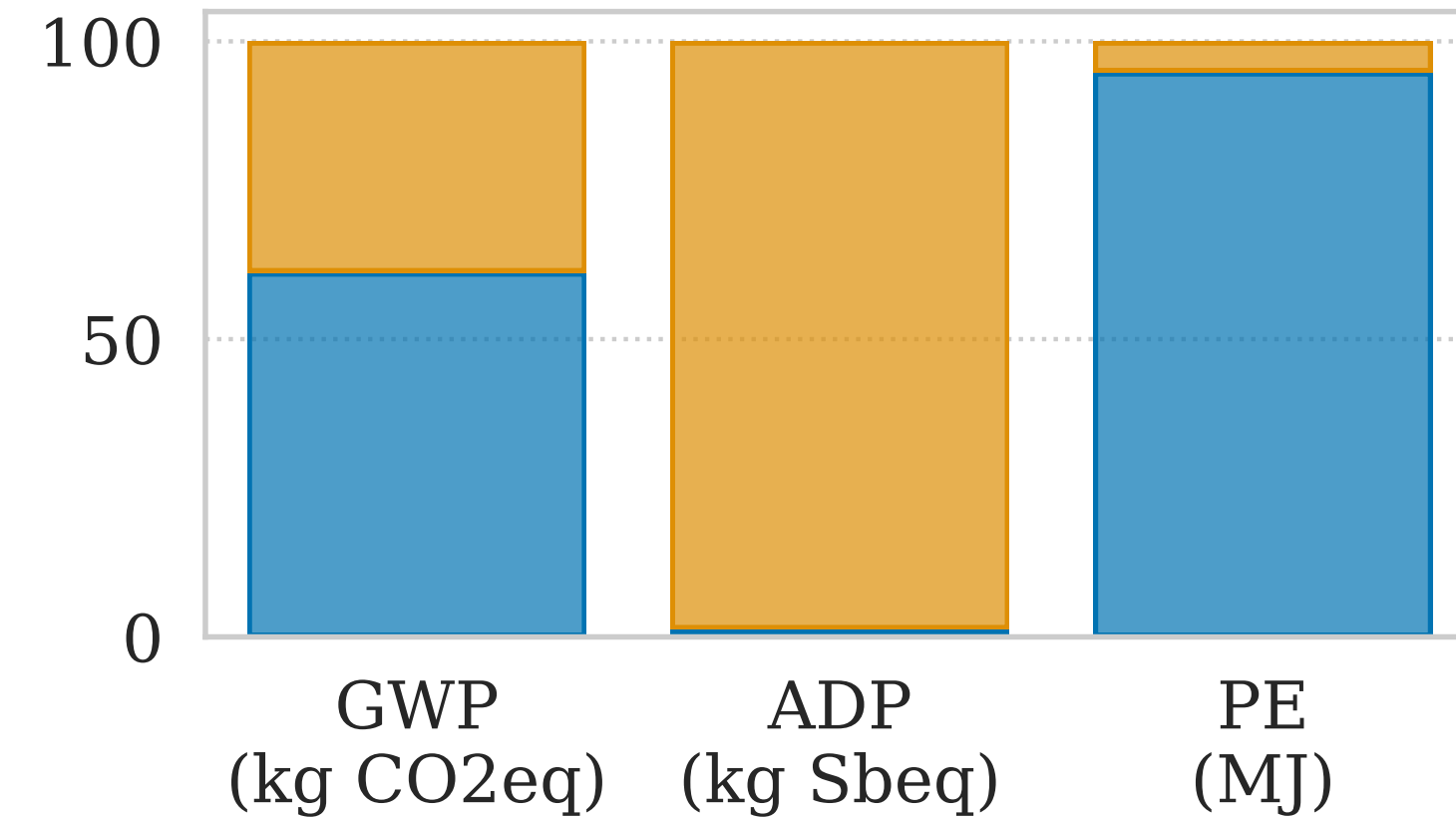
- AUR = Active Utilization Rate : 50%
- Lifetime : 4 years

Total

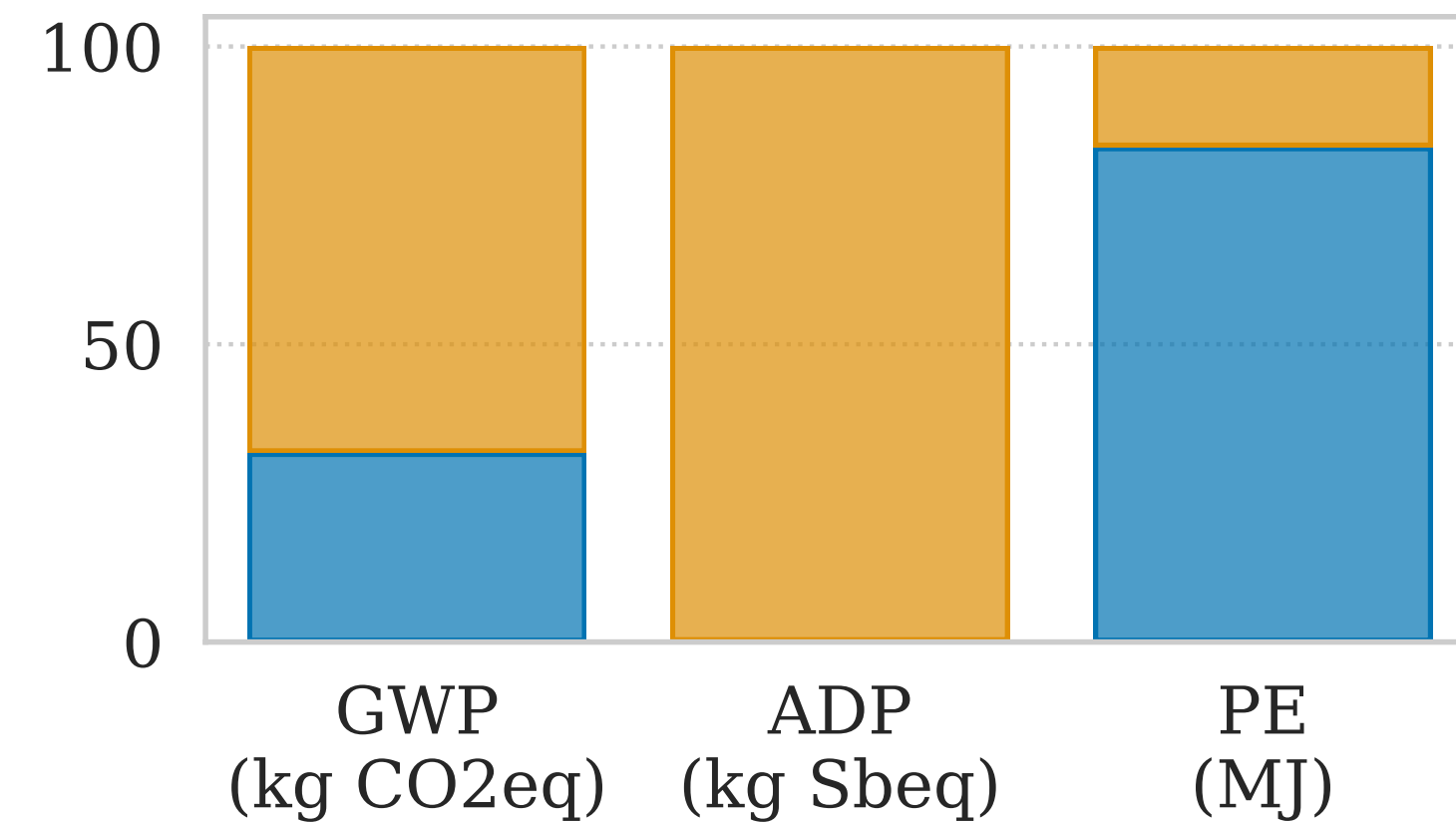
Allocation on the ResNet-50 and ResNet-50* FU

| | Usage | Embodied |
|----------------|----------|----------|
| GWP (kg CO2eq) | 1.31E-01 | 8.30E-02 |
| ADP (kg Sbeq) | 7.80E-08 | 6.00E-06 |
| PE (MJ) | 1.96E+01 | 1.07E+00 |

| | Usage | Embodied |
|----------------|----------|----------|
| GWP (kg CO2eq) | 1.60E-01 | 3.43E-01 |
| ADP (kg Sbeq) | 9.59E-08 | 1.07E-04 |
| PE (MJ) | 2.41E+01 | 4.89E+00 |



HPC: APOLLO



EDGE: JETSON

Share of usage and embodied phase in the total impacts of the ResNet-50 * FU on the **Jetson** node

FU impacts on Apollo

| | | | | | | |
|----------------|----------|----------|----------|----------|----------|----------|
| GWP (kg CO2eq) | 2.14E-01 | 2.30E-01 | 2.98E-01 | 2.62E-01 | 1.51E-01 | 2.28E-02 |
| ADP (kg Sbeq) | 6.08E-06 | 6.55E-06 | 9.00E-06 | 7.47E-06 | 4.30E-06 | 8.59E-07 |
| PE (MJ) | 2.07E+01 | 2.22E+01 | 2.79E+01 | 2.54E+01 | 1.46E+01 | 1.81E+00 |

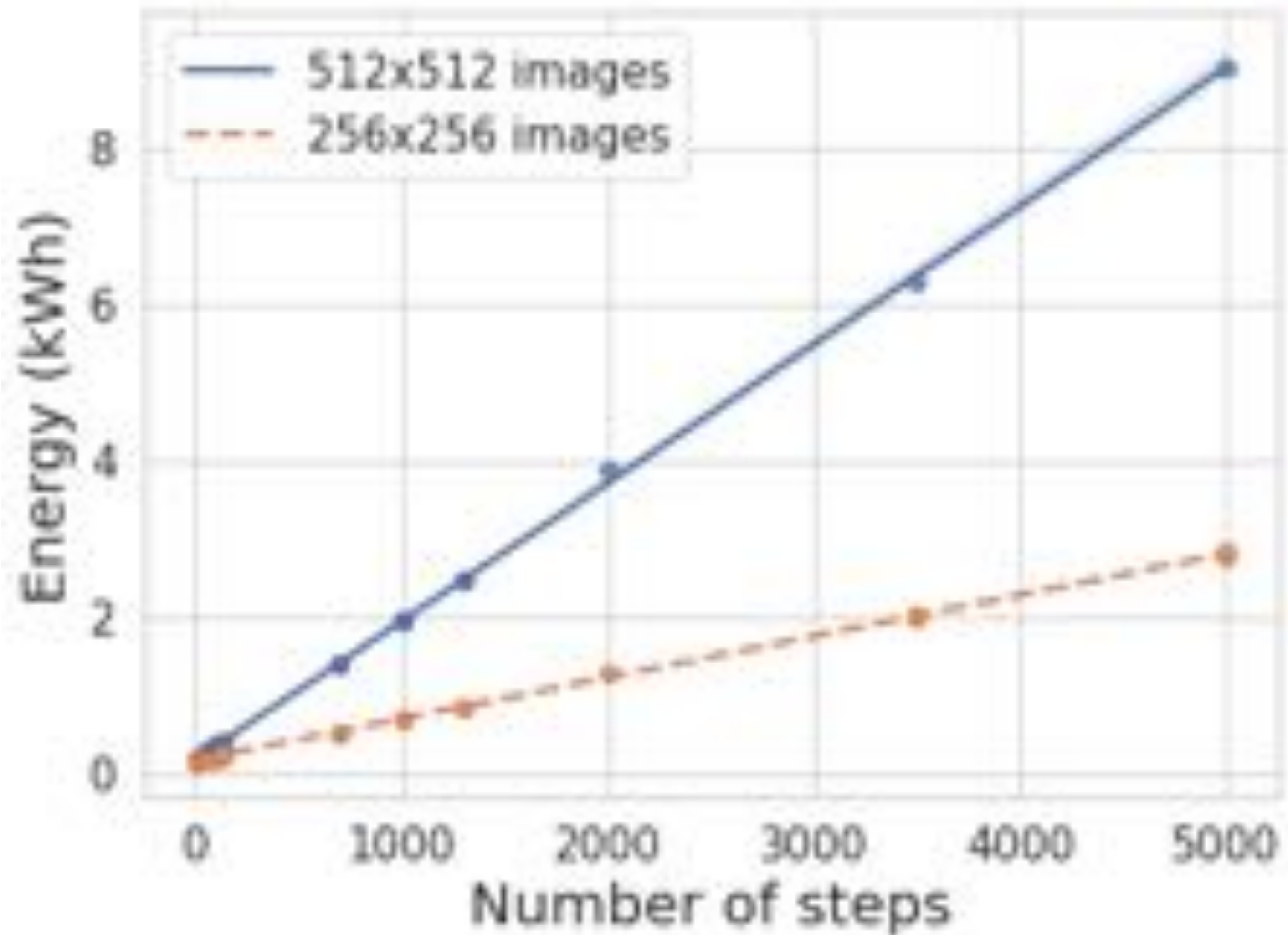
Summary of ResNet-50 and ResNet-50* FU performances

| | Jetson (ResNet-50*) | Apollo (ResNet-50) | Apollo (ResNet-50*) | Min | Max |
|---------------------|---------------------|--------------------|---------------------|-------|-----|
| Electricity c (kWh) | 1.974036108 | 1.605368 | 0.5723368444 | 3 | 0 |
| Duration (hours) | 88.86541726 | 0.4903240667 | 0.1876559211 | 100 | 0 |
| Accuracy | 0.55 | 0.759 | 0.55 | 0 | 1 |
| GWP (kg CO2eq) | 5.03E-01 | 2.14E-01 | 7.83E-02 | 0.70 | 0 |
| ADP (kg Sbeq) | 1.07E-04 | 6.08E-06 | 2.33E-06 | 0.00 | 0 |
| PE (MJ) | 2.90E+01 | 2.07E+01 | 7.39E+00 | 50.00 | 0 |
| Personnalisation | 0.9 | 0.3 | 0.3 | 0 | 1 |
| Latency | 0.9 | 0 | 0 | 0 | 1 |
| Price | 1 | 0.001 | 0.001 | 0 | 1 |
| Accessibility | 0.7 | 0.1 | 0.1 | 0 | 1 |

Stable Diffusion

| Cluster | Champollion | Estats | Gemini | Sirius |
|------------------------------|---------------------------------|--|---|-------------------------------------|
| Node model | Apollo 6500 Gen10 | Nvidia Jetson AGX Xavier | Nvidia DGX-1 | Nvidia DGX A100 |
| Number of nodes | 20 | 12 | 2 | 1 |
| GPU model | NVIDIA A100-SXM-80GB | NVIDIA GV10B, Volta architecture | Nvidia Tesla V100-SXM2-32GB | Nvidia A100-SXM4-40GB |
| Number of GPU per node | 8 | 1 | 8 | 8 |
| GPU TDP (W) | 400 | | 400 | 280 |
| CPU model | AMD EPYC 7763 64-Core Processor | Nvidia Carmel (Carmel), aarch64, 8 cores | Intel Xeon E5-2698 v4 (Broadwell, 64 cores/CPU) | AMD EPYC 7742 (Zen 2, 64 cores/CPU) |
| Number of CPU per node | 2 | 1 | 2 | 2 |
| CPU TDP (W) | 280 | | 135 | 225 |
| Memory | 1 TB | 32 GB | 1 TB | 512 GiB |
| Switch model | Mellanox HDR Infiniband | | | |
| Number of switch | 8 | | | |
| Switch power consumption (W) | 375 | | | |
| Installation year | 2022 | 2023 | 2019 | 2021 |
| Available thought | HPE local network - slurm | Grid'5000 - OAR | Grid'5000 - OAR | Grid'5000 - OAR |
| Power meter | HPE iLO 5 + RAPL + NVML | Jetson-stats | RAPL/NVML + OmegaWatt+ BMC | RAPL/NVML + OmegaWatt+ BMC |

Linear regression from smaller number of steps



Estimation the electricity consumption of training Stable Diffusion

For 256x256 images

$$\text{Energy (kWh)} = 5.26e^{-04} \times N + 2.01e^{-02}$$

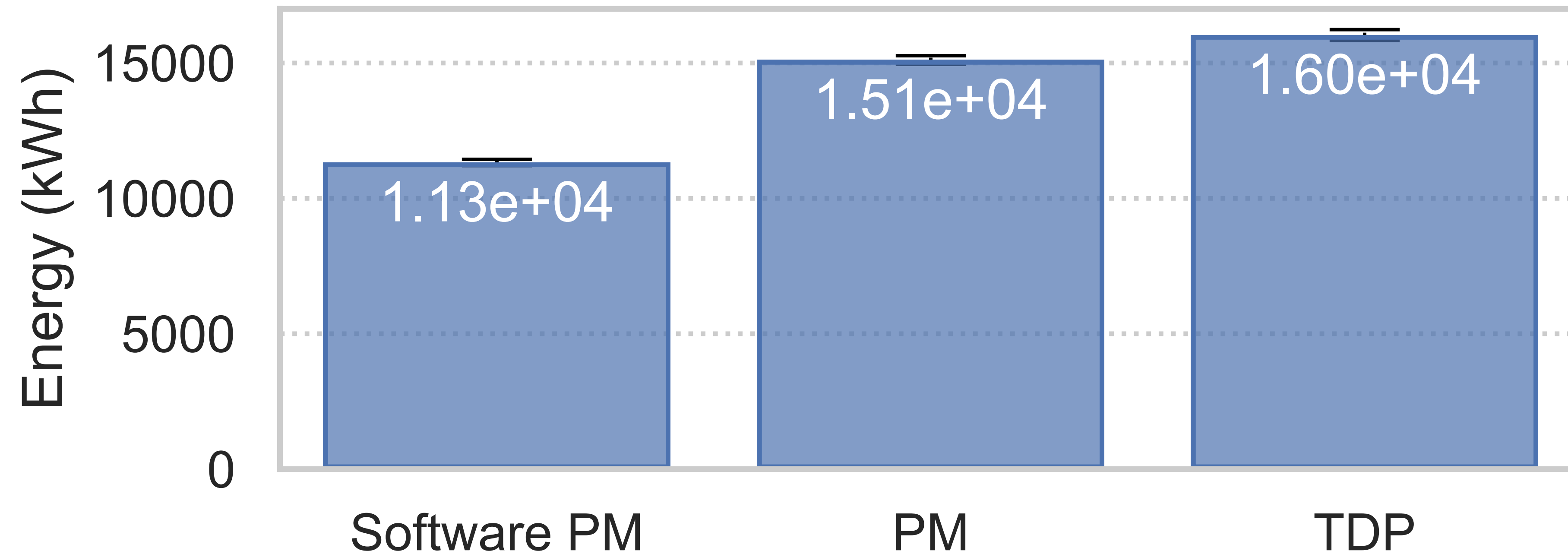
For 512x512 images

$$\text{Energy (kWh)} = 1.78e^{-03} \times N + 1.64e^{-02}$$

Where N is the number of training steps.

| Version | Image size | # steps | Estimated energy (kWh) | |
|---------|------------|---------------|------------------------|---------------|
| | | | 1 node | 32 nodes |
| v1-1 | 256 | $2.37e^{+05}$ | $4.70e^{+02}$ | $1.50e^{+04}$ |
| | 512 | $1.94e^{+03}$ | | |
| v1-4 | 512 | $2.25e^{+05}$ | $4.01e^{+02}$ | $1.28e^{+04}$ |
| v1-5 | 512 | $5.95e^{+05}$ | $1.06e^{+03}$ | $3.39e^{+04}$ |

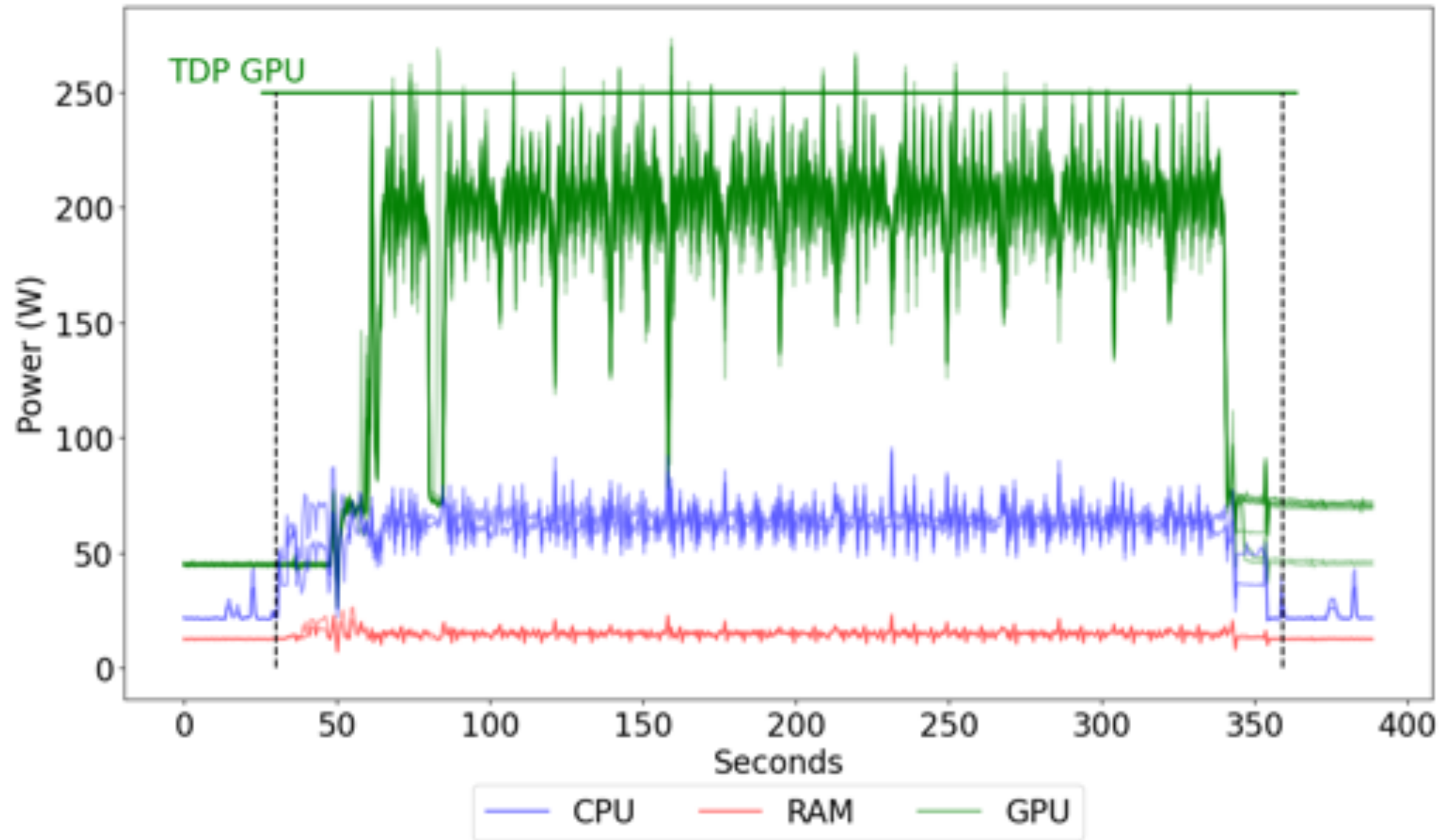
Impact of the energy measurement method



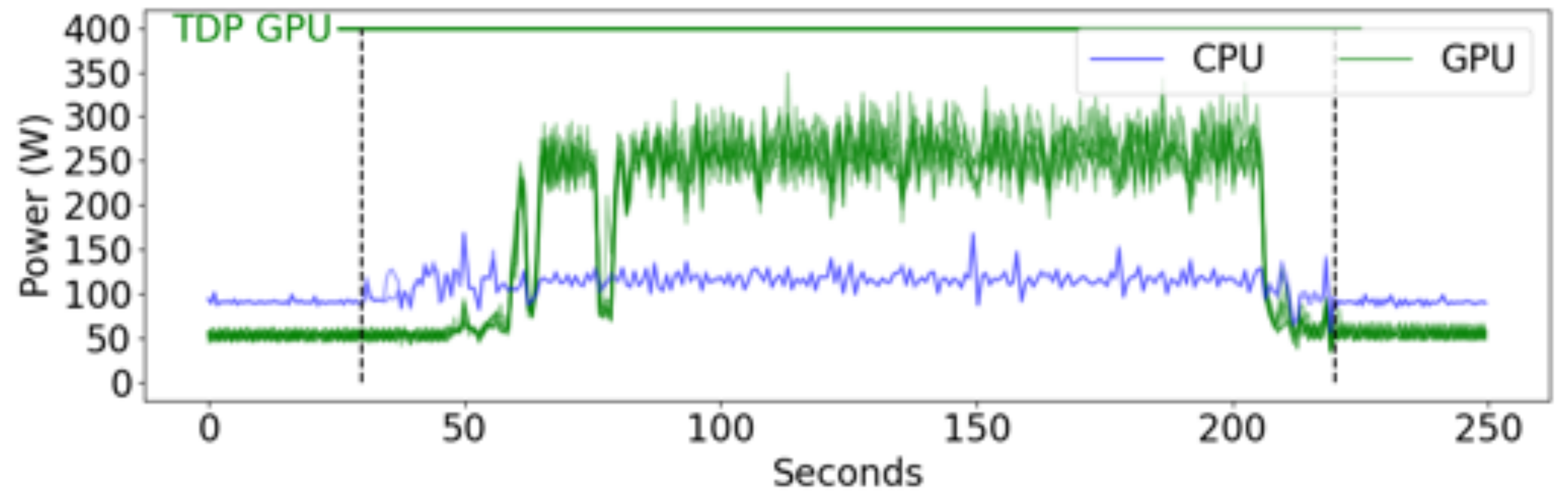
Estimation of the electricity cost of training Stable Diffusion with different measurement method
PM: Power Meter, **TDP**: Thermal Design Power

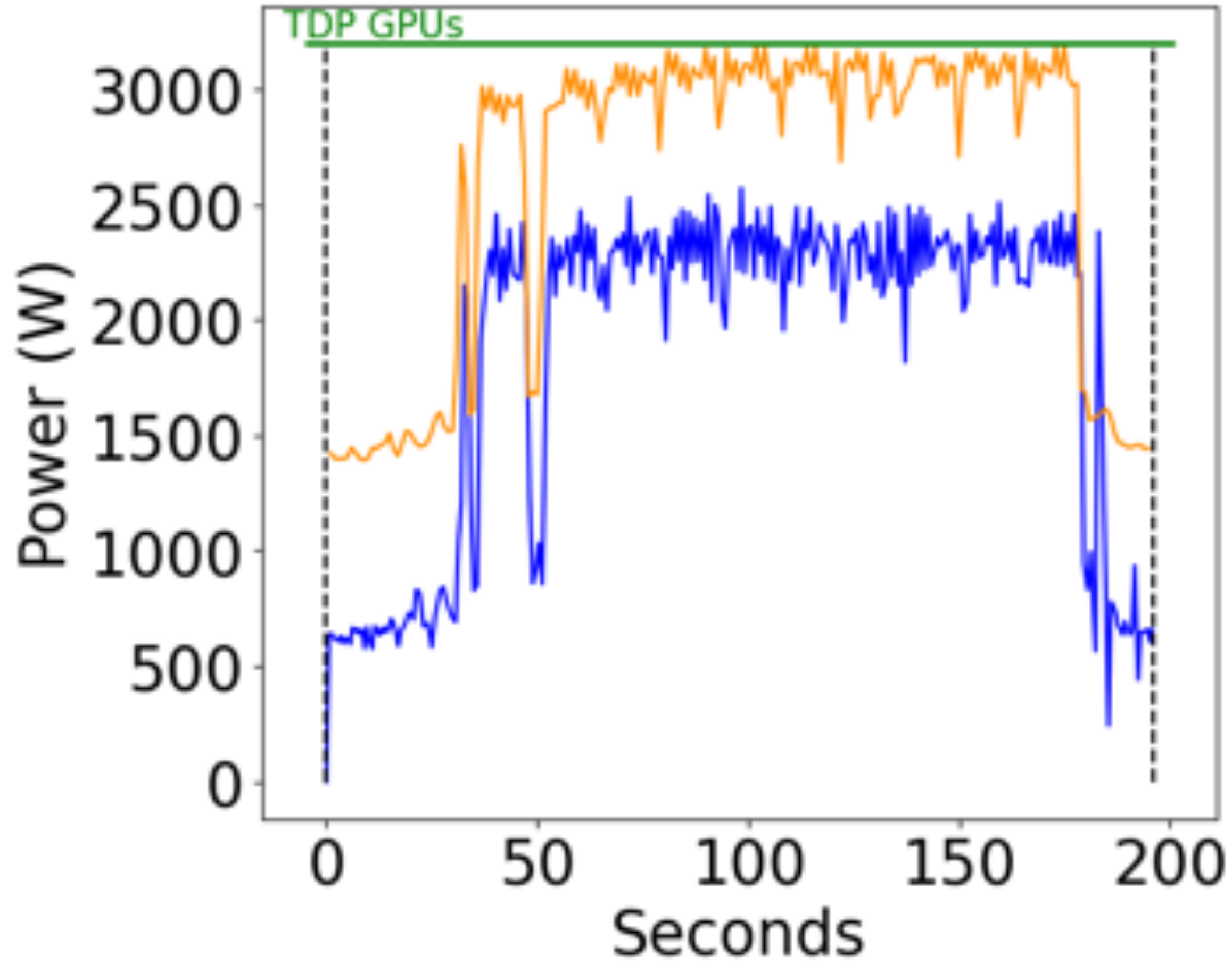


Training Stable Diffusion on the Gemini cluster

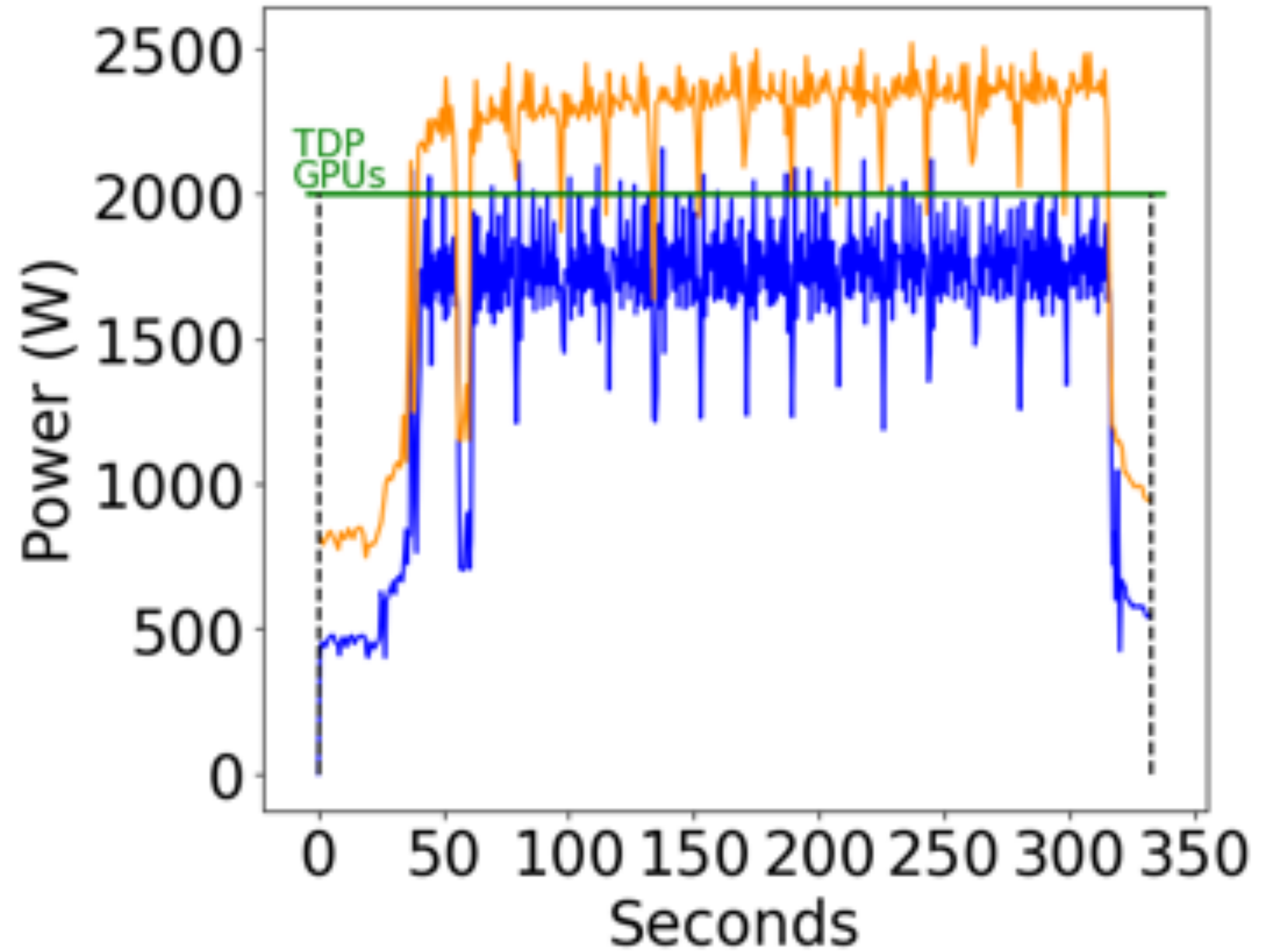


Training Stable Diffusion on the Sirius cluster





Training Stable Diffusion on the Sirius cluster



Training Stable Diffusion on the Gemini cluster



Reproducibility

Reproducibility

- Fixed environment
 - One node, and always the same
- Controlled environment
 - Fixed frequencies
 - Fixed power cap or mode
 - Minimalist software stack
 - Empty cache before each experiments
- Make sure the initial conditions are the same
 - Idle period between experiments
- Breach to reproducibility
 - Temperature in the Jetson cluster varies when I used all of them and that influenced the power draw
 - Didn't fix the set of nodes when working on Champollion at first, thus we noticed a big difference in energy consumption